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Author(s): M. Marcer P. A. Stentoft, E. Bjerre, E. Cimoli, A. Bjørk, L. Stenseng and H. Machguth

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Three decades of volume change of a small Greenlandic glacier using ground penetrating radar, Structure from Motion, and aerial photogrammetry

M. Marcer^{1,2}, P. A. Stentoft^{1,3}, E. Bjerre^{1,3}, E. Cimoli^{1,4}, A. Bjørk⁵, L. Stenseng⁶, and H. Machguth^{1,7,8}

¹Arctic Technology Centre ARTEK, Department of Civil Engineering, Technical University of Denmark, Brovej, Building 118, 2800 Kgs. Lyngby, Denmark

²Institut de Géographie Alpine IGA, PACTE, Université Grenoble-Alpes, Avenue Marie Reynoard 14 bis, 3800 Grenoble, France

³DTU Environment, Technical University of Denmark, Bygningstorvet Bygning 115, 2800 Kgs. Lyngby, Denmark

⁴Institute for Marine and Antarctic Studies, University of Tasmania, Castray Explanade 20, 7004 Hobart, Australia

⁵Centre for GeoGenetics, Natural History Museum of Denmark, Oster Voldgade 5-7, 1350 Copenhagen K, Denmark

⁶DTU Space–National Space Institute, Technical University of Denmark, Department of Geodesy, Elektrovej 328, DK–2800 Kgs. Lyngby, Denmark

⁷Department of Geography, University of Zurich, Winterthurerstrasse 190, 8057 Zurich, Switzerland

⁸Department of Geosciences, University of Fribourg, Chemin du Musée 4, 1700 Fribourg, Switzerland

*Corresponding author's email: marco.marcer@univ-grenoble-alpes.fr

A B S T R A C T

Glaciers in the Arctic are losing mass at an increasing rate. Here we use surface topography derived from Structure from Motion (SfM) and ice volume from ground penetrating radar (GPR) to describe the 2014 state of Aqutikitsoq glacier (2.85 km²) on Greenland's west coast. A photogrammetrically derived 1985 digital elevation model (DEM) was subtracted from a 2014 DEM obtained using land-based SfM to calculate geodetic glacier mass balance. Furthermore, a detailed 2014 ground penetrating radar survey was performed to assess ice volume. From 1985 to 2014, the glacier has lost $49.8 \pm 9.4 \cdot 10^6$ m³ of ice, corresponding to roughly a quarter of its 1985 volume ($148.6 \pm 47.6 \cdot 10^6$ m³) and a thinning rate of 0.60 ± 0.11 m a⁻¹. The computations are challenged by a relatively large fraction of the 1985 DEM (~50% of the glacier surface) being deemed unreliable owing to low contrast (snow cover) in the 1985 aerial photography. To address this issue, surface elevation in low contrast areas was measured manually at point locations and interpolated using a universal kriging approach. We conclude that ground-based SfM is well suited to establish high-quality DEMs of smaller glaciers. Provided favorable topography, the approach constitutes a viable alternative where the use of drones is not possible. Our investigations constitute the first glacier on Greenland's west coast where ice volume was determined and volume change calculated. The glacier's thinning rate is comparable to, for example, the Swiss Alps and underlines that arctic glaciers are subject to fast changes.

INTRODUCTION

Glaciers and ice caps, that is, all glaciers excluding the Greenland and Antarctic ice sheets, are sensitive indica-

tors of climatic change. Knowledge of their sizes and distribution is prerequisite to estimate their sea level equivalent and to improve future scenarios of sea level change. Available ice thickness measurements of glaciers

and ice caps have recently been compiled (Gärtner-Roer et al., 2014) with the aim of making an improved baseline data set available to the scientific community. Greenland is represented in the database by the ice volume measurement from one single glacier (Mittivakkat glacier, south-east coast; Yde et al., 2014). Mittivakkat also holds the only published longer-term (two decades) volume change of a Greenlandic glacier (Yde et al., 2014). This lack of data contrasts with the importance of Greenland's glaciers: Greenland is home to 90,000 to 130,000 km² of glaciers and ice caps, corresponding to ~7% of all glaciers in the world (Rastner et al., 2012), and these glaciers show a higher sensitivity to climate change than the ice sheet (Bolch et al., 2013).

The restricted number of geodetic glacier mass balance surveys on Greenland is probably related to the absence of digital elevation models (DEMs) of sufficient accuracy and to the remoteness of many glaciers, which renders field surveys costly. Aerial photographs recorded in the 1970s and 1980s, however, have recently been reanalyzed, and a DEM of known accuracy and time stamp, for all of the coastal areas of Greenland, has been established (Kjær et al., 2012; Korsgaard et al., 2016). Provided recent measurements of surface elevation are available, the 1970s/1980s DEM could provide a baseline to measure surface elevation changes of Greenland glaciers over the last approximately three decades. Recent surface elevation can be obtained from newly established DEMs (e.g., Noh and Howat, 2015), from ICESat satellite data, or from NASA's airborne topographic mapper ATM (e.g., Krabill et al., 2000; Sørensen et al., 2011). ICESat and ATM, however, are predominantly available for the ice sheet and offer only limited coverage on glaciers and ice caps (Bolch et al., 2013). In recent years, so called Structure from Motion (SfM) has gained popularity as a tool to produce DEMs, as the technique offers high resolution and accurate elevation data at minimal costs (e.g., Westoby et al., 2012; Fonstad et al., 2013; Smith et al., 2016). The technique thus provides the possibility to determine geodetic mass balance for glaciers in Greenland where contemporary data of surface height are lacking (Piermattei et al., 2015; Ryan et al., 2015; Thomson and Copland, 2016).

Here we determine ice volume, and changes therein, for a small valley glacier, labeled Aqutikitsoq, on Greenland's west coast. We estimated volume change of Aqutikitsoq glacier based on surface elevation changes from 1985 to 2014, determined from comparing the newly generated historical DEM (Korsgaard et al., 2016) to a 2014 DEM generated using SfM. Furthermore, we performed a ground penetrating radar (GPR) survey to measure ice thickness distribution over the entire glacier surface and to calculate total ice volume. Volume change

from 1985 to 2014 was finally analyzed in the context of total ice volume measured from GPR, as well as earlier studies on glacier thickness change in Greenland (Bolch et al., 2013, Gardner et al., 2013). Our study demonstrates the usefulness of ground-based SfM and provides, to our knowledge, the first detailed volume measurement and geodetic measurement of mass balance of a glacier on Greenland's west coast.

STUDY SITE

The glacier under investigation lacks an official name (cf. Bjørk et al., 2015). Here we refer to the glacier as "Aqutikitsoq glacier," named after the highest mountain peak in its immediate vicinity. In contrast to the meaning of the mountain's name (Aqutikitsoq [Greenlandic] is translated as "has little/limited path"), the glacier was chosen because of being relatively easy to access by boat (from the town of Sisimiut) and a subsequent hike from the fjord to the glacier tongue. Furthermore, the glacier's characteristics are fairly typical for the Sisimiut glaciers (see below).

The Aqutikitsoq glacier catchment is located at 67.10°N, 53.23°W, approximately 27 km northeast of the town of Sisimiut, South-West Greenland (Fig. 1). Aqutikitsoq glacier is a valley glacier and extended in 2014 over an area of approximately 2.85 km². The glacier has two tongues (Figs. 2 and 3); a lower one terminating at 530 meters above sea level (m a.s.l.) where the glacier river leaves the glacier, and a second one terminating in a proglacial lake at 820 m a.s.l. (Figs. 3 and 4). In 2014 the glacier had a length of roughly 4 km, as measured from the lower tongue to 1280 m a.s.l. in the uppermost accumulation area. A glacierized pass constitutes one of the highest topographical points from where the ice flows both into Aqutikitsoq glacier and an adjacent unnamed glacier.

