Offshore Wind Power Plant Technology Catalogue - Components of wind power plants, AC collection systems and HVDC systems

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Offshore Wind Power Plant Technology Catalogue

Components of wind power plants, AC collection systems and HVDC systems

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October, 2017
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By
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Glossary

AC  Alternating Current. 1, 2
CSC  Current Source Converter. 2, 14
DC  Direct Current. 2
DFIG  Doubly-fed induction generator. 4
DRU  diode rectifier unit. 17
FRC  Fully Rated Converter. 4
HTS  High Temperature Superconducting. 6, 8, 9
HVAC  High Voltage Alternating Current. 1, 2, 6, 7, 10
HVDC  High Voltage Direct Current. 1, 2, 10, 13, 14
LCC  Line Commutated Converter. 12, 14–16
MI  Mass Impregnated. 10
MV  Medium Voltage. 1
MVAC  Medium Voltage Alternating Current. 7
OHL  Overhead Line. 2
OWPP  Offshore Wind Power Plant. 1, 3, 14, 23
PMSG  permanent magnet synchronous generator. 4
TCSC  Thyristor Controlled Series Compensation. 28
TRL  Technology Readiness Level. 3
VSC  Voltage Source Converter. 2, 12, 14–16
WPP  Wind Power Plant. 7, 8
WRIG  wound rotor induction generator. 4
WRSG  Wound rotor synchronous generator. 4
WT  Wind Turbine. 1
XLPE  Cross-linked polyethylene. 6, 7, 10
1 Introduction

Traditionally, Offshore Wind Power Plants (OWPPs) are connected through many components as shown in the figure 1. An OWPP consists of controllable, variable speed Wind Turbines (WTs). These WTs are connected through Medium Voltage (MV) submarine cables typically at voltage level of up to 33-66 kV to the Offshore Alternating Current (AC) substation. The transformer in offshore AC substation steps up the voltage to 132-200 kV for further transmission. The stepping up of voltage is important to reduce the current flow through the cables. Reduced current flow decreases the copper/aluminium requirement for the cables as well reduce the power losses through them.

Offshore AC substation can be connected to the grid at shore either directly through High Voltage Alternating Current (HVAC) cables or through High Voltage Direct Current (HVDC) converters and HVDC cables.

HVDC transmission technology has been developed and applied from as early as 1880s. In the early 1950s, HVDC transmission technology was used for the development of subsea interconnection with mercury arc valves used for electric AC/DC converters. HVDC transmission lines are applied when there is a need to transport high electrical power over long distances and/or in a controlled manner.

In terms of submarine applications, HVDC transmission technology is mainly applied either for connecting offshore platforms and OWPPs to land or for transmitting electricity over long distances through the sea where overhead lines cannot be used. Another subsea application can be for connecting the island networks to the mainland. HVDC transmission is the most viable solution available for the transfer of high
power across long subsea distances. However, choice between HVAC and HVDC is based on economic considerations. Furthermore, HVDC is a proven technology for transmission projects that interconnect asynchronous networks.\textsuperscript{1} HVDC subsea transmission technology also has been largely applied in single point-to-point connections. The system approach gives the effective rating. Current maximum HVDC power under planning is up to ± 600 kV and 2200 MW per bipole as a system.\textsuperscript{2} Looking into the future, meshed HVDC subsea systems may become available. However, development of meshed HVDC networks today is still limited as circuit breaker technology for DC grid is still not commercially matured. Circuit breakers, so called switchgear, secure the operation of the meshed HVDC system. As per the Europacable report,\textsuperscript{3} the development of this circuit breaker technology is in final development phase.

Vaféas et. al.\textsuperscript{4} studied and enumerated the benefits of HVDC technology over conventional HVAC in the REALISEGRID project. HVDC technology has been proved to be attractive for various applications such as long distance power transmission, long submarine cable links and interconnection of asynchronous systems. There are mainly two types of HVDC technology. The more recent technology is self-commutated Voltage Source Converter (VSC) technology. VSC technology is more flexible than the more conventional line-commutated Current Source Converter (CSC) since it allows controlling active and reactive power independently.\textsuperscript{5} Independent power flow controllability along with the advantage of increased transmission capacity can make HVDC technology preferable to conventional HVAC. Although the choice of HVDC vs. HVAC should be made based on economic studies; since the investment cost of a VSC-HVDC converter station is generally higher than HVAC substation. However, the overall investment costs of a Direct Current (DC) transmission link can be lower than those ones of a corresponding AC interconnection if a certain transmission distance is reached called “break-even” distance.\textsuperscript{6} The break-even distance upon which DC is more economical is project dependent (typically between 80 and 120 km for offshore submarine cable connections, while for onshore applications, the break-even distance between an AC and DC Overhead Line (OHL) is in the order of magnitude of 700 km)\textsuperscript{7} and the decision of using AC or DC should result from a techno-economic

\begin{enumerate}
\item Ibid.
\item Gianluigi Migliavacca, Advanced technologies for future transmission grids (Springer Science & Business Media, 2012).
\item Ibid.
\end{enumerate}
analysis including the line, station and losses components of costs.\textsuperscript{8,9}

1.1 Motivation

Building an offshore grid is a technically complex endeavour implying a significant number of components. While for AC connections the technology is mature and well known, in the area of power electronics and HVDC technology the component development is in its more incipient phases. This has prompted for the creation of a technology catalogue covering all the main components needed when developing offshore wind power and grids projects.

The main purpose of this Technology Catalogue is to serve as a common source for the techno-economic assessments done in the Baltic InteGrid project. To qualify for this, it should include both technical characteristics and cost parameters for all the relevant components of an OWPP and its connection to the grid.

The technology development has been classified in four main categories in this technology catalogue and described in Table 1. European definition of Technology Readiness Level (TRL)\textsuperscript{10} is associated with the categories.

Table 1: Categories of technology development

<table>
<thead>
<tr>
<th>Category</th>
<th>Description</th>
<th>TRL\textsuperscript{11} today</th>
</tr>
</thead>
<tbody>
<tr>
<td>mature</td>
<td>commercially available today</td>
<td>9</td>
</tr>
<tr>
<td></td>
<td>- with (some) operational experience</td>
<td></td>
</tr>
<tr>
<td>young</td>
<td>full scale prototypes available</td>
<td>6-8</td>
</tr>
<tr>
<td></td>
<td>- very close to commercialization</td>
<td></td>
</tr>
<tr>
<td>future</td>
<td>some prototypes available</td>
<td>4-5</td>
</tr>
<tr>
<td></td>
<td>- but development still needed</td>
<td></td>
</tr>
<tr>
<td>distant future</td>
<td>proof of concept and small scale prototypes</td>
<td>1-3</td>
</tr>
<tr>
<td></td>
<td>- significant development still needed</td>
<td></td>
</tr>
</tbody>
</table>

1.2 Outline of the Report

This report aims to cover most of the technical components for offshore network starting from wind turbines up to the onshore connecting substation. This report contains small description of each of the components followed by stages of development, cost and lifetime.

\textsuperscript{8} Patrick PANCIATICI et al., “e-HIGHWAY 2050 Modular Development Plan of the Pan-European Transmission System 2050.”
\textsuperscript{9} Gianluigi Migliavacca, Advanced technologies for future transmission grids (Springer Science & Business Media, 2012).
2 Wind Turbines

2.1 Description

Wind turbine technology has been drastically improving and has become matured during the last decade. While wind turbine design objectives were traditionally convention-driven but they have been changed over these years to being optimized driven within the operating regime and market environment.\textsuperscript{12} Not only the wind turbines have become larger in size, but also the wind turbine technology have progressed from fixed-speed, stall-controlled and with drive trains with gearboxes, to become pitch controlled, variable speed and with or without gearboxes.\textsuperscript{13} Decreasing cost of power electronics also increasingly supports the trend toward variable speed turbines.

