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# Integrating load-balancing into multi-dimensional bin-packing problems

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- 2 Integration of load-balancing: problem definition
- 3 MIP model for balancing a single bin
- MIP model for joint packing and balancing
- A multi-level local-search heuristic
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# Multi-dimensional Bin-Packing problem (MBP)

#### Instance

- Set of D-dimensional rectangular-shaped boxes  $V = \{1, ..., n\}$ . Box i has width  $= w_{i,d}$  in dimension d
- Identical bins with width =  $W_d$  in dimension d

#### **Problem**

Orthogonally insert all boxes into the bins avoiding overlapping and using as few bins as possible. Rotations are not allowed







#### **Applications**

Shipping and transportation industry, filling up containers, loading trucks etc. Most real-world problems have  $D \le 3$ , but all results hold for any dimension

#### MIP model for the MBP

s.t. 
$$\sum_{d \in D} (I_{ijd} + I_{jid}) + p_{ij} + p_{ji} \ge 1$$
 
$$\forall i < j \in V$$
 
$$x_{id} - x_{jd} + W_d I_{ijd} \le W_d - w_{id}$$
 
$$\forall i \neq j \in V, \ d \in D$$
 
$$x_{id} \le W_d - w_{id}$$
 
$$\forall i \in V, \ d \in D$$
 
$$a_i - a_j + n \ p_{ij} \le n - 1$$
 
$$\forall i \neq j \in V$$
 
$$1 \le a_i \le N$$
 
$$\forall i \in V$$
 
$$var: a_i, N \in \mathbb{N}, \ x_{id} \in \mathbb{R}^+, \ I_{iid}, p_{ij} \in \{0, 1\}$$
 
$$\forall i, j \in V, \ d \in D$$

## Difficult to solve in practice due to many:

- symmetries
- big-M constraints

# Load-Balanced MBP (LB-MBP)

#### Instance

MBP instance + density of items  $\rho_i$  (or mass)

#### **Problem**

Arrange items into the miminum number of bins, in such a way that the barycenters of the loaded bins fall as close as possible to an ideal point (e.g. the center of the bin or center of its base)

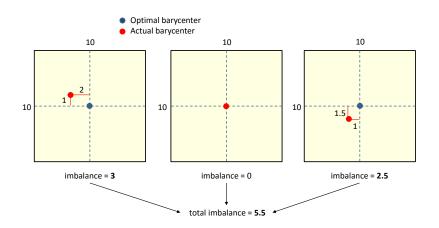
## **Applications**

Transport (ship, truck, aircraft's cargo): a good position of the center of mass increases the safety and effciency of the travel, minimizing the waste of fuel

## **Objective function**

#### Minimize the total imbalance over:

- used bins
- dimensions



# Balancing a single bin

Assume to have a set V of items which fit into a single bin:

$$\begin{aligned} & \min & \sum_{d \in D} k_d \left( r_d + s_d \right) \\ & \text{s.t.} : r_d - s_d = B_d^{opt} - \frac{1}{M} \left( \sum_i m_i \left( x_{id} + \frac{w_{id}}{2} \right) \right) & \forall d \in D \\ & \sum_{d \in D} \left( l_{ijd} + l_{jid} \right) \geq 1 & \forall i < j \in V \\ & x_{id} - x_{jd} + W_d \, l_{ijd} \leq W_d - w_{id} & \forall i \neq j \in V, \ d \in D \\ & x_{id} \leq W_d - w_{id} & \forall i \in V, \ d \in D \\ & \text{var} : & x_{id}, r_d, s_d \in \mathbb{R}^+ & l_{ijd} \in \{0, 1\} & \forall i, j \in V, \ d \in D \end{aligned}$$

To solve the LB-MBP we could:

- 1) Find the smallest number of bins
- 2) Balance each bin to optimality

...but the packing and balancing phases are not linked together!