Clearly visible lateral and frontal moraines (Fig. 3) indicate the position of the glacier front during the Little Ice Age (LIA, ca. a.d. 1890 in central West Greenland; Weidick, 1959). The glacier has retreated by roughly 1.2 km (~24% of its LIA length) since the end of the LIA. This value is based on the location of the LIA moraine, as identified on the 1985 orthophoto (Fig. 2) and in the field, and the current glacier extent as determined from the 2014 orthophoto established in this study (Fig. 3).

Regional Characteristics

The mountains around Aqutikitsoq glacier are home to a cluster of small valley and mountain glaciers (termed "Sisimiut glaciers" in the following). The isolated group of glaciers, 60 km north of the strongly gla-

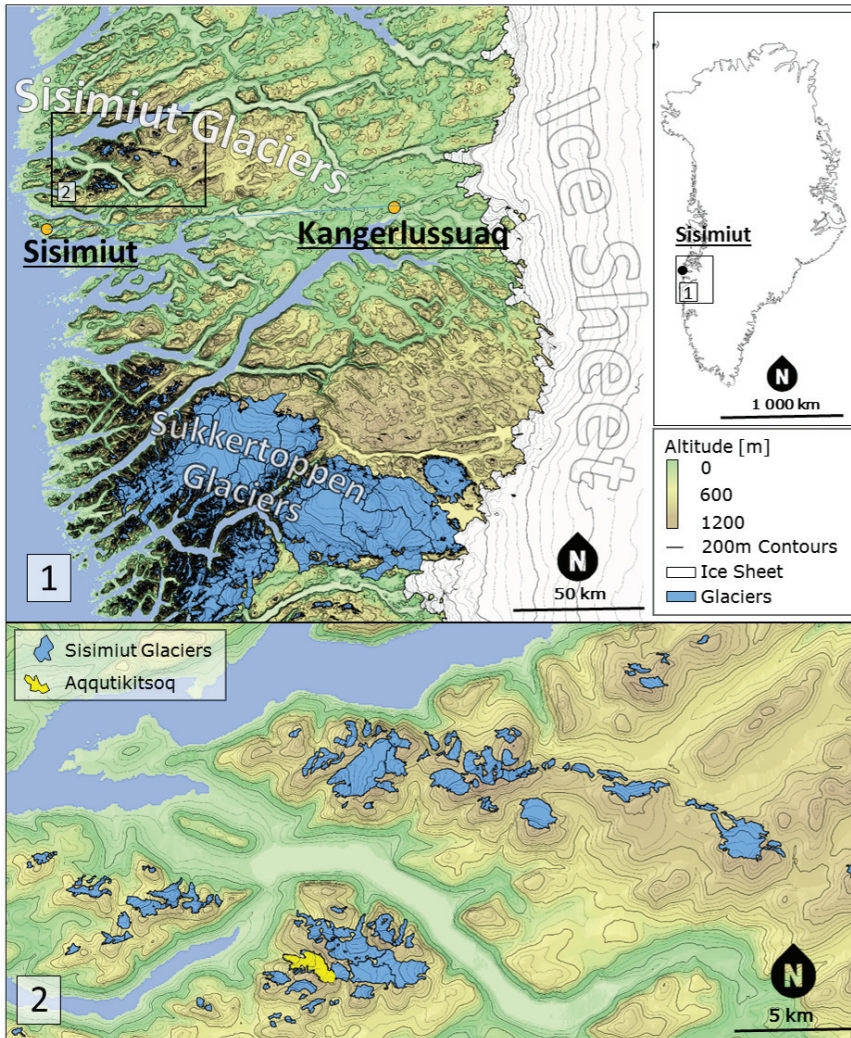


FIGURE 1. Overview of the investigated area and the Sisimiut glaciers. The two nearby towns are indicated with orange dots, and Aqutikitsoq glacier is highlighted in yellow.

cierized Sukkertoppen area (Fig. 1), covers an area of $\sim 85 \text{ km}^2$ and consists of exactly 100 glaciers or glacierets according to the Greenland glacier inventory by Rastner et al. (2012). By surface area, Aqutikitsoq glacier is the fifth largest of the Sisimiut glaciers.

Hydrological observations have been carried out in the region of the Sisimiut glaciers (e.g., Bøggild, 2000). The authors are not aware of previous glaciological measurements on the Sisimiut glaciers, except for unpublished energy balance measurements carried out in spring 1998 on a small ice cap $\sim 25 \text{ km}$ west of Aqutikitsoq (Nielsen, 1999). Surface mass balance observations elsewhere in South-West Greenland (Olesen, 1986; Ahlstrøm et al., 2007; Van de Wal et al., 2012; Machguth et al., 2016) indicate a pronounced gradient in equilibrium line altitude (ELA), from relatively low values at the coast to high values on the ice sheet. Using median elevation as a proxy for ELA (Braithwaite and Raper, 2009) indicates that the unmeasured Sisimiut glaciers are subject to a similar gradient in ELA that is related to a precipitation decrease

from relatively moist conditions at the coast toward a dry ice sheet margin (cf. Boas and Wang, 2011). The median elevation of Aqutikitsoq glacier (946 m a.s.l.) lies close to the mean ($994 \pm 173 \text{ m a.s.l.}$) of all 41 glaciers in the Sisimiut area exceeding 0.5 km^2 in area.

DATA AND METHODS

Fieldwork on Aqutikitsoq glacier was focused on establishing an accurate DEM using SfM and measuring ice thickness distribution from GPR. Both approaches are described in the following. The field campaign took place during 9–17 August 2014. Due to poor weather during the first few days, most measurements were carried out 12–17 August.

2014 Structure from Motion-Based DEM

The 2014 DEM was derived using SfM, a technique that performs a 3D reconstruction of an object using

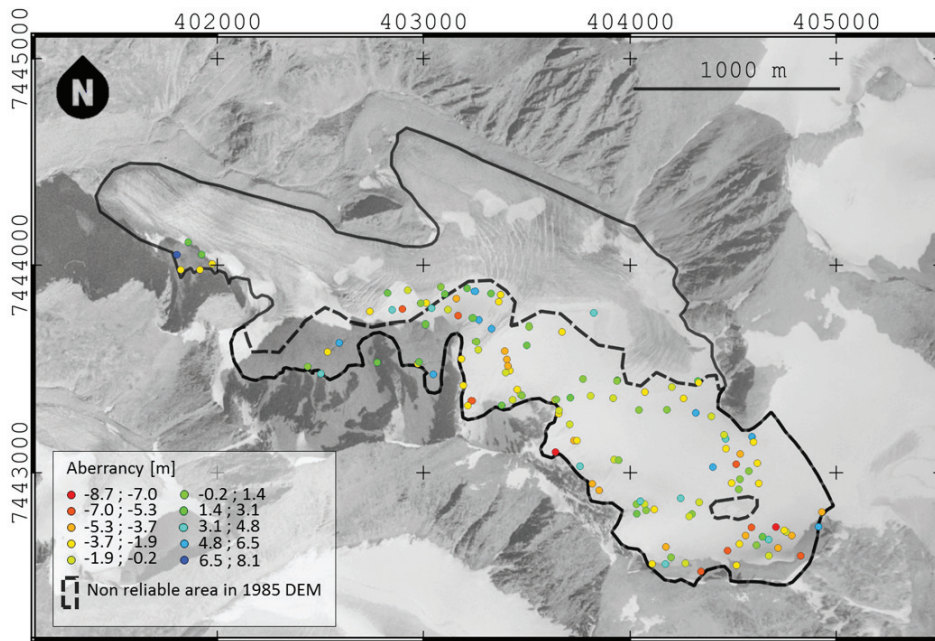


FIGURE 2. 1985 orthophoto. The area south of the dashed line is snow covered and resulted in low digital elevation model (DEM) quality. Colored dots indicate the points at which 1985 surface elevation was manually measured. The points' colors indicate their relative deviations from their neighbors within a 100 m diameter. Coordinates refer to Universal Transverse Mercator (UTM) zone 22N.