Offshore wind turbines are categorically converter based variable speed wind turbines.\textsuperscript{14}

The most commonly applied variable speed wind turbines can be categorized into two types:

2.1.1 Doubly-fed Induction Generator (DFIG) based Wind Turbine

Doubly-fed induction generator (DFIG) configuration represents variable speed controlled wind turbine with a wound rotor induction generator (WRIG) and partial-scale frequency converters (rated to approx. 30\% of nominal generator power) on the rotor circuit. Stator of the wind turbine generator is directly connected to the grid. Partial-scale frequency converter controls rotor speed. The speed range of the rotor is dictated by power rating of the partial-scale frequency converter. Speed range is typically around $\pm 30\%$ of the synchronous speed. The frequency converters can provide additional support like reactive power compensation.\textsuperscript{15}

2.1.2 FRC based Wind Turbine

In this configuration, full variable speed control of the wind turbine is achieved through full-scale frequency converters. The generator is isolated from the grid through this full-scale frequency converter. The frequency converter provides additional supports like reactive power compensation and a smooth grid connection. FRC based wind turbine can operate in the entire speed range as opposed to limited speed range of DFIG. The generator can either be electrically excited (Wound rotor synchronous generator (WRSG)) or permanent magnet excited type (permanent magnet synchronous generator (PMSG)).\textsuperscript{16} Some FRC based wind turbines may have no gearbox but a bulky direct

\textsuperscript{14} Ibid.
\textsuperscript{15} Ibid.
\textsuperscript{16} Anca D. Hansen et al., Dynamic wind turbine models in power system simulation tool DlgSILENT, technical report (2004).
driven multipole generator.\textsuperscript{17}

\section{2.2 Technical feasibilities}

Installed offshore wind turbines are typically today in the 2-6 MW range, which is a mature and well proven technology today. According to Wind Europe,\textsuperscript{18} the average size of installed offshore wind turbine was 4.2 MW in 2015, a 13% increase over 2014. This was due to the increased deployment of 4-6 MW turbines in 2015.\textsuperscript{19} However, all the major wind turbine suppliers are commercially offering wind turbines in the 6-8 MW range\textsuperscript{20,21} with some of them being able to produce up to 9 MW,\textsuperscript{22} qualifying them as a young technology today, but with clear prospects and development timeline.

In the 10-20 MW range, there are no commercially available wind turbines today. However, research efforts in providing initial designs are being performed, mainly by academia. A 10 MW reference wind turbine design has been developed by Technical University of Denmark (DTU).\textsuperscript{23} In the European project-INNWIND, this design was up-scaled to 20 MW,\textsuperscript{24} however no detailed design data are available yet. This is considered a future technology.

\section{2.3 Stages of Development}

Mature

\section{2.4 Cost and Lifetime}

- Capex: 1500-2500 US$/kW\textsuperscript{25}
- Opex: N/A

\textsuperscript{19} Ibid.
\textsuperscript{21} Mitsubishi Vestas Offshore, \textit{V164-8.0 MW}, \url{http://www.mhivestasoffshore.com/innovations/}.
\textsuperscript{22} Mitsubishi Vestas Offshore, \textit{World’s most powerful wind turbine once again smashes 24 hour power generation record as 9 MW wind turbine is launched}, \url{http://www.mhivestasoffshore.com/new-24-hour-record/}.
\textsuperscript{24} Innovative Wind Conversion Systems (10-20MW) for Offshore Applications, INNWIND Project, \url{www.innwind.eu}.
• lifetime: 20-25 years
3 AC Cables

Most prevalent types of HVAC Cables are Cross-linked polyethylene (XLPE) cables. Another technology, High Temperature Superconducting (HTS) cables is mature but their large application in electricity highways can be limited due to constraints of the cryogenic systems. However, HTS cables can be deployed in specific projects based on economic studies.

3.1 XLPE cables

XLPE cables belong to the class of extruded cables. Extruded cables can generally be categorized into 3 categories:

- EPR - ethylene propylene rubber
- PE - polyethylene
- XLPE - cross-linked polyethylene

Cross-linked polyethylene has good electrical properties such as low dielectric loss factor, which makes it feasible to operate at higher voltage than other kind of material like Poly Vinyl Chloride (PVC) insulated cables. Polyethylene as thermoplastic material is used as cable insulation but with applications limited by thermal constraints.\(^26\) Cross-linking is performed in XLPE through the process known as ‘vulcanization’ or ‘curing’. Chemical additives are added to the polymer in small quantity which enable the molecular chains of the polymer to be cross-linked into a lattice structure.\(^27\)

Example of XLPE cable design is shown in Figure 2. Extruded insulation cables consist of many layers. Surrounding the conductors, there is inner semi-conducting

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27. Ibid.
screen layer, the insulation compound and an outer semi-conducting insulation screen, extruded simultaneously.\textsuperscript{29} A semi-conducting water swelling tape separates the outer semi-conducting screen and the metallic sheath limiting water propagation along the cable core in case of cable damage. A layer of polyethylene compound is extruded over the lead alloy based metallic sheath.\textsuperscript{30}

XLPE cables are used for both HVAC as well as Medium Voltage Alternating Current (MVAC).

### 3.1.1 Technical feasibilities

- **Length:** 20-100 km; However, maximum length depends on voltage rating and amount of shunt compensation.\textsuperscript{31}
- **Maximum Voltage:** 500 kV\textsuperscript{32}
- **Current Rating:** 1.9-2.6 kA\textsuperscript{33}
- **Cross-section:** Example for Prysmian MVAC/HVAC cables is given in Table below:\textsuperscript{34}

<table>
<thead>
<tr>
<th>Rated Voltage (kV)</th>
<th>Cross-section (mm$^2$)</th>
</tr>
</thead>
<tbody>
<tr>
<td>66</td>
<td>240-2000</td>
</tr>
<tr>
<td>110</td>
<td>400-2500</td>
</tr>
<tr>
<td>132</td>
<td>400-2500</td>
</tr>
<tr>
<td>150</td>
<td>400-2500</td>
</tr>
<tr>
<td>220</td>
<td>630-2500</td>
</tr>
<tr>
<td>275</td>
<td>630-2500</td>
</tr>
<tr>
<td>345</td>
<td>800-2500</td>
</tr>
<tr>
<td>400</td>
<td>800-2500</td>
</tr>
<tr>
<td>500</td>
<td>1600-2500</td>
</tr>
</tbody>
</table>

- **Deep Sea Installation:** 400kV subsea cables can be either single core or 3-core. Although, sea depth does not influence maximum transmissible power through the cable, however, cable laying facilities can limit the cable diameter at the deepest water.\textsuperscript{35}

\textsuperscript{29} Soo-Bong Lee et al., “Development of 250kV HVDC XLPE cable system in Korea,” in Electrical Insulating Materials (ISEIM), Proceedings of 2014 International Symposium on (IEEE, 2014), 334–337.


\textsuperscript{31} Grid Innovation Online, Technology Database, http://www.gridinnovation-on-line.eu/Technology-Database.


\textsuperscript{33} Ibid.

\textsuperscript{34} Ibid.