#### MIP model for the LB-MBP

$$\begin{aligned} & \min & N \, C + \sum_{d=1}^D \sum_{j=1}^N K_d \left( r_{jd} + s_{jd} \right) \\ & \text{s.t.} : \sum_{d=1}^D \left( l_{ijd} + l_{jid} \right) + p_{ij} + p_{ji} \geq 1 \\ & \times_{id} - x_{jd} + W_d \, l_{ijd} \leq W_d - w_{id} \\ & a_i - a_j + n p_{ij} \leq n - 1 \\ & \times_{id} \leq W_d - w_{id} \\ & 1 \leq a_i \leq N \\ & n(c_{ij} - 1) \leq a_i - j \leq n (1 - c_{ij}) \\ & 1 - (n + 1) \left( 1 - \delta_{ij} \right) \leq a_i - j \leq -1 + (n + 1) \left( 1 - \gamma_{ij} \right) \\ & c_{ij} + \gamma_{ij} + \delta_{ij} = 1 \\ & w_{i} W_d \left( c_{ij} - 1 \right) \leq e_{ijd} - m_i \left( x_{id} + w_{id} / 2 \right) \leq m_i \, W_d \left( 1 - c_{ij} \right) \\ & w_{i} W_d \left( c_{ij} - 1 \right) \leq \alpha^{ijd} - m_i \left( W_d^{opt} - r_{jd} + s_{jd} \right) \leq m_i \, W_d \left( 1 - c_{ij} \right) \\ & e_{ijd} \leq c_{ij} \, W_d \, m_i \\ & \omega_{ijd} \leq c_{ij} \, W_d \, m_i \\ & \sum_{i=1}^N e_{ijd} = \sum_{i=1}^N \alpha_{ijd} \\ \end{aligned} \end{aligned} \end{aligned}$$

## Sequential vs. joint problem

3D instance with 18 items,  $\rho_i = 1$ ,  $B^{opt} = (5, 5, 0)$ 

## Sequential problem

bin 1 bin 2 bin 3 bin 4	1	2	3	4	5	7	8	10
bin 2	6	11						
bin 3	9	12	14	17				
bin 4	13	15	16	18				

### Optimal 3DBPP: uses 4 bins

bin	B <sub>x</sub>	$B_y$	$B_z$	f <sub>bin</sub>
bin 1	5.00	5.00	4.18	4.18
bin 2	6.12	5.00	4.44	5.56
bin 3	5.00	5.00	4.38	4.38
bin 4	5.00	5.00	3.32	3.32
fcoord	1.12	0.00	16.32	17.44

# Joint problem

bin 1	1	2	3	5		
bin 2	4	6	7	8	10	12
bin 3	9	11	14	17		
bin 4	13	11 15	16	18		

#### Different 3DBPP solution

bin	B <sub>x</sub>	$B_y$	Bz	f <sub>bin</sub>
bin 1	5.00	5.00	4.22	4.22
bin 2	5.00	5.00	3.64	3.64
bin 3	5.00	5.00	4.59	4.59
bin 4	5.00	5.00	3.32	3.32
f <sub>coord</sub>	0.00	0.00	15.77	15.77

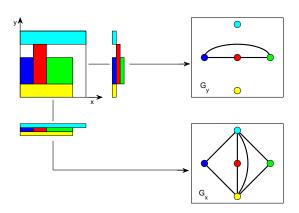
### 10% improvement!

But running time is 4 vs. 132 seconds. In general the joint model cannot be solved for instances larger than 15-20 items

## **Heuristic load balancing**

We now develop a heuristic algorithm to solve large instances

It is possible to characterize feasible packings by means of a set of Interval Graphs (Fekete-Schepers)



# **Properties (1/2)**

#### **Theorem 1**

If D graphs  $G_d$ ,  $d \in D$ , are obtained from a packing, then the following conditions are fulfilled:

P<sub>1</sub>: Each G<sub>d</sub> is an interval graph

 $P_2: \cap_d G_d = \emptyset$ 

 $P_3$ : The stable sets of  $G_d$  have total weight less than the d-dimension of the bin

#### **Definition**

Let G be an undirected graph. An orientation  $\Phi$  of G is called transitive orientation (TRO) if:

$$(a,b) \in \Phi \land (b,c) \in \Phi \Longrightarrow (a,c) \in \Phi$$

# Properties (2/2)

#### **Theorem 2**

If G is an interval graph, then its complement  $\overline{G}$  is transitively orientable

#### **Theorem 3**

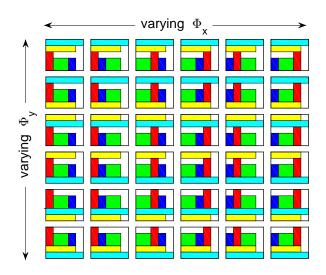
Let  $G_d$ ,  $d \in D$  be D graphs satisfying  $P_1$ ,  $P_2$ ,  $P_3$ , and call  $\Phi = (\Phi_d)_{d \in D}$ , where  $\Phi_d$  is a transitive orientation of  $\overline{G}_d$ .