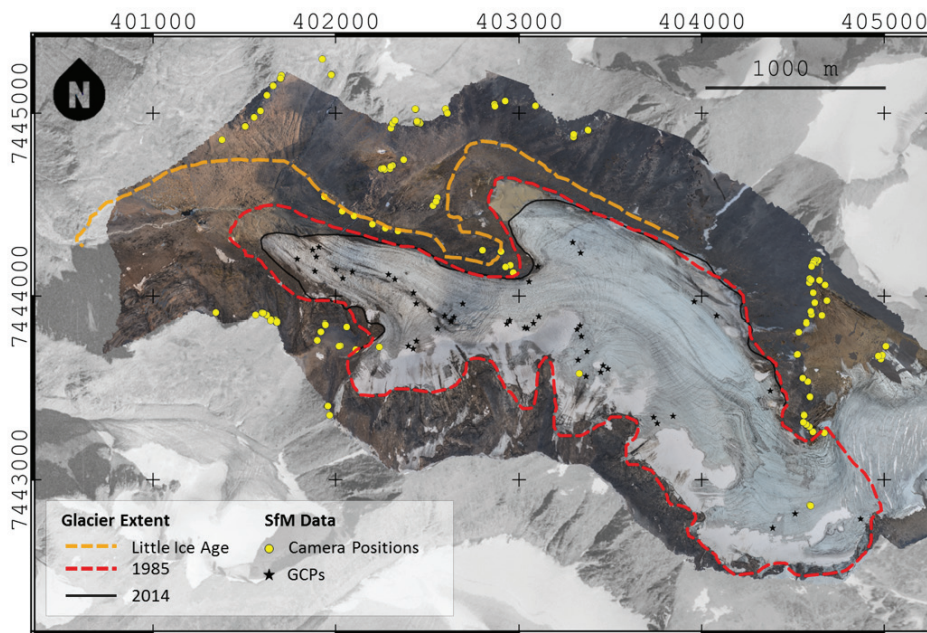


FIGURE 3. Orthophoto from August 2014 obtained by the Structure from Motion (SfM) process, camera positions and ground control points (GCPs). As the 2014 orthophoto is limited to the surroundings of the glacier and its immediate surroundings, it is superimposed on the 1985 orthophoto (monochromatic) to illustrate the estimated extent of the glacier at the end of the Little Ice Age. Coordinates refer to UTM zone 22N.

a set of highly overlapping pictures of the object itself. Several authors tested SfM for glacier DEM reconstruction, demonstrating that this method, using only a consumer level camera and a differential GPS, is capable of achieving precision and resolution comparable to laser scanning techniques (Piermattei et al., 2015; Ryan et al., 2015; Thomson and Copland, 2016). Although often coupled with unmanned aerial vehicles (UAVs), low cost ground-based SfM surveys were also carried out taking advantage of natural viewpoints and

small size of study sites ($<0.1 \text{ km}^2$) (Westoby et al., 2012; Piermattei et al., 2015).

The ease of the process, the high resolution, and the referencing precision achievable made SfM the optimal choice for generating a DEM of Aqutikitsoq glacier during the 2014 field campaign. Because no drone was available, we performed a ground-based campaign for an area ($\sim 3 \text{ km}^2$) that would usually be measured from UAVs. We also considered the use of the satellite-derived SETSM DEM (Noh and Howat,

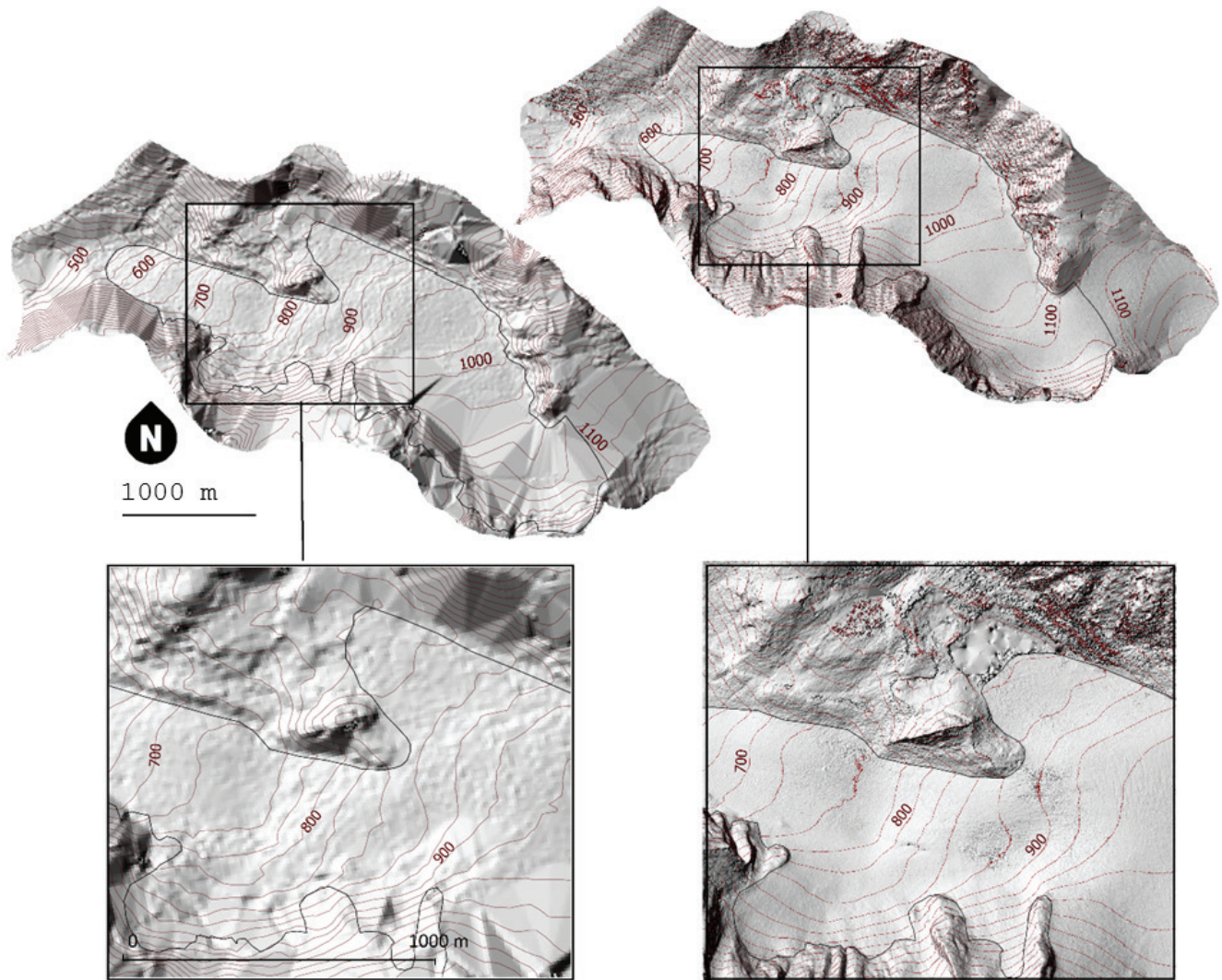


FIGURE 4. 1985 (left) and 2014 (right) DEMs with 25 m contour lines as well as the respective glacier outlines. Magnified sections of the DEMs are shown to highlight the difference in resolution and accuracy between the two models.

2015). However, comparison of the 2-m-resolution 2012 SETSM DEM against 1985 and SfM DEM indicated that SETSM is subject to a systematic vertical offset in the order of 6 to 10 m (cf. Bjerre and Stentoft, 2015). The difference was measured over stable terrain in vicinity of the glacier and likely related to the 2012 DEM not being tied to ground control points (cf. Noh and Howat, 2015). Furthermore, SETSM shows artifacts of similar characteristics to those occurring on the 1985 DEM. For these reasons, SfM was deemed better suited for the purpose of calculating geodetic mass balance of Aqutikitsoq.