\textsuperscript{35} Grid Innovation Online, Technology Database, http://www.gridinnovation-on-line.eu/Technology-Database.
3.1.2 Stages of Development

Mature

3.1.3 Cost and Lifetime

- **Capex**: 3675-4062 k€/km (installation cost = 29%)
- **Opex**: 7.3-8.1 k€/km (OPEX assumed at a 0.2% p.a.)
- **Lifetime**: N/A

The prices stated for the cables above also include installation costs that vary substantially depending on the area of application. For example, the prices for the XLPE-HVAC cables can be higher than that for the XLPE-HVDC cables. The reason is that the installation costs are included per km. The AC cables are mainly used for the array cabling of the Wind Power Plant (WPP), that means there are a lot of cables with a length of less than 1km. However, every cable needs lifting work and a connection on both ends. Therefore, extrapolating this cost to €/km can make the installation costs very high. Approximate CAPEX based on cable area of cross-section are as follows:

- **95mm²**: 113k€/km
- **150mm²**: 136k€/km
- **240mm²**: 174k€/km
- **400mm²**: 240k€/km
- **630mm²**: 336k€/km

Installation costs are depending on the length and amount of lines of the WPP

3.2 HTS cables

The property of HTS to transmit power without resistance loss allows the utilities to increase power density by 2 to 8 times.

**Benefits of HTS Power Cables**

- Increased current carrying capability
- No resistive electrical losses
- Use of liquid nitrogen as coolant which is environmentally benign
- Can be installed into existing conduit infrastructure

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37. Ibid.
39. Ibid.
• Takes up less space than conventional cables therefore further expansion possible
• Increased power requirements of existing substations can be satisfied
• Can operate at high current levels with much lower losses also requiring less voltage transformations (reduced cost of transformers)

3.2.1 Technical feasibilities

• Length: 3 km; Although, there is no theoretical limitation in length however, actual maximum single length without joint installed is about 600 m. Major economic limitation for mass application of HTS lies mainly in the operation and maintenance of the cryogenic system.\textsuperscript{40}
  • Maximum Voltage: $220 \text{kV}$\textsuperscript{41}
  • Current Rating: 4 kA\textsuperscript{42}

3.2.2 Stages of Development

Mature

3.2.3 Cost

• Capex: N/A
• Opex: N/A
• Lifetime: N/A

Cost in future will depend on the evolution of the market and material properties of HTS in future.

\textsuperscript{40} Grid Innovation Online, \textit{Technology Database}, http://www.gridinnovation-on-line.eu/Technology-Database.
\textsuperscript{41} Ibid.
\textsuperscript{42} Ibid.
4 HVDC Cables

4.1 Description

HVDC transmission technology is mainly applied when either transport of high electrical power over long distances becomes uneconomical for HVAC transmission; power transmission needs to be done with higher controllability and/or to connect two asynchronous networks.

Subsea application of HVDC transmission is predominantly used for connecting offshore wind farms to land or transmitting electricity over long distance through the sea where application of overhead lines may be technically or economically not feasible. However, HVDC cables are beginning to be used also for land transmission projects for transmitting high volume of power. HVDC is a proven technology for transmission projects that interconnect asynchronous networks.43

HVDC underground cables are used to carry medium and high power (100 MW – 1,000 MW) over distances above 50 km. HVDC underground cables have been commercially been used since the 1950s. Two types of HVDC cable technologies are mainly available commercially - Mass Impregnated (MI) Cables and XLPE Cables. Self-contained fluid filled cables are also becoming popular however they are used for very high voltage and short connections due to hydraulic limitations.44

4.1.1 Self-Contained Fluid Filled Cables

Self-Contained Fluid Filled Cables are paper insulated oil filled cables. These kinds of cables are more suitable for HVDC transmission for short distances up to approximately 50 km. The insulation system in these cables need to be constantly under oil pressure. This oil pressure prevents from formation of cavities when oil contracts as the cable cools down. These kind of cables can be used for both AC and DC operations. Examples using low pressure oil filled cables are the interconnections between Saudi Arabia - Egypt (“Aqaba Project”) and the Spain-Morocco project.45

4.1.2 Mass Impregnated Cables

Mass-impregnated subsea HVDC cables do not need oil feeding and therefore, there is no limitation in terms of length. Mass-impregnated cables are composed of a high viscous impregnating material which does not cause any leakage in events of cable damage/failure. Compared to oil filled cables, the compact design of Mass-impregnated subsea HVDC cables also allows for deep water applications. An example using mass-impregnated subsea HVDC cables is the interconnection between Spain - Mallorca.

45. Ibid.
This type of cable is currently one of the most used, however, extruded cables are being used more and more in recent years as can be seen from Figure 3.\textsuperscript{47,48}

Mass impregnated cables has been in service for many years and is a matured technology that can be used for voltages up to ± 500 kV and 1600 A DC which corresponds to a maximum pole rating of 800 MW and bipole rating of 1600 MW. Conductor sizes are typically up to 2500 mm\textsuperscript{2} (at transmission capacity of 2000 MW bipole).

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{figure3.png}
\caption{Evolution of length for mass impregnated paper cables and extruded cables for submarine and underground applications\textsuperscript{49}}
\end{figure}


Further improvement in voltage and capacity can be expected in the near future.\textsuperscript{50}

### 4.1.3 Cross-Linked Poly-Ethylene Cables

Polymeric cables are only used in Voltage Source Converters (VSC) applications that allow reversing power flow without reversing the polarity.\textsuperscript{51} This technology has mainly been applied at voltages up to $\pm 200$ kV (in service with a power capacity of 400 MW). However, recent project such as European TEN-E France - Spain Interconnector (INELFE) has voltage rating of $\pm 320$ kV and power rating of 1000 MW per cable.\textsuperscript{52,53}

### 4.2 Technical feasibilities

- HVDC cables: XLPE
  - Transmission Distance: $>1000$ km\textsuperscript{54}
  - Losses: 27 W/m (21 W/m in future) (Typical losses per circuit (bipole))\textsuperscript{55}
  - Maximum Voltage: 400-525-640 kV\textsuperscript{56,57}
  - Recently 640 kV extruded HVDC cable system has been developed, however, mainly for underground applications.\textsuperscript{58}
  - Current rating: 1900 kA\textsuperscript{59}
  - Max Power per VSC substation (bipole): 1524-1710 MW (1710-1895 MW in future)\textsuperscript{60}
  - Max Power per LCC substation (bipole): 600 MW\textsuperscript{61}

\textsuperscript{54} Grid Innovation Online, Technology Database, http://www.gridinnovation-on-line.eu/Technology-Database.
\textsuperscript{55} Ibid.
\textsuperscript{56} Ibid.
\textsuperscript{57} ABB, The new 525 kV extruded HVDC cable system, 2014, https://library.e.abb.com/public/7caadd11d27d8e5c1257d93b002ff3ee/The%5C%20new%5C%20525%5C%20kV%5C%20extruded%5C%20HVDC%5C%20cable%5C%20system%5C%20White%5C%20PaperFINAL.pdf.
\textsuperscript{59} Grid Innovation Online, Technology Database, http://www.gridinnovation-on-line.eu/Technology-Database.
\textsuperscript{60} Ibid.
\textsuperscript{61} Ibid.
– Cross-section Area: 2500 mm² for voltage rating of 320 kV
– Deep sea installations: 500 m (1000 m in future)

• HVDC cables: MI
  – Losses: 10.4 W/m
  – Maximum Voltage: 600 kV
  – Current rating: 1555 kA (1950 kA in future)
  – Max Power per VSC substation (bipole): 1860 MW
  – Max Power per Line Commutated Converter (LCC) substation (bipole): 1860 MW
  – Cross-section Area: 2000 mm² for 300 kV
  – Deep sea installations: 1600 m (2000 m in future)

Europe’s longest interconnector: NordLink project with VSC converters rated at +/- 525 kV and 1400 MW bipole configuration having route length of 623 km route length is being built.

