Volumetric 3-D Vector Flow Measurements using a 62+62 Row-Column Addressed Array

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Volumetric 3-D Vector Flow Measurements using a 62+62 Row-Column Addressed Array

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Abstract—Experimental results from volumetric 3-D vector flow measurements using a 62+62 row-column addressed (RCA) array are presented. A plane-by-plane steered transmit sequence and its post processing steps are described for obtaining 3-D vector flow in a volume. A modified version of the transverse oscillation (TO) velocity estimator is used, which exploits the focal lines generated with the tall elements of a RCA array. Validation of the method is made in a flow-rig system where circulating blood mimicking fluid produced a steady parabolic flow profile with a flow rate of 13.7 mL/s, translating to a peak velocity of 24.1 cm/s. A volume rate of 16.4 volumes per second is obtained, and estimated flow rates based on nine steered planes can be translated to a peak velocity $v_0$ via the relation $v_0 = 2Q/(\pi R^2)$.

\section*{TABLE I
\textbf{TRANSDUCER PARAMETERS}}

\begin{tabular}{|l|l|}
\hline
Parameter & Value \\
\hline
Transducer type & 2-D Row-Column \\
Number of elements in $x$ & 62 \\
Number of elements in $y$ & 62 \\
Pitch in $x$ & $0.27 \text{ mm} = 0.53\lambda$ \\
Pitch in $y$ & $0.27 \text{ mm} = 0.53\lambda$ \\
Width & 0.245 mm \\
Kerf & 0.025 mm \\
Sampling frequency & 35 MHz \\
Center frequency & 3.0 MHz \\
Footprint size & $1.67 \times 1.67 \text{ cm}^2$ \\
\hline
\end{tabular}

\section{II. MATERIALS & METHODS}

\subsection*{A. Transducer array and scanner}

An piezoelectric RCA 2-D array \cite{7,4} with 62+62 elements and roll-off hardware apodization \cite{8} was used, with properties as described in Table I. The probe was connected to the ultrasonic research scanner SARUS \cite{9} and raw RF data from all 124 channels were sampled at 35 MHz.

\subsection*{B. Flow-rig system}

An in-house built flow-rig system was used to validate the estimated volumetric 3-D velocities. The flow-rig contains a long inlet of 1.2 m which ensures a steady laminar parabolic flow profile at the measuring site. Blood mimicking fluid is driven inside the rubber vessel ($R = 6 \text{ mm}$) by a centrifugal pump in a closed loop circuit. The volume flow $Q$, is measured with a MAG 1100 flow meter (Danfoss, Hasselager, Denmark), which, due to the assumption of a laminar parabolic flow, can be translated to a peak velocity $v_0$ via the relation $v_0 = 2Q/(\pi R^2)$.

\subsection*{C. The transverse oscillation method}

Conventional use of transverse oscillation (TO) velocity estimator requires emissions weakly focused in a point \cite{10,11}. After each transmit event, three lines are beamformed; a center line used for the axial velocity estimate, and two lines spatially separated by $\pm \lambda_x/8$, where $\lambda_x$ is the lateral wavelength, required for the transverse velocity estimate. Thus, from one transmit event 2-D vector flow information can be extracted along the beamformed centerline. With RCA arrays, however, focusing will result in a focal line, rather than
Volumetric Sequence

Fig. 1. The RC sequence for obtaining volumetric 3-D vector flow using TO: first, the N row emissions are made followed by the M column emissions. For each row emission, 3-D velocities are estimated in the plane defined by the focus line and the center of the emitting aperture. To make this, three lines (center and $\pm \lambda_x/8$, where $\lambda_x$ is the lateral wavelength) are beamformed for each line along which estimates are desired using the signals received by the column elements. This yields the velocity components in the $x$ and $z$-directions. By similarly transmitting with columns and receiving with rows, the $y$ and $z$-components are found. These are then combined to attain the 3-D vector information.

a focal point, due to the tall element dimensions. This can be exploited to beamform several TO pairs along the focal line, such that 2-D vector flow can be estimated in an entire plane from one single transmit event [5] as illustrated in Fig. 1.