The function  $p^{\Phi}: V \longrightarrow \mathbb{R}_0^{+D}$  defined by:

$$\rho_d^{\Phi}(v) = \begin{cases} 0 & \text{if } \exists u \in V : (u, v) \in \Phi_d \\ \max\{\rho_d^{\Phi}(u) + w_d(u) \, | \, (u, v) \in \Phi_d \} \end{cases} \text{ otherwise}$$

produces a packing

# How many transitive orientations?



Different transitive orientations produce different packings

## **Local search among TROs**

### How many TROs?

From graph theory: number of TROs of a graph is  $\prod_{i=1}^{k} r_i!$  where  $r_i$  is the number of vertices of particular substructures

#### Is it possible to find TROs?

From graph theory: we can characterize them all TROs of a graph (it's complicated though)

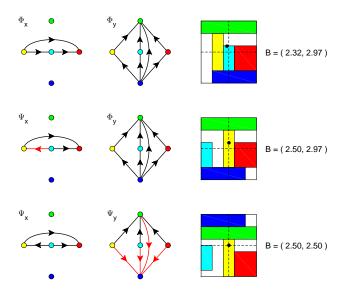
#### Local Search

We define a best-improvement local search exploring a quadratic neighborhood of TROs. For each TRO:

- go back to the corresponding packing
- evaluate the load balancing

## **Example for a 2D case**

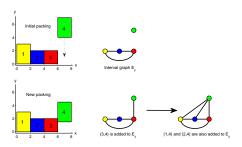
Items have different densities, bin= 5x5,  $B_{opt} = (2.5, 2.5)$ 



## Local search at graph level

Purpose: improve cases where the number of TROs is limited How: modifying the structure itself of the graphs:

- Consider interval graphs G<sub>d</sub>
- Add or remove edges using specific rules (Crainic et al.)



 If new graphs correspond to a packing, then start local search on TROs

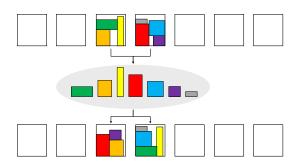
# Local search at bin-packing level (1/2)

### Purpose

Exploit the balancing potential of having a large number of bin-packings solutions with the same number of bins

#### How

Iteratively repack and rebalance n-tuples of weakly balanced bins using *variable-depth neighborhood search* (VDNS)



# Local search at bin-packing level (2/2)

Define a k-neighborhood as the set of all bin-packing solutions obtained by repacking at most k bins

## VDNS algorithm

- Assign imbalance scores to the bins
- 2 Select k bins using roulette wheel selection
- Repack the bins using a heuristic for MBP
- 4 If k bins are still used, balance them
- If balancing is improved: save solution and update scores

k is dynamically adjusted:

if no solutions are found after *n* iterations: k = k + 1

# Results for 3D Bin-Packing instances (1/2)

Optimal barycenter  $\left(\frac{W_1}{2}, \frac{W_2}{2}, \frac{W_3}{2}\right)$ : center of the bin