4.3 Stages of Development
Mature

4.4 Cost and Lifetime
• HVDC cables: XLPE
  – Capex: 1470-1625 k€/km (Installation costs: 29%)72
  – Opex: 2.9-3.2 k€/km (OPEX assumed at a 0.2% p.a.)73

64. Ibid.
65. Ibid.
66. Ibid.
67. Ibid.
68. Ibid.
69. Ibid.
70. Ibid.
72. Ibid.
73. Ibid.
- lifespan: >40 years

• HVDC cables: MI
  - Capex: N/A
  - Opex: N/A
  - lifespan: >40 years

• HVDC cables: Self-Contained Fluid Filled
  - Capex: N/A
  - Opex: N/A
  - lifespan: N/A

Experience of HVDC underground cabling and their cost is currently limited. Based on analysis conducted by Realise Grid in 2010, the cost of HVDC underground cables (two cables, ±350 kV, 1,100 MW) is between 1 - 2.5 million €/km. Some estimations of costs for HVDC cables for different cross-sections can be found in some reports. 

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75. Ibid.
76. EU-FP7 project - REseArch, methoDologies and technologies for the effective development of pan-European key GRID infrastructures to support the achievement of a reliable, competitive and sustainable electrical supply, http://realisegrid.rse-web.it/.
79. REALISEGRID, D3.3.2 Review of costs of transmission infrastructures, including cross border connections, http://realisegrid.rse-web.it/content/files/File/Publications%5C%20and%5C%20results/Deliverable_REALISEGRID_3.3.2.pdf.
5 AC-DC Converters

All the electricity transmission and distribution networks in the world are based on AC systems. In order to transmit power from far off OWPP through HVDC cables, AC power are converted to DC power and vice versa using AC-DC power converters. Power converters currently available on the market can be classified in two major categories in terms of technology: Line Commutated Converters (LCC) and Voltage Source Converter (VSC). Both of these type of technologies can be used in a full HVDC scheme (AC/DC converter - HVDC line or cable - DC/AC converter) or in a back-to-back (B2B) HVDC scheme (AC/DC converter - DC circuit - DC/AC converter, with all these components installed in a single station) or a more recent configuration for multi-terminal HVDC (MTDC) applications.

LCC and VSC have different characteristics and are operated in different manner because of the intrinsic differences of power electronic components. The characteristics of LCC and VSC are compared in Table 2.

5.1 Line Commutated Converters

5.1.1 Description

LCC or CSC are the conventional, mature and well established power converter technology which has been used to convert electrical current from AC to DC and vice versa since early 1950. Such converters require robust AC voltage source at either end. Multi-terminal LCC connections are possible and exist (two schemes exist). However, larger systems with a more complex structure may not be practical configuration mainly due to limitations on controllability of LCC converters.

5.1.2 Technical feasibilities

- Voltage (line to ground) for converter: 800-1100 kV
- Voltage (line to ground) for cables: 550 kV
- Current: 4-5 kA (6 kA in future)
- Max Power per substation (bipole): 8-11 GW (upto 13.2 GW in future)

82. Ibid.
84. Ibid.
85. Ibid.
Table 2: Comparison between LCC and VSC

<table>
<thead>
<tr>
<th>LCC</th>
<th>VSC</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Background</strong></td>
<td><strong>Background</strong></td>
</tr>
<tr>
<td>• Also known as Current Source Converter (CSC)</td>
<td>• Since 1999</td>
</tr>
<tr>
<td>• Since early 1950</td>
<td>• Contrary to CSC, can also be used for connecting isolated networks to the grid, e.g. supply power from generation sources like WPPs or to remote islands.</td>
</tr>
<tr>
<td>• Typically uses thyristors</td>
<td>• Recent technology, compact VSC Multilevel Converters have lower losses</td>
</tr>
<tr>
<td>• Connected by two power networks at either side of link</td>
<td></td>
</tr>
<tr>
<td><strong>Key characteristics of LCC</strong></td>
<td><strong>Key characteristics of VSC</strong></td>
</tr>
<tr>
<td>• More powerful</td>
<td>• Younger technology</td>
</tr>
<tr>
<td>• Low losses</td>
<td>• Able of “black start” (i.e. able to start without additional power at either end)</td>
</tr>
<tr>
<td>• Requires robust networks in operation on both sides and therefore can be preferred technology for interconnections of synchronous networks</td>
<td>• Currently limited in power (in the order of 3000 MW) and voltage (up to ±640 kV)</td>
</tr>
<tr>
<td>• Requires more space than VSC depending on power rating and therefore preferred on land</td>
<td>• More flexible, smaller and lighter and therefore preferable for offshore applications.</td>
</tr>
<tr>
<td>• Induces more severe requirements for cables, therefore cables designed for LCC can also be used for VSC, but not vice versa.</td>
<td>• Allows independent control of active and reactive power.</td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td>• Maximum length of the line: 2000 km(^{87})</td>
<td></td>
</tr>
<tr>
<td>• Maximum length of the cable: 580-600 km(^{88})</td>
<td></td>
</tr>
<tr>
<td>• Transmission Losses: 0.7-1.1% of rated power per converter station.(^{89}) A converter station usually contains converters, capacitors or synchronous condensers for reactive power, filters for harmonic suppression, switch gears, auxiliary equipment and transformers.</td>
<td></td>
</tr>
</tbody>
</table>


\(^{88}\) Ibid.

\(^{89}\) Ibid.
5.1.3 Stages of Development

Mature

5.1.4 Cost and Lifetime

- Capex: 101-112 M€/GW (Installation costs: 37%)\(^90\)
- Opex: 2% of investment costs per year\(^91\)
- lifetime: 40 years\(^92\)

Cost ranges are given per “per terminal” for the typical 1000 MW LCC configuration at 2013.\(^93\)

5.2 Voltage Source Converters

5.2.1 Description

VSC are self-commutated converters using devices suitable for high power and high voltage applications. This technology can rapidly control both active and reactive power independently.\(^94\) It allows higher flexibility and controllability to place converters at different locations in the AC network since no robust AC voltage source is required to be connected at its end. Although there are some technology challenges that still needs to be addressed, such as DC breakers, higher powers, losses reduction etc. for larger deployment in multi-terminal applications.\(^95\)

5.2.2 Technical feasibilities

- Voltage (line to ground) for converter: 500-800 kV (1100 kV in future)\(^96\)
- Voltage (line to ground) for cables: 500 kV\(^97\)
- Current: 1.5-3 kA (3-4 kA in future)\(^98\)
- Max Power per substation (bipole): 2000-4800 MW (6400 MW in future)\(^99\)

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\(^90\) Grid Innovation Online, Technology Database, http://www.gridinnovation-online.eu/Technology-Database.

\(^91\) Ibid.

\(^92\) Ibid.

\(^93\) Ibid.


\(^96\) Grid Innovation Online, Technology Database, http://www.gridinnovation-online.eu/Technology-Database.

\(^97\) Ibid.

\(^98\) Ibid.

\(^99\) Ibid.
• Maximum length of the line: 700-2000 km (3000 km in future)
• Maximum length of the cable: 400 km (600-1000 km in future)
760 km long HVDC interconnector called Viking Link between Denmark and UK is being proposed.

• Transmission Losses: 0.9-1.3% of rated power (0.7-1.1% in future) per converter station. A converter station usually contains converters, capacitors or synchronous condensers for reactive power, filters for harmonic suppression, switch gears, auxiliary equipment and transformers.

