

3D Finite Element Modelling of Drilling Process of Al2024-T3 Alloy with solid tooling and Experimental Validation

Davoudinejad, Ali; Tosello, Guido

Publication date: 2017

Document Version Publisher's PDF, also known as Version of record

Link back to DTU Orbit

Citation (APA):

Davoudinejad, A., & Tosello, G. (2017). 3D Finite Element Modelling of Drilling Process of Al2024-T3 Alloy with solid tooling and Experimental Validation. Poster session presented at euspen's 17th International Conference & Exhibition, Hannover, Germany.

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Hannover (Germany), 29th May – 2nd June 2017



alidav@mek.dtu.dk

¹ Department of Mechanical Engineering, Technical University of Denmark (DTU), Produktionstorvet, Building 427S, Kgs. Lyngby, DK-2800, Denmark ² Department of Mechanical Engineering, Politecnico di Milano, Campus Bovisa Sud, via La Masa 1, 20156 Milano, Italy

Abstract

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Drilling is an indispensable process for many manufacturing industries due to the importance of the process for assembling components. This study presents a 3D finite element modeling (3D FEM) approach for drilling process of aluminum 2024-T3. The 3D model of tool for two facet HSSCo and four facet HSS were generated base on the details geometry. The simulations were carried out for both drills in different cutting conditions. The numerically obtained thrust forces were compared against experimental results. The tool stress distribution, chip formation and temperature distribution in the chip area were determined numerically. The results confirm the ability and advantage of 3D FE model of the drilling process.

3D Finite Element Modeling (3D FEM)

- Objective \Rightarrow Evaluate different drills geometry and material for drilling Aluminum 2024-T3.
- Reduction in cost and time, mainly with advance of powerful computers to predict parameters such as stress, cutting force, temperature, strain and strain rate, which are difficult or impossible to detect experimentally [1].
- Tool modeling and cutting configuration setup (Fig. 1).
 - Different cutting tool geometries (Table 1).
- Tool and workpiece were meshed with the 4 node tetrahedral elements, type.
- Adaptive-meshing technique was applied constantly in the simulations.
- The Power Law constitutive material model. where σ_0 is the initial yield stress, ε^p is the plastic strain, ε_0^p is the reference plastic strain, ε is the strain rate, ε_0 is the reference plastic strain rate, c0 through c5 are the coefficients for the polynomial fit, T is temperature, n is the strain hardening exponent and m is the strain rate sensitivity coefficient [2].

 $\sigma(\varepsilon^p, \varepsilon^{\cdot}, \mathsf{T}) = \mathsf{g}(\varepsilon^p).\, \Gamma(\varepsilon).\, \Theta(\mathsf{T})$ $g(\varepsilon^p) = \sigma_0 \left(1 + \frac{c}{p}\right)^{1/2}$ $\Gamma(\varepsilon) = \sigma_0 \left(1 + \frac{\varepsilon}{\varepsilon_0}\right)^{1/2}$



Fig. 1 Tool 3D model and experimental image (a) two facet HSSCo (b) four facet HSS (c) 3D FE model for drilling setup

Experimental procedure for FEM validation

Table 1 Cutting tool specifications

	Tool A	Tool B
Material	HSSCo	HSS
Code	A920	A120
Hardness (HV)	980	918
Geometry	2 Facet	4 Facet





The friction phenomenon at the chip-tool interface was modeled using the Coulomb law. Based on the experimental research results and related studies [3] a constant friction factor of 0.7 is used in the finite element (FE) model.

 $\tau = \mu \sigma$ In order to validate model a comparison between numerical and experimental forces were carried out.



60.0 40.0 20.0 1.2 1.8 2.4 2.9 Time (S) (b) Tool B Fig. 3 Experimental thrust force (a) 2 facet drill

and (b) 4 facet drill at fz = 0.04 mm/rev

• Dry drilling experiments of Al2024 were carried out using CNC Deckel Maho DMC 835 [4]. • Cutting speed (94.2 m/min)

• Feed rates (0.04, 0.4 mm/rev) [4].