				$\rho_i = 1$			$ ho_i \sim \textit{U}(1,2)$			$ ho_i \sim U(1,6)$		
cl.	size	LB	bins	Init.	Bin	VDNS	Init.	Bin	VDNS	Init.	Bin	VDNS
1	100	24.12	25.64	16.48	0.91	0.011	17.03	0.68	0.054	19.22	2.26	0.201
2	100	24.64	26.12	16.19	0.85	0.011	16.69	0.68	0.042	19.01	2.28	0.198
3	100	24.48	26.08	16.34	0.87	0.006	16.78	0.66	0.030	19.16	2.21	0.245
4	100	57.44	60.60	31.74	0.58	0.011	30.64	0.29	0.030	30.91	0.93	0.090
5	100	13.60	14.60	15.83	0.92	0.003	15.87	0.71	0.068	17.65	2.70	0.425
6	100	18.20	20.08	9.83	1.45	0.190	10.30	1.70	0.396	13.49	4.54	1.210
7	100	11.12	12.36	16.89	1.19	0.012	16.53	0.79	0.050	18.37	3.11	0.559
8	100	15.52	17.08	15.66	0.78	0.008	15.34	0.64	0.056	17.35	2.63	0.501
1	200	48.84	51.16	15.05	0.79	0.007	15.74	0.82	0.032	18.36	2.57	0.208
2	200	48.48	50.80	14.81	0.77	0.006	15.57	0.85	0.044	18.24	2.58	0.217
3	200	49.24	51.24	14.91	0.77	0.005	15.68	0.83	0.036	18.29	2.65	0.262
4	200	117.8	122.2	31.91	0.53	0.004	30.66	0.29	0.012	30.91	0.96	0.034
5	200	25.60	27.36	12.47	0.75	0.011	13.06	0.89	0.147	14.90	3.23	0.801
6	200	35.84	38.24	6.74	1.30	0.241	8.17	2.19	0.523	12.09	5.44	1.505
7	200	20.36	22.40	12.72	1.26	0.057	12.95	1.15	0.329	14.89	3.99	1.567
8	200	29.40	32.04	12.75	0.70	0.016	12.79	0.98	0.183	14.66	3.33	0.921

Results are average over 25 instances, running time is < 5-10s</li>

## Results for 3D Bin-Packing instances (2/2)

Optimal barycenter  $\left(\frac{W_1}{2}, \frac{W_2}{2}, 0\right)$ : center of the base

				$\rho_i = 1$					$\rho_i \sim$	U(1, 2)		$ \rho_i \sim U(1,6) $			
cl.	size	LB	bins	Init.	Bin	VDNS	LLB	Init.	Bin	VDNS	LLB	Init.	Bin	VDNS	LLB
1	100	24.12	25.64	52.30	43.75	41.98	36.06	51.57	42.53	41.64	31.87	54.78	41.93	40.84	26.82
2	100	24.64	26.12	61.88	46.52	44.49	35.90	58.89	43.95	43.01	31.72	59.32	40.21	39.35	26.68
3	100	24.48	26.08	52.64	43.58	41.92	35.56	52.00	42.49	41.46	31.42	53.08	41.56	40.45	26.41
4	100	57.44	60.60	60.92	39.72	38.42	25.59	58.72	38.57	38.23	22.61	58.82	38.08	37.58	19.06
5	100	13.60	14.60	54.65	44.83	42.35	36.77	51.78	42.70	41.70	32.44	51.97	41.48	40.27	27.16
6	100	18.20	20.08	53.07	47.26	44.91	41.98	51.33	45.63	44.24	37.07	51.92	44.49	43.13	31.13
7	100	11.12	12.36	55.24	44.94	42.36	36.59	51.87	42.58	41.59	32.30	51.96	41.80	39.80	27.12
8	100	15.52	17.08	54.77	44.83	42.08	37.08	51.97	43.03	41.99	32.72	52.37	42.05	40.45	27.44
1	200	48.84	51.16	51.98	44.00	42.56	36.87	51.77	43.18	42.14	32.58	52.90	42.31	41.09	27.43
2	200	48.48	50.80	61.86	47.10	45.20	36.79	59.34	44.72	43.65	32.51	59.96	40.72	39.93	27.36
3	200	49.24	51.24	52.38	44.11	42.67	36.68	52.18	43.26	42.22	32.14	53.45	42.35	41.16	27.28
4	200	117.8	122.2	60.31	39.50	38.19	25.74	58.29	38.40	38.05	22.76	58.55	37.92	37.36	19.18
5	200	25.60	27.36	53.89	45.90	44.14	39.29	52.23	44.57	43.48	34.71	52.93	43.54	42.16	29.21
6	200	35.84	38.24	52.24	48.28	45.77	44.36	51.06	46.74	45.12	39.19	51.83	45.34	43.64	32.97
7	200	20.36	22.40	53.96	46.47	44.51	39.88	52.31	44.87	43.90	35.23	53.43	44.04	42.72	29.64
8	200	29.40	32.04	53.68	45.84	44.37	39.61	52.14	44.73	43.72	34.98	53.09	45.84	42.40	29.42

- Results are average over 25 instances, running time is < 5-10s</li>
- LLB is a lower bound obtained from "liquifying" the items

# **Background paper**

Alessio Trivella and David Pisinger. "The load-balanced multi-dimensional bin-packing problem". *Computers & Operations Research* 74 (2016)152–164