5.2.3 Stages of Development
Mature

5.2.4 Cost and Lifetime
• Capex: 106-118 k€/MW (Installation costs: 31%)
• O&M costs: 2% of investment costs per year
• Lifetime: 40 years

Cost ranges are given per “per terminal” for typical configuration of a bipolar VSC terminal of power rating of 1100 MW at 2013. Some estimations of costs for VSC for different power ratings can be found in some reports as well.

5.3 Diode Rectifier Units
5.3.1 Description
The design of diode rectifier unit (DRU) developed from an idea originated at the University of Valencia in Spain, replaces the air-insulated IGBT based traditional converter

105. Ibid.
106. Ibid.
107. Ibid.
108. Ibid.
111. REALISEGRID, D1.3.2 Review of costs of transmission infrastructures, including cross border connections, http://realisegrid.rse-web.it/content/files/File/Publications%5C%20and%5C%20results/Deliverable_REALISEGRID_3.3.2.pdf.
and air-insulated DC switch gear — which requires much space and costly air conditioning with diode rectifiers.

For example, a 0.9GW VSC requires 50,000 cubic metres of space. Whereas, DRU with a 1.2GW rating requires three platforms each with a pair of DRUs converting from 66kV to 106.7kV strung together to add up to 320kV as provided by the VSCs used today. The three platforms have a total volume of just 6,500 cubic metres, or a nearly 90% volume saving on the VSC platform.\textsuperscript{112}

DRU are simple, robust, encapsulated and have low losses & low maintenance costs. However, DRU does not allow bidirectional power flow as compared to VSC technology. Since WT\'s need auxiliary power to maintain systems, mainly grid outage; therefore additional AC cable is needed running parallel to the DC cables from the onshore network.

AC voltage control is performed by the WT\'s

\subsection{5.3.2 Technical feasibilities}

- Nominal power: 200 MW\textsuperscript{113}
- Nominal voltage AC: 66 kV\textsuperscript{114}
- Nominal voltage DC: 106.7 kV\textsuperscript{115}
- Size fits for transport by road and ship\textsuperscript{116}
- Bio degradable and flame retardant ester insulation\textsuperscript{117}

\subsection{5.3.3 Stages of Development}

\textbf{Future}

\subsection{5.3.4 Cost and Lifetime}

- Capex: N/A
- Opex: N/A
- lifetime: N/A

\begin{thebibliography}{99}
\item Sara Knight, \textit{Analysis: Siemens’ radical substation plan}, News Article - WindPower Offshore, 2015, \url{http://www.windpoweroffshore.com/article/1338456/analysis-siemens-radical-substation-plan}.
\item Grid Innovation Online, \textit{Technology Database}, \url{http://www.gridinnovation-online.eu/Technology-Database}.
\item Ibid.
\item Ibid.
\item Ibid.
\item Ibid.
\end{thebibliography}
6 DC-DC Converters

6.1 Description

This would be a device to convert one DC voltage to another DC voltage level and have equivalent function of a transformer in an AC grid. The AC transformer has greatly facilitated AC transmission systems to operate at different voltage levels (110kV, 220kV, 400kV etc.) optimising the AC grid and its components. The DC equivalent can fulfil the same function in future HVDC grid also sometimes referred as Supergrid. Unless the Supergrid is specifically designed to operate at a common DC voltage, DC–DC converters will be essentially required to combine DC networks at different voltage levels.\(^{118,119}\)

There has been some recent standardisation efforts to unify voltage levels and to avoid the need for DC-DC conversion. However, still different voltage levels may appear. For example, several different DC voltage levels are already applied for offshore wind integration in Germany. The fast progress in converter and cable technology also implies that significantly higher voltages can be foreseen in future. Utilising a standard voltage would waste future possible benefits from improved future voltage ratings.

There are generally two possibilities to connect two different DC voltage levels:

- With a DC-DC converter
- Through regular 50 Hz AC with an DC-AC converter and an AC-DC converter\(^{120}\)

A DC-DC converter is likely to be cheaper and more efficient than two separate converters with regular 50Hz AC in between.\(^{121}\) DC-DC converter also has the advantage to regulate the current or power flow through the converter, which helps to operate a meshed DC grid. It could even be applied for this purpose only, connecting two buses of the same voltage level. However, there is other component specialised for this kind of function called DC current flow controller.\(^{122,123}\)

DC-DC converters topologies can be effectively classified into two groups:\(^{124}\)

- Isolated DC-DC Converters
- Non-isolated DC-DC Converters

\(^{120}\) Til Kristian Vrana and Raymundo E Torres Olguin, “Technology perspectives of the North Sea Offshore and storage Network (NSON),” 2015.
\(^{121}\) Ibid.
\(^{122}\) Ibid.
\(^{124}\) Til Kristian Vrana and Raymundo E Torres Olguin, “Technology perspectives of the North Sea Offshore and storage Network (NSON),” 2015.
6.1.1 Isolated DC-DC Converters

In an isolated DC-DC converter, the input and the output port are isolated using galvanic insulation. Isolated DC-DC converter comprises of two AC-DC converters connected to each other by a transformer. Example of possible topology is shown in Figure 4. Main design parameters of an isolated DC-DC converter are switching frequency and AC side frequency. AC side frequency is typically higher than the network nominal frequency (50/60 Hz). Operating in high frequency can allow for significant reduction of the size and volume of the transformers and components like capacitors and inductors. However, a higher frequency leads to increased power losses and complex design of transformer (e.g. amorphous core materials, Litz wires).\(^{125}\)\(^{126}\)\(^{127}\)\(^{128}\)

![Figure 4: Isolated DC-DC converters](image)

Left: Resonant bridge converter; right: Dual active bridge converter\(^{125}\)

Availability of DC-DC converter for high power application as market product is rather limited and studied academically for power ratings spanning from tens of kVs to a few MWs and with an AC operating frequency in the kHz range using several topologies.\(^{129}\)\(^{130}\)\(^{131}\)\(^{132}\)\(^{133}\)

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132. G Ortiz et al., “1 Megawatt, 20 kHz, isolated, bidirectional 12kV to 1.2 kV DC-DC converter for renewable energy applications,” in *Power Electronics Conference (IPEC), 2010 International* (IEEE, 2010), 3212–3219.
6.1.2 Non-Isolated DC-DC Converters

Non-isolated DC-DC converters are structurally simpler, cheaper and smaller than isolated converters.\textsuperscript{134,135} Two topologies are shown as an example in Figure 5. However, these converters are only capable of achieving a limited voltage ratio, which reduces the scope of application for these types of converters.

Figure 5: Non-isolated DC-DC converters\textsuperscript{136} left: Bidirectional high-power DC transformer\textsuperscript{137}; right: Modular multi-level capacitor-clamped DC-DC converter\textsuperscript{138}

Classical DC-DC converter configurations such as buck, boost, cuk are not suitable for high power applications since they require large duty cycles at higher conversion ratio which lead to low efficiency and reliability. There are some proposals in the literature, for example a switched capacitor multilevel DC-DC converter has been proposed by Zhang et. al.\textsuperscript{139} and Vrana et. al.\textsuperscript{140} A main limitation lies in terms of lack of bidirectional power and modularity.\textsuperscript{141,142} Modular multilevel capacitor clamped converters are proposed by Vrana et. al.\textsuperscript{143} and Khan & Tolbert\textsuperscript{144} Although modular multilevel capacitor clamped converter has advantage of modular design, bidirectional and high frequency operation and low current ripple at input and output; but it has major drawback in terms of unequal voltage stress at the switches.\textsuperscript{145,146} Anot-
her interesting topology is soft-switched transformer-less topologies using thyristors. However, expensive large resonant capacitor is needed for this kind of technology.147

6.2 Technical feasibilities
N/A

6.3 Stages of Development
Distant future

6.4 Cost and Lifetime
• Capex: N/A
• Opex: N/A
• lifetime: N/A

7 Filters

Large OWPPs consist many non-linear devices such as power electronic devices in wind turbines, FACTS devices and/or HVDC transmission and other passive components such as cable arrays, transformers, transmission cables etc. Consequently, there are many harmonic generation sources. Bradt et al. summarize the most important issues with respect to harmonics and resonances within wind power plants.