The workflow of DEM generation followed the classical SfM process, divided into four steps: (1) pictures acquisition, (2) GPS survey and processing, (3) DEM generation, and (4) accuracy assessment (e.g., Smith et al., 2015; Carrivick et al., 2016).

In the photographic survey we acquired pictures of the glacier, taken from natural viewpoints on the relatively high and steep mountains surrounding the glacier. Four distinct peaks, three of them located on the southwestern side of the glacier and one on the northeastern side, were climbed (Fig. 3). In total, 622 pictures were recorded using two consumer-level cameras: Nikon D3100 (10 megapixels) with a Sigma 10–20 mm f/4.5 lens and Nikon D3200 (24.2 megapixels) with a Nikon 18–55 mm f/3.5 lens.

A GPS survey was performed to obtain high-precision coordinates of ground control points (GCPs) to georeference the SfM DEM. In the present study, a Trimble 5700 receiver combined with a Zephyr 4-points feed antenna was used. Because the GCPs need to appear in the SfM pictures, artificial ground targets were installed on the glacier during the first day of the survey. However, severe weather made picture acquisition impossible during the

following days, and the targets were destroyed by storms and heavy rainfall. Consequently, we decided to use natural GCPs, such as large boulders on the glacier surface, that could not be moved by strong winds. This allowed the survey to be undertaken on separate days, and GPS coordinates of the edges of big boulders could be acquired regardless of weather conditions, saving the rare days of clear weather for the photogrammetric survey. However, the identification of these natural features in the SfM pictures is not straightforward. To ensure that a minimum number of GCPs will be available, GPS coordinates of natural GCPs were taken intentionally in big quantities (173 points). Out of these, 138 could be non-ambiguously identified in the SfM pictures. GPS coordinates were measured using the post-processing rapid-static approach, which combines high precision and acquisition time of 5–10 s, which allowed a fairly quick collection of the large GCP data set. The in situ GPS data were processed using Leica GEO Office (LGO) and base station data from the Sisimiut Reference Station, located at 26 km southwest of the study site. The elevation accuracy of the post-processed GPS coordinates estimated by LGO was 0.09 m.

The DEM generation using SfM was divided in five main steps: (1) pictures alignment, point matching, and point cloud generation, (2) densification of the point cloud, (3) mesh generation, (4) georeferencing, and (5) export of the model to a regular grid. The present DEM was generated using the software Agisoft Photoscan, which offers several functions to perform a semi-automated correction for each of the aforementioned steps. Furthermore, the software uses the metadata of each picture to evaluate the lens distortion model, allowing us to treat all the photos together, even if taken by two different cameras and at variable focal lengths and apertures. The criteria used to correct the DEM within the reconstructing process were the removal of clusters or single outliers and the smoothness of the ice surface. Step (3) results in a dimensionless 3D model of the glacier, which was subsequently georeferenced by manually identifying the GCPs in the pictures that build the model and by assigning co-

ordinates to the identified GCPs. The model was exported as a grid of elevation values, that is, a DEM (Fig. 4), and as orthophoto, generated by a mosaic of the pictures used in the reconstruction (Fig. 3). The final SfM DEM was calculated based on a reduced set to 249 pictures (removing redundancies and assigning a similar number of pictures to each viewpoint).

Evaluation of DEM Accuracy and Resolution

The glacier was successfully modeled as a point cloud with 18.2 million points (step [2]) that evenly covered the ice surface and most of the surrounding slopes at a resolution of 1.6 points m^{-2} . The accuracy of the DEM was assessed by investigating the dependency of model residuals in X, Y, and Z direction on the number of GCPs used for the georeferencing and the spatial distribution of GCPs over the DEM area, following an approach similar to Tonkin and Midgley (2016) for UAV surveys. The GCP data set was divided in referencing and validation points. The errors of the two subsets, in the following termed referencing and validation error, were compared performing two tests. Firstly, the DEM was sequentially referenced with a spatially growing cluster of GCPs. Secondly, a cross validation was performed by randomly removing 60% of the GCPs and using them as validation points.

The results of the first georeferencing assessment are reported in Table 1 and Figure 5. The results agree with previous findings based on UAV surveys (Tonkin and Midgley, 2016) and show a dependence of the validation error on the spatial extent covered by the GCPs. Validation and referencing errors become comparable in mean and variance when the reference GCPs cover the maximum area coverable by the GCPs, that is, when they are evenly distributed over the entire glacier area.

The cross validation test was performed adhering to the maximum area principle, and the validation GCPs were selected avoiding spatial clusters. The Kolmogorov-

TABLE 1

DEM accuracy assessment: registration and validation errors and related variance for different numbers of ground control points (GCPs).

Number Of GCPs	Area GCP Total DEM area	Mean registration error (m)	Mean validation error (m)	Registration error variance (m)	Validation error variance (m)
4	0.0111	-0.17	1.40	0.91	4.62
5	0.0189	-0.20	-2.26	0.82	5.23
6	0.0322	0.26	1.34	0.80	2.37
7	0.1185	0.36	0.79	0.79	1.29
8	0.3704	0.26	-0.10	1.11	0.90

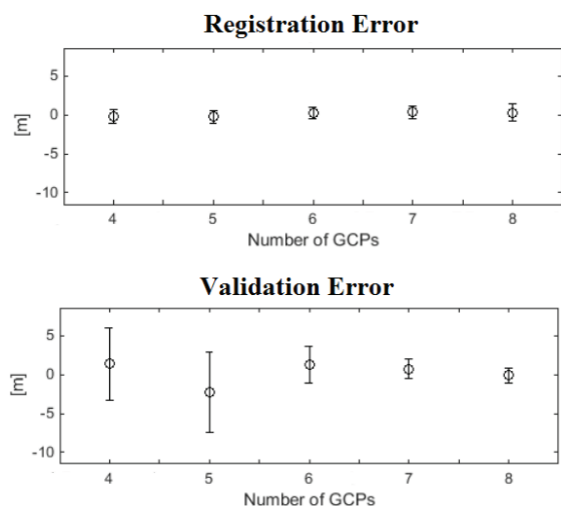


FIGURE 5. Registration and validation errors as functions of the number of the GCPs. Error bars represent residuals' variance. Note that the glacier surface area covered by the GCPs is proportional to their number. While the registration error does not depend on the number of GCPs, the validation error and its standard deviation decrease with an increasing number of GCPs. At eight GCPs the validation and registration errors become very similar.

Smirnov test on the residuals of four DEMs, each referenced with 20 randomly selected GCPs, highlighted no statistically significant difference among the models. On the basis of this result, we conclude that 20 reference GCPs, evenly distributed over the ice surface, are sufficient for georeferencing the DEM. The same test performed on the residuals of a DEM georeferenced with the full data set of 138 GCPs confirmed that there is no statistically significant difference to a DEM referenced with 20 randomly but evenly distributed points. Nevertheless, the DEM finally used for calculating the geodetic mass balance (Fig. 4) is the one referenced with the full GCP data set. Analysis of the residuals of the elevations indicates an elevation confidence interval (95%) of 1.87 m for the Z-coordinates. The final DEM was exported on a regular grid at a native resolution of 0.73 m.