D. Emission sequence

A plane-by-plane 3-D volumetric vector flow imaging emission sequence was designed by expanding the single plane approach described in previous work [5]. A schematic illustration of the applied steered transmit sequence is seen in Fig. 1. As described in Section II-C, 2-D vector flow can be obtained in an entire plane from each transmit event. By transmitting $N$ distinguishable steered focused emissions by only exciting row elements and perform TO beamforming on each of the events, results in $N$ planes in a volume containing 2-D vector flow estimates. By interleaving the sequence with $M$ steered focused emissions where only column elements are excited, yields 2-D vector flow information also in the orthogonal dimension. Combining the 2-D vector flow information from the row and column emissions results in volumetric 3-D vector flow in the intersections of the $N$ and $M$ planes as illustrated...
in Fig. 1. The repeating volumetric sequence is schematically written as

\[ C_1 \rightarrow C_2 \rightarrow \ldots C_M \rightarrow R_1 \rightarrow R_2 \rightarrow R_3 \rightarrow \ldots R_N \]

where \( C_i \) indicates focal line index \( i \) when emitting with column elements and \( R_i \) similarly for row elements.

The volumetric sequence consisted of \( N = 11 \) row emissions and \( M = 9 \) column emissions and was designed to acquire continuous data. The row emissions were steered from \(-15^\circ\) to \(15^\circ\) in steps of \(3^\circ\) and the column emissions from \(-8^\circ\) to \(8^\circ\) in steps of \(2^\circ\). This produces estimates along the intersections of the \( N \times M = 99 \) planes corresponding to a \(16^\circ \times 30^\circ\) volume. The c-plane at \(3\) cm depth spans an area of \(16.1 \text{ mm} \times 8.4 \text{ mm}\).

E. Data processing

The emission sequence was repeated 2240 times corresponding to 4.3 seconds of data. The data was beamformed offline on a Linux cluster using a delay-and-sum beamformer specialized for RCA arrays [8]. Velocities were estimated with averaging over 32 estimates yielding 70 independent velocity estimates for each point using the TO method.

The nine scan-planes corresponding to cross-sections of the vessel are extracted for volume flow estimation. Volume flow is calculated by integrating the angle corrected estimates across each cross-sectional plane. The bias with respect to the flow rate reported by the flow rig and standard deviations are calculated for the volume flow through each scan plane.

III. EXPERIMENTAL SETUP

With the described probe and scanner a measurement was performed with the volumetric 3-D emission sequence. The applied transmit frequency was 3.0 MHz and the pulse repetition frequency \( f_{prf} \) was 10.5 kHz. For the continuous data acquisition sequence presented here with \( M + N = 20 \) emissions and averaging over 32 estimates, 16.4 independent 3-D vector flow volumes per volume are attained.

The flow rate chosen in this setup was 13.7 m L s\(^{-1}\), translating to a peak velocity of 24.1 cm s\(^{-1}\). The center of the vessel was located 2.9 cm from the transducer’s surface.

IV. RESULTS

A volumetric representation of the mean out-of-plane velocity estimates are shown in Fig. 2. Based on the velocity component perpendicular to the cross-sectional area, the mean flow rate for each plane was calculated and are shown in Fig. 3. A positive bias was found for all of the steering angles, with the smallest at \(2^\circ\) (6.5 \%) and the largest at \(-8^\circ\) (21.2 \%). Similarly, the smallest standard deviation was found for the plane steered by \(8^\circ\) (\(\pm 3.0 \%\)) and the largest standard deviation was at a steering of \(0^\circ\) (\(\pm 3.8 \%\)). The overall mean flow rate, based on the estimated value for each plane was 15.2 \(\pm 0.7\) m L s\(^{-1}\). However, erroneous velocities are estimated at larger steering angles, which may be due to the chosen lateral wavelength not matching the expected velocity range or that a further optimization of the beamforming for steered directions are required.

An illustration of the present parabolic flow is seen in Fig. 4, where the mean out-of-plane velocity component for the nine cross-sectional scan planes are shown. As expected, similar
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