Primarily there are two ways to mitigate harmonics in WPPs: (i) avoiding harmonic resonance and emission by appropriate design (ii) use of harmonic filters. A good design can avoid high levels of harmonic voltages or currents through system layout, component selection and tuning of controller parameters. Both passive and active harmonic filtering can be used for harmonic mitigation. Passive filter technology is the state-of-the-art technology. Passive filter requires extensive system knowledge during the WPP design, which is very complex process since, there are many uncertainties involved in this process.

Although active and hybrid filters have been commonly used for harmonic filtering in many other industrial applications, however they have not been so common practice in WPP applications. Passive filters are more common for WT level and on the system level, e.g. point of common coupling (PCC). A major challenge for passive filter is that resonance can occur due to natural frequency matching with line impedance. Active filters have recently being introduced more and more for WTAs well, with the development of semiconductor devices and improvement of current control strategies.

7.1 Passive Filter

7.1.1 Description

Passive filters consist of a bank of tuned LC filters and/or low-pass/high-pass filter. They have been very popular owing to low initial cost and high efficiency. They have following disadvantages:

• Filtering is strongly dependent on source impedance.

• Harmonic currents on the source side can drastically increase at certain frequencies owing to parallel resonance between source and passive filter.

• Similarly, excessive harmonic currents can flow into the passive filter due to series resonance with source impedance.


7.1.2 Technical feasibilities

- Voltage: 550 kV\textsuperscript{152}
- Power: >3 Mvar\textsuperscript{153}

7.1.3 Stages of Development

Mature

7.1.4 Cost and Lifetime

- Capex: N/A
- Opex: N/A
- lifetime: N/A

7.2 Active Filter

7.2.1 Description

With improvement of technology and reducing costs of semiconductor switching devices such as GTO, thyristors and IGBT, active filters are becoming more practical choice for harmonics mitigation. They consist of voltage-source or current-source PWM inverters and have the ability to overcome the inherent disadvantages in passive filters.\textsuperscript{154,155}

Active dc filter of an HVDC Transmission was first demonstrated by a test installation in 1991 at Lindome station of the Konti-Skan HVDC link. First commercial active dc filter was installed in 1993 at the Skagerrak 3 HVDC Intertie which was followed by Baltic Cable HVDC Link in 1994, Chandrapur-Padghe HVDC Power Transmission in 1998, “Tiang-Guang Long Distance HVDC Project” in 2000 and at the “EGAT-TNB HVDC Interconnection” in 2001.\textsuperscript{156}

Active DC filter is basically a hybrid filter which consists of mainly two parts: a passive part and an active part. The passive part generally comprises of a double tuned passive filter which connects the active part with the DC line.\textsuperscript{157} The active part consists of the following as shown in Figure 6.\textsuperscript{158}

\textsuperscript{153} Ibid.
\textsuperscript{156} Stefan Gunnarsson, Lin Jiang, and Anders Petersson, “Active filters in HVDC transmissions,” in Proceedings of the 40th Session Regular Meeting of the CIGRE Study Committee B4–HVDC and Power Electronics Equipments (2009).
\textsuperscript{157} CIGRE Brochure, Active Filters in HVDC Applications, 2003.
\textsuperscript{158} Ibid.
• Current transducer: The main function of the current transducer is to measure current.

• Control system: The control system circuitry has the main function to control the active DC filter to create virtually a low impedance path between the pole and electrode lines (or ground, depending on the configuration of the system) at the chosen harmonic frequencies.

• Amplifier: To amplify the control signal voltage in the range of 300 to 1000 V.

• Transformer: To increase the amplified voltage further above 3 kV.

• Protection Circuit and arrester: The protection circuit protects the amplifier by limiting the currents and voltages.

• Bypass switch and disconnectors: Bypass switch and disconnectors allows to repair and maintain the active part without taking the HVDC link out of operation.

The active part in the DC filter is defined as the components within the box shown in Figure 6.¹⁵⁹

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7.2.2 Technical feasibilities

- Active DC filter
  - Voltage: 500 kV (Chandrapur-Padghe HVDC power transmission project), 450 kV (Baltic Cable HVDC Link)
  - Filtering frequency range: 350-2500 Hz (Chandrapur-Padghe HVDC power transmission project), 300-3000 Hz (Baltic Cable HVDC Link)

7.2.3 Stages of Development

Mature

7.2.4 Cost and Lifetime

- Capex: N/A
- Opex: N/A
- lifetime: N/A
8 Reactive Compensation

Reactive power compensation in power systems can be categorized either as shunt compensation or series compensation.

8.1 Shunt Compensation

8.1.1 Description

Power transmission capacity can be increased and the voltage profile along the line can be controlled by reactive shunt compensation.\textsuperscript{161} Shunt reactors are applied to minimize line overvoltage due to capacitive effect of the line under light load conditions and shunt capacitors are applied to maintain voltage levels under heavy load conditions by minimizing the inductive effect of the line.\textsuperscript{162}

Static Var Compensator (SVC) and Static Synchronous Compensator (STATCOM) are variable static reactive power (called as var) generators, whose output is varied to maintain the voltage as per the requirement of power systems. A static (var) generator of controlled reactive impedance type is made of thyristor-controlled and switched reactors and capacitors. A synchronous voltage source var Compensator employs a switching power converter, while a hybrid type can employ a combination of these elements. The operating principles of all these var generators are different from each other with varying V-I characteristics, loss vs. var output characteristics, speed of response, attainable frequency bandwidth, etc. However, their functionality is similar in providing the controllable reactive shunt compensation within their linear operating range.

8.1.2 Technical feasibilities

- SVC
  - Voltage (line to ground) for converters: 765 kV (Voltage depending on interfacing power transformers)\textsuperscript{163}
  - Dynamic Reactive power: -300/+600 MVar (Based on need from grid studies)\textsuperscript{164}
  - Current: 4-5 kA per branch\textsuperscript{165}
  - losses per converter station: 1.5-2 % of the rated power\textsuperscript{166}

- STATCOM

\textsuperscript{161} Yong-Hua Song and Allan Johns, \textit{Flexible ac transmission systems (FACTS)}, 30 (IET, 1999).
\textsuperscript{163} Grid Innovation Online, \textit{Technology Database}, http://www.gridinnovation-online.eu/Technology-Database.
\textsuperscript{164} Ibid.
\textsuperscript{165} Ibid.
\textsuperscript{166} Ibid.
– Voltage (line to ground) for converters: 765 kV (Voltage depending on interfacing power transformers)\textsuperscript{167}
– Dynamic Reactive power: -200/+200 MVar (Depending on need from grid studies; can be offset by a combined solution with fixed capacitor banks or thyristor controlled capacitor banks)\textsuperscript{168}
– Current: 2-3 kA per branch\textsuperscript{169}
– losses per converter station: 1.5-2% of the rated power\textsuperscript{170}