1985 Aerial DEM

The aerial photos were recorded in 1985 at a scale of 1:150,000 as part of a Greenland-wide mapping campaign taking place during 1978 to 1987. A 25 m DEM and 2 m orthophotograph were produced for the entire ice-free parts of Greenland and the margin of the ice sheet (Korsgaard et al., 2016). Here we used the 1985 images to create an additional DEM in 10 m horizontal resolution (Fig. 4) and a 2 m orthophotograph (Fig. 1). The images were aero-triangulated following the ap-

proach described in Korsgaard et al. (2016), which consists of using GPS ground control points measured as part of the GPS-based REFGR Greenlandic reference network. Using the software SOCET SET 5.6 from BAE-Systems, multiple DEMs were generated using a suite of different strategies for automated terrain extraction to account for low contrast areas in the photos. Subsequently, the Figure-of-merit values, an indicator of the quality of the terrain extraction, were computed and chosen for each pixel using the NGATE module in SOCET SET 5.6. High values of the Figure-of-merit are interpolations, and low values are elevations measured in several images.

Determining Geodetic Mass Balance

Glacier surface elevation change from 1985 to 2014 was calculated from the 2014 and 1985 DEMs. Because the two DEMs are of differing spatial resolution, the 2014 DEM was down-sampled to the grid size of the 1985 DEM, that is, 10 m. The potential vertical and horizontal shifts between the DEMs were addressed by coregistration, optimizing on the X, Y, and Z Cartesian coordinates to minimize the vertical difference. Coregistration was based on areas of stable terrain outside the glacier perimeter where height change is expected to be zero. The coregistration indicates a horizontal mean shift of 1.25 m in the eastern direction, 0.35 m in the northern direction, and 2.3 m in the vertical direction. The standard deviation of the shifts is calculated to be 1.6 m east, 1.0 m north, and 2.0 m vertical. The 1985 DEM was therefore corrected for the mean shifts to avoid systematic errors in calculating the 1985 to 2014 glacier surface elevation change. The standard deviation of the vertical differences of the DEMs in stable areas was used as uncertainty quantification where the area of both DEMs area is considered reliable.

The approach described above allowed calculating glacier surface elevation change for only 50% of the 1985 glacier surface because the 1985 DEM shows pronounced triangulation artifacts over most of the upper half of the glacier (Fig. 4). In this area, corresponding to the 1985 accumulation area, automated photogrammetry failed to match pixels on low-contrast snow surfaces (Fig. 2). Visual inspection of the aerial photographs, however, indicated that the snow-covered areas are not completely featureless, and small crevasses, rocks, and irregularities in the snow cover can be recognized. Such features were used to generate manually 192 points of 1985 surface elevation (Fig. 2) in the areas where automated photogrammetry has failed. Surface elevation at these points is subject to uncertainty because of the manual and somewhat subjective process. The uncertainty was quantified

by manually measuring 20 points in the ablation area and comparing their elevation to the respective grid value in the 1985 DEM. This analysis shows a standard deviation of 4.3 m between the two methods. However, the identification of points in the snow-covered area is more challenging than in the ablation area. To address this issue, we identified outliers in the manually measured 1985 elevations by analyzing the surface elevation change (1985 to 2014) at the manually measured points and thereby assumed that neighboring points exhibit similar elevation changes. This assumption is valid within a certain distance radius for which the lowering of the glacier's surface can be considered homogeneous. This distance was evaluated by finding the points' average deviation within a varying size neighborhood (from 50 to 1200 m). Average deviation is minimal (8.4 m) within a neighborhood of 100 m (Fig. 6). The value of minimal average deviation was defined as the maximal accepted variation of the surface lowering within a 100 m radius. Subsequently, elevation change at each point was compared to its neighboring points within a 100 m buffer. Points deviating more than the maximal accepted variation of the surface lowering were considered outliers and discarded. After the filtering, 112 points were left. The manually generated and filtered points were subsequently used to calculate 1985 to 2014 elevation change for the 1985 accumulation area.

We calculated spatially continuous surface elevation change over the 1985 accumulation area using a kriging approach (e.g., Rippin et al., 2011; Carrivick et al., 2015). Because the manually extracted elevations are rather sparse in the area, surface elevation change obtained from DEM differencing over the 1985 ablation area was used

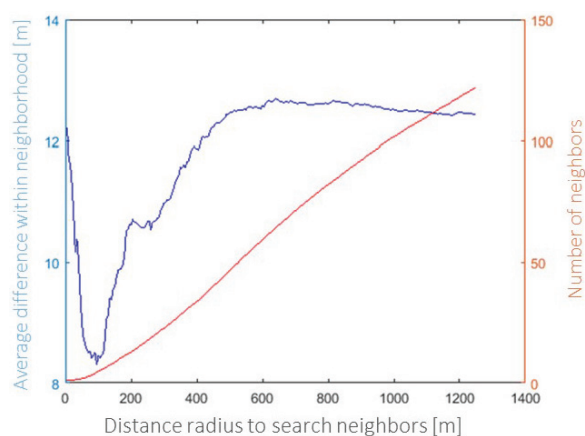


FIGURE 6. Average deviation of surface lowering (1985 to 2014) at the manually selected points, expressed as a function of horizontal distance. For a neighborhood distance of 100 m, the deviation is minimal, that is, 8.4 m. On average, we find 4.5 neighboring points within 100 m.

to calibrate the method. Firstly, a linear trend between elevation and ice thickness change was observed, indicating glacier loss is smaller at higher altitudes. Hence, we applied universal kriging, using elevation as a regression variable (Isaaks and Srivastava, 1989). Secondly, the empirical semivariogram was computed on elevation changes in the 1985 accumulation area (i.e., at the points for which the 1985 surface elevation was determined manually) and 112 randomly selected samples of ice thickness changes in the 1985 ablation area (i.e., determined from direct DEM differencing). This way, we modeled the semivariance using both data from the ablation and accumulation area, ensuring the consistency of the spatial variability of the ice thickness change process over the entire glacier. The empirical semivariogram was fitted using a spherical model. The semivariogram was evaluated and modeled using the R functions “variogram” and “vgm,” whereas the universal kriging interpolation was performed using the function “krige”; both are available in the package “gstat” (Pebesma, 2004). Eventually, we joined the gridded surface elevation change resulting from kriging interpolation (1985 accumulation area) with the grid of elevation changes derived from DEM subtraction (1985 ablation area) into a grid of elevation changes covering the entire 1985 glacier area (Fig. 7).

Ice Thickness Distribution and Ice Volume

A total of 37 GPR profiles were collected in the field from which we retrieved the ice thickness and estimated the total ice volume of Aqutikitoq glacier. An ideal grid where the survey lines extend over the entire glacier was envisaged, but had to be adapted (Fig. 8) because of inaccessible areas that include crevasses and areas with a risk of rock fall. The glacier was mostly depleted of firn and snow and, consequently, all measurements were carried out on an ice surface. The GPR unit used was a Malå ProEx combined with a 50 MHz Rough Terrain Antenna. The ice thickness profiles were obtained by continuously moving the GPR on the glacier surface along survey lines, thereby keeping the transmitter and receiver, included in the flexible hose-shaped antenna, at a fixed geometry. The spatial position of the GPR was continuously recorded from a hand-held GPS. The accuracy of the GPS receiver in the X and Y direction was a few meters. For the conversion of travel time of the GPR signal to ice thickness, a mean velocity of 0.168 m ns^{-1} of electromagnetic waves in glacier ice was applied. The value was considered appropriate for a polythermal glacier based on Bogorodsky et al. (1985), Bælum and Benn (2011), Pettersson and Holmlund (2003), Cuffey and Paterson (2010), Friedt et al. (2013), and Ai et al. (2014).