8.1.3 Stages of Development
Mature

8.1.4 Cost and Lifetime

\begin{itemize}
  \item SVC
    \begin{itemize}
    \item Capex: 30-50 k€/MVAR (Average investment cost ranges for a SVC at 2013, rating: 100-850 MVAR/MVA; 400 kV)\textsuperscript{171}
    \item Opex: N/A
    \item Lifetime: 40 years\textsuperscript{172}
    \end{itemize}
  \item STATCOM
    \begin{itemize}
    \item Capex: 50-75 k€/MVAR (Average investment cost ranges for a STATCOM at 2013, rating: 100-400 MVAR/MVA; 400 kV)\textsuperscript{173}
    \item Opex: N/A
    \item Lifetime: 40 years\textsuperscript{174}
    \end{itemize}
\end{itemize}

8.2 Series Compensation

8.2.1 Description

The main purpose of shunt compensation as mentioned in the previous subsection is to maintain the desired voltage profile along the transmission line and providing support to the end voltage of radial lines in the face of increasing power demand.\textsuperscript{175} However, shunt compensation is not controllable in order to control the actual transmitted power through a transmission line which is ultimately determined by the series line impedance and the angle between the end voltages of line.\textsuperscript{176}

\textsuperscript{167} Grid Innovation Online, Technology Database, http://www.gridinnovation-on-line.eu/Technology-Database.
\textsuperscript{168} Ibid.
\textsuperscript{169} Ibid.
\textsuperscript{170} Ibid.
\textsuperscript{171} Ibid.
\textsuperscript{172} Ibid.
\textsuperscript{173} Ibid.
\textsuperscript{174} Ibid.
\textsuperscript{175} Narain G Hingorani and Laszlo Gyugyi, Understanding FACTS (IEEE press, 2000).
\textsuperscript{176} Ibid.
Power transmitted over a long transmission line is limited by the series reactive impedance of the line. Series capacitive compensation can be introduced in the line to cancel a portion of the reactive line impedance and thereby increase the transmittable power. Within this functionality, variable series compensation is highly effective in both controlling power flow in the line and in improving grid stability.  

Fixed Series Capacitor and Thyristor Controlled Series Compensation (TCSC) are most commonly used technology for series compensation.

8.2.2 Technical feasibilities

- **Fixed Series Capacitor**
  - Voltage (line to ground) for converters: 765 kV\(^{178}\)
  - Rated Reactive Power: 1350 MVAr\(^{179}\)
  - losses: negligible\(^{180}\)

- **TCSC**
  - System voltage: 400-550 kV\(^{181}\)
  - Rated continuous current: 1500 A\(^{182}\)
  - Rated overall power: 493 Mvar
  - Degree of compensation:
    * Total: 70 %
    * Thyristor controlled: 21 %

8.2.3 Stages of Development

Mature

8.2.4 Cost and Lifetime

- **Fixed Series Capacitor**
  - Capex: 10-20 k€/MVAR (Average investment cost ranges for a FSC at 2013, rating: 100-1000 MVAR/MVA; 400 kV)\(^{183}\)
  - Opex: N/A

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179. Ibid.
180. Ibid.
- Lifetime: 40 years\(^\text{184}\)

- TCSC
  - Capex: N/A
  - Opex: N/A
  - Lifetime: N/A

9 Transformers

9.1 Description

Transformer technology has been invented more than hundred years ago but the basic operating, physical and design principles of transformers are quite the same even today. Although the technology has improved significantly resulting in increased efficiency, higher power rating, reduced weight, decreased dimensions, and reducing costs. Traditionally, the loads are located at farther distance away from the generation plants. Therefore, voltage needs to be increased substantially to transmit large volume of power over long distances.

The main purpose of transformer is to increase the output voltage resulting in reduced losses, increased transmission capacity, reduced copper/aluminium requirements etc. Transformers are very widely used in AC power system and design of transformer depends on application, operating voltage level and rated power. Transformers can be broadly categorized into 2 groups based on their application in power transmission and distribution:

- Power transformer for transmitting power over long distances at high voltages
- Distribution transformer for distributing power to consumers at medium and low voltage levels

Mainly power transformers are considered in this section based on the scope of this catalogue. Depending on applications power transformers can be further categorized into many types such as Generator step-up (GSU) transformer, Step-down transformer, HVDC Converter transformer, Phase shifting transformer (PST), System intertie transformer etc.

Generator step-up (GSU) transformers, as name suggests, are installed in generating substations and used to increase the voltages in order to transmit over long distances. These kind of transformers are generally operated at full load day and night.\(^{185}\) As discussed in previous section that HVDC technology is cost-effective and more efficient to transmit large volume of power over large distances. System intertie transformers are generally equipped with on-load-tap changers (OLTC) and used to reduce the incoming transmission high voltages to medium voltages.\(^ {186}\) HVDC converter transformer connects AC grid and high power converter making the voltage suitable for the converter. It also acts as isolator for the converter from grid faults.\(^ {187, 188}\)

Highest transmission voltage for HVDC has been constantly increasing. For example, ABB has developed Ultra-High Voltage Direct Current converter transformer of


voltage rating of 1100 kV that allows the HVDC to transmit power up to 10000 MW over distances as long as 3000 km.189

9.2 Technical feasibilities

- Voltage (line to ground): 765 kV (Typical up to 400kV. 765kV technically possible.)190
- Current: 10 kA (Not a limiting factor in power systems. Design of short circuit currents up to 40kA available.)191
- Max Power per unit: Technical capability - 1630 MVA192
  Please note that maximum power (or current) is not a limiting factor, rather transport capability of the cable dictates the size of the transformer.
  A typical 765 kV transformers have power rating close to 800 MVA.
- Losses per unit: 0.2-0.4% of rated power193

9.3 Stages of Development

Mature

9.4 Cost and Lifetime

- Capex: 60 M€194
- Opex: N/A
- lifetime: 40 years

191. Ibid.
192. Ibid.
193. Ibid.
10 Offshore Substructures

10.1 Description

Offshore substructures and foundation technology which lies below the water level is chosen based on multiple site conditions and platform properties. The most relevant site conditions are water depth, wave heights/transparency, sensitivity to the soil and water currents. The main relevant platform properties are size and vertical/horizontal weight. Selection is based on structural analysis and cost-benefit analysis.

Although the substructures can be classified based on many criteria, they are classified into six basic types in this report and shown in Figure 7.

- Monopiles
- Tripods
- Tripiles
- Jackets
- Gravity foundations
- Floating foundations

Figure 8 shows the share of substructures for offshore wind farms based on data until end of 2012. It can be seen that monopile substructures constitute most of the proportion. However, monopiles are more favoured technology for shallow water with


typical water depth less than 30 m. As can be seen from Figure 9, all the online wind farms in this considered dataset belongs to offshore locations with water depth less than 30 m. As wind farms are moving far offshore and deeper waters, other technologies such as gravity, jacket and floating foundations are becoming more relevant.

Figure 8: Share of substructures for online offshore wind farms based on data until end of 2012

Figure 9: Water depth vs. distance to shore for offshore wind farms based on data until end of 2012

10.1.1 Monopile Substructures

Monopile substructures comprise for most of all substructures of the European operating wind farms. The monopile needs to be drilled down into the seabed. Monopiles are easy to install in shallow to medium water depths. This type of structure is well suited for sites with water depth ranging from 0-35m. Advantages of monopile foundation lies in its simplicity, light weight and versatility. However, it can be expensive for large size installations such as for converter substation platform. Decisions on monopiles should be made on cost-benefit analysis. This type of installation is also difficult to remove. Recently, monopiles with bigger diameter called XXL monopiles are being considered as viable alternative to jacket substructures for deeper water installations. World’s heaviest monopile of 7.8 m of diameter and weight of 1302.5 t is used in Veja Mate offshore wind farm. Research is even ongoing for applying monopile technology to as deep as 50 m.