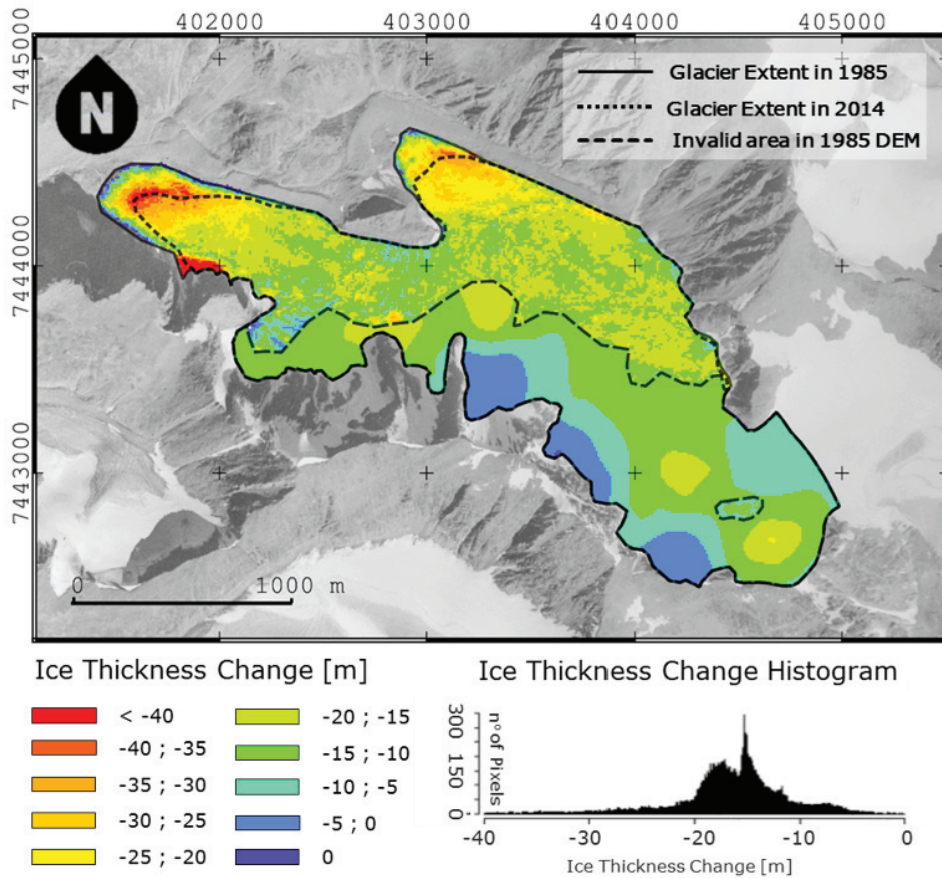


FIGURE 7. Ice thickness loss (m) of Aqutikitsoq glacier from 1985 to 2014 using the difference of DEMs in the 1985 ablation area and universal kriging in the 1985 accumulation area. Coordinates refer to UTM zone 22N.

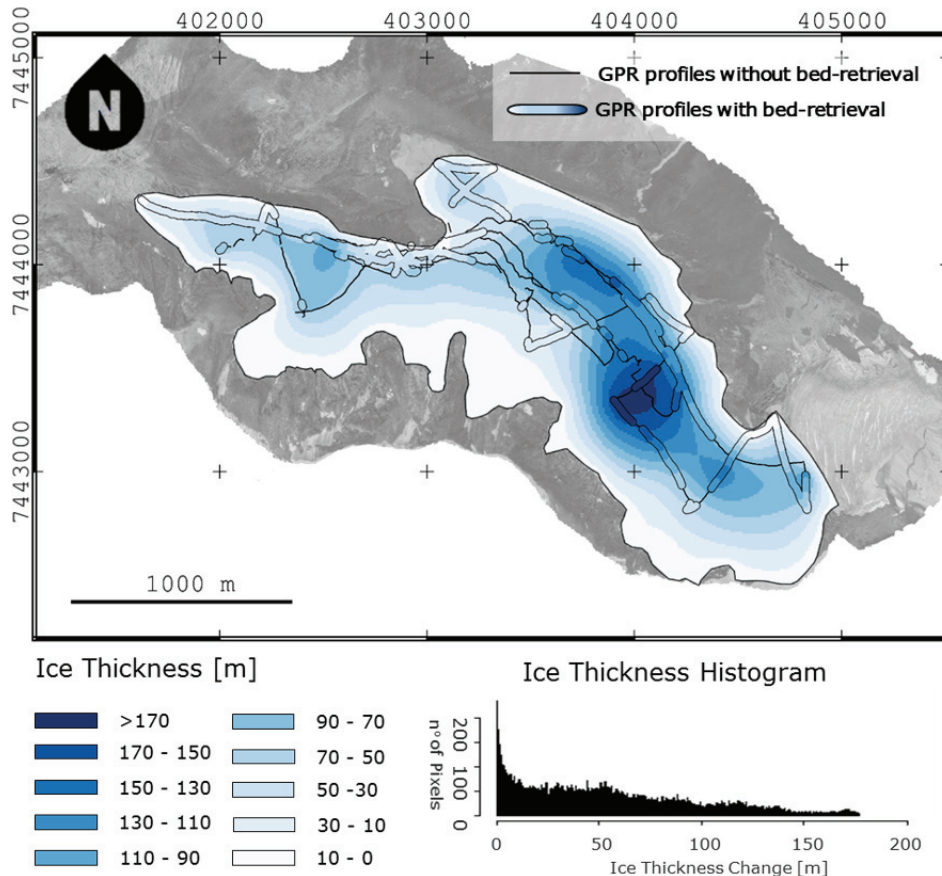


FIGURE 8. Location of ground penetrating radar (GPR) profiles and ice thickness distribution, August 2014. Coordinates refer to UTM zone 22N.

The software ReflexW (version 7.1.4) was used for post-processing the GPR profiles and identifying the bedrock. Four filters were applied: (1) subtract mean (dewow) filter for removing low frequency parts, (2) manual gain filter to enhance signals from greater depths, (3) 2D background removal filter for removing temporally consistent noise, and (4) 1D bandpass Butterworth filter to eliminate very low and high frequency parts. Tentatively, we migrated selected radar transects. Interpretation of bed topography from the bed returns, however, did not change in our case and consequently we decided to skip migration of the remaining data.

The analysis of the radar data shows for many profiles the characteristics of a polythermal glacier with cold ice nearly transparent on top and strong internal reflections from temperate ice closer to the bed (cf. Bamber, 1988; Pettersson and Holmlund, 2003). Attention was paid not to misinterpret the interface of cold and temperate ice for the glacier bed. Where an unambiguous bed-return was missing, no glacier bed was mapped. The error of the interpretation of GPR profiles was evaluated through quantification of the residuals in ice thickness at all intersecting profiles, that is, by crossover analysis. The total number of intersections is 16, and the standard deviation of the differences is 1.9 m. A continuous bedrock topography was then obtained by ordinary kriging using the ice thickness measurements and the glacier outline (ice thickness equals zero) obtained from the 2014 SfM orthophoto (Binder et al., 2009; Ripplin et al., 2011; Williams et al., 2016).

RESULTS

Ice Thickness Distribution and Ice Volume

A total of 18.5 km of GPR profiles was measured. Thereof, 8.5 km are interpreted as showing unambigu-

ous bed returns (Fig. 8). The remaining profiles of lacking or ambiguous bed return were discarded. Most of the profiles show cold ice at the top and temperate ice close to the glacier bed. The cold ice layer is typically a few decameters thick; however, at certain locations the radar data are nearly free of internal scatter down to the bedrock at 140 m depth and thus indicate that locally the ice column might be entirely cold.

On the basis of interpolated ice thickness, the total ice volume of Aqutikitsoq glacier is estimated to be $148.6 \pm 47.7 \cdot 10^6 \text{ m}^3$ in August 2014 (Table 2). The uncertainty of the ice volume was first quantified at each grid cell using the spatially distributed semivariance associated with the ordinary kriging interpolation. Then, total volume uncertainty was calculated by summing the root square of the semivariance (i.e., the standard deviation) of each grid cell over the entire glacier area.

The maximum depth in Aqutikitsoq glacier is measured to be 174 m (cf. Fig. 8). The average ice thickness over the entire glacier is calculated to be $51.8 \pm 16.6 \text{ m}$. The mean measured ice thickness calculated solely from the GPR profiles is 63.8 m. The difference from the calculated ice thickness is explained by the fact that steep and shallow areas could not be measured.

Geodetic Volume and Mass Balance

The surface elevation change over the 1985 glacier area is between -10 and -30 m in most areas, and the average elevation change equals $-17.4 \pm 3.3 \text{ m}$. On the two tongues, however, the surface lowering reaches values from 40 to almost 60 m (Fig. 7). Areas with limited elevation change are primarily located at higher altitudes and on the north-facing mountainside. Uncertainties in calculated elevation changes are because of the digitizing error in the 1985 accumulation area and

TABLE 2

Volumes and uncertainty calculation for ice thickness in 2014 and volume change between 1985 and 2014.

Surface	Glacier volume		Δh	
	2014	Ablation area	Accumulation area	Entire glacier
Computation method	GPR + ordinary kriging	Difference of DEMs 1985 and 2014	Manual points selection and universal kriging	Sum of the two surfaces
Uncertainty estimation method	Square root semivariance map	σ of difference in altitudes in stable areas	σ between manual points and 1985 in ablation area	Each surface has its uncertainty
Uncertainty	(5.3–29.9) m	2.0 m	4.3 m	2.0 m; 4.3 m
Volume estimation (10^6 m^3)	148.623	30.156	19.653	49.809
Total Uncertainty (10^6 m^3)	47.645	3.111	6.285	9.396
Relative Uncertainty (%)	32.06%	10.32%	31.98%	18.86%

TABLE 3

Length, area, volume, and ice thickness of Aqutikitsoq glacier in 1985 and 2014, as well as absolute and relative changes in the aforementioned parameters.

	1985	2014	Absolute change	Relative change (%)
Length (km)	4.22	4.05	-0.17	-4
Planar area (10^6 m ²)	3.05	2.87	-0.18	-5.8
Ice volume (10^6 m ³)	255.5 ⁽¹⁾	196.3 ⁽¹⁾	-59.2 ⁽¹⁾	-23.2 ⁽¹⁾
	141.3 ⁽²⁾	101.0 ⁽²⁾	-40.4 ⁽²⁾	-28.6 ⁽²⁾
Mean thickness (m)	83.8 ⁽¹⁾	68.4 ⁽¹⁾	-15.4 ⁽¹⁾	-18.4 ⁽¹⁾
	46.4 ⁽²⁾	35.2 ⁽²⁾	-11.2 ⁽²⁾	-24.1 ⁽²⁾

⁽¹⁾Values calculated with maximum expected ice thickness in 2014 and maximal volume change between 1985 and 2014.

⁽²⁾Values calculated with minimum expected ice thickness in 2014 and minimum volume change between 1985 and 2014.

the coregistration error between the two DEMs in the 1985 ablation area (cf. Table 2)

Over the 1985 ablation area, the total volume change is $30.2 \pm 3.1 \cdot 10^6$ m³. For the 1985 accumulation area, the universal kriging extrapolation calculates a volume change of $19.7 \pm 6.3 \cdot 10^6$ m³. Volume change is converted to mass change assuming an average density of 850 ± 60 kg m⁻³ (cf. Huss, 2013), yielding a mass loss of 0.042 ± 0.008 Gt.

Given the unique data set that combines volume measurements with geodetic mass balance, the relative volume loss of the Aqutikitsoq glacier is estimated to be between 23.2% and 28.6% of its 1985 volume. This estimation is based on the extremes in the uncertainties of the ice thickness and thickness change, as presented in Table 3. This results in a range of possible values of relative volume change, which is here expressed as the mean range value \pm the range's amplitude, that is, $25.9\% \pm 2.7\%$.

DISCUSSION

Quality of the SfM Elevation Model and Geodetic Mass Balance

The 2014 DEM is affected by three sources of uncertainty: the position accuracy of the GCPs, the georeferencing process, and the systematic deformations induced by the software in the model. The elevation confidence interval of the 2014 DEM (1.87 m) is about one order of magnitude greater than the GCPs coordinates' precision (0.09 m), indicating that GPS accuracy does not contribute substantially to the overall error.

Deformations of the model introduced by the software have not been directly assessed. However, the survey strategy based on collecting pictures on a near-

circular orbit around the glacier, varying the distance and the inclination of the camera with respect to the target, is expected to produce DEM errors in the order of magnitude of 0.1 m (James and Robson, 2014).

The georeferencing process is the main error source of the 2014 DEM. Georeferencing requires localizing the GCPs in the pictures where the pixels have a ground resolution ranging from tens of centimeters to meters, depending on the distance between the GCP and the camera. Hence, the identification of the GCPs in the pictures is sometimes ambiguous and subject to user interpretation.

The georeferencing error is absolute with respect to an absolute reference system. However, the geodetic mass balance is calculated from the coregistered 2014 and 1985 DEMs, rendering this source of error irrelevant in the context of a relative registration. Therefore, considering the major sources of uncertainty, that is, limitations in the 1985 DEM, we conclude that the SfM DEM does not contribute significantly to the overall uncertainty of calculated geodetic mass balance.

In the 1985 accumulation area, the uncertainty sources had to be addressed differently from the ablation area, as they are associated to the process of manual elevation measurements for selected points. The semivariance map produced by the universal kriging interpolation, however, results in values that are smaller than 4.3 m, which is the value obtained by comparison of surface elevation at manually measured points and automatically derived 1985 DEM. Therefore, 4.3 m of uncertainty was used as a more conservative estimate. Even this estimate, however, might be optimistic. The value of 4.3 m was derived over the 1985 ablation area where the glacier surface is of high contrast and manually measuring surface elevation at selected point locations was arguably easier than in the 1985 accumulation area.

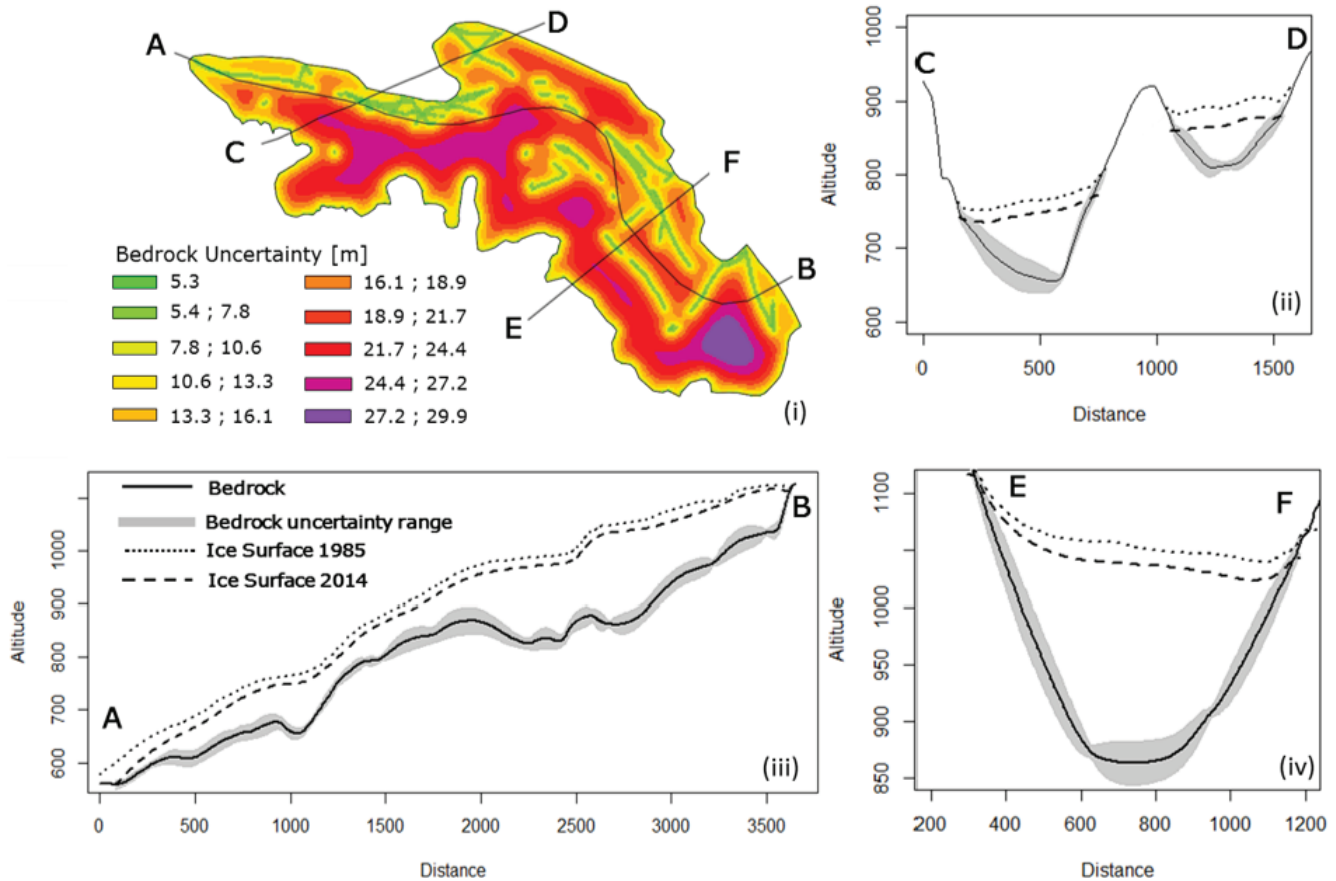


FIGURE 9. Uncertainty in the bedrock reconstruction given by the ordinary kriging approach (plot 1 in upper left). Three transects are shown (plots 2, 3, and 4) and vertically exaggerated by a factor 3 to visualize the surface lowering of the glacier surface and the uncertainty in bedrock interpolation.

Measured Ice Thickness and Calculated Ice Volume

The main source of error in the ice thickness measurement is considered to be the interpretation and digitization of the GPR profiles. Uncertainty in interpretation of the GPR profiles is 1.9 m, as indicated by the crossover analysis. Given the available GPR equipment, it was not possible to validate the propagation velocity of 0.168 m s^{-1} through a common midpoint survey. Instead, we relied on propagation velocities measured in polythermal glaciers in earlier studies. Published values do not vary strongly, and uncertainty related to our velocity assumptions is thus assumed to be relatively small.

The interpolated ice thickness appears realistic and shows a typical distribution with thick glacier ice underneath the flat glacier sections and thinner ice in steeper sections (e.g., Haeberli and Hölzle, 1995). The distribution of radar profiles in the flat upper section of the glacier is relatively dense and allows for a reliable interpolation and assessment of ice volume where the glacier is thickest and most of its ice is stored. Nevertheless, ice thickness interpolation is the major source of uncertainty in esti-

imating Aqutikitsq glacier volume and can locally reach 30 m (Fig. 9 and Table 2). Uncertainty resulting from interpretation of the GPR profiles (1.9 m) is relatively small compared to the nugget of the kriging semivariogram (5.3 m, cf. Fig. 9). This is because a considerable fraction of the glacier area lacks GPR data (cf. Figs. 8 and 9). These areas at the orographically left glacier perimeter were inaccessible mainly due to crevasses and risk of rock fall from the steep adjacent slopes. The ice thickness for these areas has thus been derived from interpolation between the GPR measurements and the ice margin where ice thickness is 0 m. The influence of these glacier sections on overall uncertainty in ice volume estimation is somewhat reduced by the general steepness and thus relatively small ice thickness.

Volume Loss in a Local to Global Context

From 1985 to 2014, Aqutikitsq glacier has lost substantial amounts of ice at all elevations. Ice loss is maximal at the tongue, where thinning rates exceed 1 m a^{-1} . However, even at high elevations, average thinning rates

amount to $>0.3 \text{ m a}^{-1}$. It appears the glacier has no accumulation area left nowadays, which is underlined by our 2014 orthophoto (Fig. 3) showing only marginal patches of remaining snow. The glacier is thus very likely to disappear, even if climate does not change any further.

Bolch et al. (2013) and Gardner et al. (2013) used ICESat data to assess volume change of glaciers and ice caps for all of Greenland. However, ICESat data cover only a relatively short time period (2003 to 2009), and the measurements along widely spaced lines require extensive extrapolation involving a considerable level of uncertainty. After Mittivakkat glacier on the southeast coast (cf. Yde et al., 2014), Aqutikitoq is only the second glacier on Greenland with detailed and longer-term volume change data. While Aqutikitoq glacier volume decreased from $\sim 0.2 \text{ km}^3$ to $\sim 0.14 \text{ km}^3$ ($\sim 25\%$) over the time period 1985 to 2014, the larger Mittivakkat glacier (15.8 km^2 in 2012) decreased from 2.02 km^3 to 1.44 km^3 ($\sim 29\%$) in the period 1994–2012 (Yde et al., 2014). Because Mittivakkat did not change substantially from 1981 to 1994 (Knudsen and Hasholt, 1999) relative volume losses of both glaciers are rather similar at roughly a quarter of their early or mid-1980s volumes. Obviously, at a given rate of thinning a thinner glacier will experience a larger relative volume loss.

The measured 1985–2014 thinning rate of $\sim 0.6 \text{ m a}^{-1}$ at Aqutikitoq glacier is similar to, for example, the observed mean geodetic mass balance for 1980–2010 for all glaciers of the Swiss Alps ($-0.62 \pm 0.07 \text{ m w.e. a}^{-1}$; Fischer et al., 2015). While the sample of measured Greenland glaciers is much smaller and also observation periods differ slightly, our data from Aqutikitoq and the studies on Mittivakkat (Yde et al., 2014) indicate that current changes on Greenland are similar to mid-latitude glaciers. The data set for Aqutikitoq glacier thus makes a small but valuable contribution to an improved understanding of Greenland glacier changes and will, we hope, motivate further research on the changing ice masses surrounding the Greenland ice sheet.

CONCLUSION

Our study demonstrates the usefulness of ground-based SfM in establishing high-quality DEMs over a smaller (2.85 km^2) valley glacier. The advantages of the method are low cost, low resources (e.g., no UAV needed), and flexibility as the required images and GCPs can be acquired with limited logistical effort. Using these advantages and combining the SfM survey with GPR measurements, a comprehensive data set describing surface topography and ice thickness of a glacier was compiled. The data are of particular interest as our measurements constitute the first such detailed data set

for a glacier on Greenland's west coast. Therefore, the Aqutikitoq ice thickness measurements have already been extensively used as one of 18 globally distributed test glaciers in the "ice thickness models intercomparison experiment" (ITMIX) (Farinotti et al., 2017).

We have explored the applicability of a newly available Greenland-wide DEM for the 1970s to 1980s (here in this study 1985) to assess geodetic mass balance of a glacier. In the case of Aqutikitoq glacier, extended low-contrast areas in the aerial photos from 1985 cause a number of challenges that have been addressed by manual determination of 1985 surface height at point locations in low surface contrast areas. While this allowed calculation of geodetic mass balance of Aqutikitoq over the time period 1985 to 2014, the manual approach appears challenging for application to larger glacier samples.

Our findings indicate substantial mass loss of the investigated glacier, which lost $25.9\% \pm 2.7\%$ of its volume over the past three decades. With the historical DEM at hand and new DEMs becoming available (e.g., TanDEM-X, ArcticDEM; Zink et al., 2014; Noh and Howat, 2015), we suggest that the investigations could be extended to larger glacier samples to assess Aqutikitoq's representativeness in a wider context.

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