10.1.2 Tripod Substructures

The tripod structure is standard lightweight three-legged structure made of cylindrical steel tubes. It consists of a central steel column between the turbine and a steel frame. This central shaft transfers the forces from the tower into three vertical or inclined steel piles. These piles are driven 10-20m into the seabed. In order to make it suitable for actual environmental and soil conditions, base width and pile penetration depth of this substructure can be adjusted. This type of structure is generally suitable for water depth of 20-50 m. This type of substructure has good stability and overall stiffness. This type of structure are suitable for most conditions but deep soft material. It is quite rigid and versatile. However, this type of construction and installation are

expensive and difficult to remove.\textsuperscript{212}

10.1.3 Tripile Substructures

The tripile structure is also called jacket-monopile hybrid structure. As name suggests, this kind of structure has a three-legged jacket structure in the lower section which is then connected to a monopile in the upper part of the water column (made of cylindrical steel tubes). In order to make it suitable for actual soil conditions, base width and pile penetration depth of the tripile substructures can be adjusted. This type of structure is generally suitable for water depth of 20-50 m.\textsuperscript{213, 214}

This type of technology has been used at BARD Offshore 1 wind farm.\textsuperscript{215}

10.1.4 Jacket Substructures

Jacket substructures are made of a truss frame which consists of many tubular members welded together. In order to secure the structure from lateral forces, piling is driven through each leg of the jacket into the seabed (or through skirt piles at the bottom of the foundation).\textsuperscript{216}

Jacket foundations have been applied to wind turbines in the Alpha Ventus offshore wind farm and for converter platform in 400 MW BorWin1 converter which weighs 3200 tons.

10.1.5 Gravity substructures

Gravity based structures are made of concrete structures (often filled with gravel, sand, iron ore and/or stones to increase weight and stability) which can be constructed with or without small steel or concrete skirts. This type of structure uses its weight to resist wind and wave loading. In order to make it suitable for actual soil conditions, base width can be adjusted.\textsuperscript{217}

Concrete gravity based structures are virtually suitable for all soil conditions. It has advantage of allowing float-out installation. It can be expensive because of weight.\textsuperscript{218}

Steel gravity based structures are virtually suitable for all soil conditions but preferable for deeper water than concrete based. It has advantage of being lighter than concrete based which also allows easier transportation and installation. However, it

\textsuperscript{215} Ibid.
can be expensive in an erosion prone region mainly because of additional requirement of cathodic protection system.\(^{219}\)

### 10.1.6 Floating Substructures

Since the cost of all bottom-fixed foundations increases more than linear with water depth, floating foundation can be a better choice than bottom-fixed foundations at deep waters.\(^{220}\) The break-even-point of water depth is unclear yet, mostly due to limited experience with floating foundations. It has some degrees of freedom for movement, but it is held in place by an anchoring system.

When considering floating foundations for electrical installations, one important restriction has to be regarded: Floating electrical installations usually cannot be connected to MI-type power cables, as those are not flexible enough to cope with the movements of floating structures.\(^{221}\)

It has the advantage of inexpensive foundation construction. Further, the structure being non-rigid, it is susceptible to lower wave loads. However, disadvantage of this type of foundation lies in higher mooring and platform cost. Also, this kind of foundation excludes fishing and navigation from areas of wind farm.\(^{222}\)

### 10.2 Technical feasibilities

- **Monopile Foundation**
  - Sea Depth : 0 - 30 m.\(^ {223}\) Mega(XXL) monopiles: upto 45-50 m\(^ {224}\)

- **Tripod Foundations**
  - Sea Depth : > 6-7 m\(^ {225}\) (Typically 20-50 m)

- **Tripile Foundations**
  - Sea Depth : 25-40 m\(^ {226}\)

- **Jacket Foundation**


\(^{220}\) Til Kristian Vrana and Raymundo E Torres Olguin, “Technology perspectives of the North Sea Offshore and storage Network (NSON),” 2015.

\(^{221}\) Ibid.


– Sea Depth: 20–50 m

- Gravity Foundation
  – Sea Depth: 0–25 m

- Floating Foundation
  – Sea Depth: <40 m

### 10.3 Stages of Development

- Monopile Foundation
  Mature

- Tripod Foundation
  Mature

- Tripile Foundation
  Mature

- Jacket Foundation
  Mature

- Gravity Foundation
  Mature

- Floating Foundation
  Young/Shortly Coming

A pilot turbine called Hywind was placed in waters off Norway in 2009. The foundation consists of an 8.3 m diameter, 100 m long submerged cylinder secured to the seabed by three mooring cables. Another pilot project in the wind industry is Blue H which consists of a two blade turbine placed on top of a buoyant, semi-submerged steel structure attached to a counterweight on the seabed.

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228. Ibid.
229. Ibid.
10.4 Cost and Lifetime

• Wind Turbine Platform
  
  – Capex: Cost depends on water depth, environment and soil condition. Figure 10 shows Monopiles and Jacket foundation costs expressed for different water depths.

![Figure 10: Monopile and jacket foundation costs for an 8 MW Wind Turbine](image)

• Converter Platform
  
  – Capex: N/A
  – Opex: N/A
  – lifetime: N/A

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11 Protection Equipment

11.1 AC Circuit Breaker

11.1.1 Description

Circuit breakers are the central part of air-insulated (AIS) and gas-insulated (GIS) switchgear which are used to disconnect feeders when faults are detected. High-voltage circuit breakers are mechanical switching devices which carry the nominal current in closed position and break current circuits (operating currents and fault currents).232

High-voltage breakers can be categorized based on the medium used to extinguish the arc as follows:

- Bulk oil
- Minimum oil
- Air blast
- Vacuum
- SF6
- CO2

Due to environmental and cost concerns over insulating oil spills, SF6 based circuit breakers are mostly used in recent times.233 High-voltage AC circuit breakers are routinely available with ratings up to 765 kV.234 1200 kV breakers were launched by Siemens in November 2011, followed by ABB in April the following year.

11.1.2 Technical feasibilities

- Voltage (line to ground): upto 800kV (Typical up to 400kV. 800kV technically possible.)235
- Current: 80 kA236
- Reliability (per unit): >99.9%237
- Losses per unit: ≈ 0238

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236. Ibid.
237. Ibid.
238. Ibid.
11.1.3 Stages of Development

Mature

11.1.4 Cost and Lifetime

- Capex: N/A
- Opex: N/A
- lifetime: 8000-10000 operations per unit

11.2 DC Circuit Breaker

11.2.1 Description

In future HVDC grids, DC breakers will be needed to isolate faulty parts of the grid during earth faults whereas, other kinds of faults can be handled by converters or slower DC switches depending on the fault. Generally, DC breakers require to quench fault currents with very fast rising times since DC circuits operate without a natural zero crossing current as compared to AC circuits.

Electronic breakers are capable of operating very fast but have relatively high on-state losses. While a hybrid DC breaker has a mechanical bypass path to reduce the losses to near zero (60 kW at 320 kV DC) while maintaining clearance time.\textsuperscript{239}

Power electronic based DC breakers consists of only semiconductor-based switches. When switches are turned off to break the current, the magnetic energy stored in inductance within the circuit, oppose sudden change in current, resulting in commutating the current into a means of energy dissipation.\textsuperscript{240}

The advantages of power electronic HVDC circuit breakers are as follows:\textsuperscript{241}

- Fast operation
- Low maintenance due to absence of moving parts
- Modular design
- Increased redundancy
- Almost no limitation on number of operations
- Fast reclose
- Requirement for series inductance can be reduced due to faster response
- Lower current turn-off capability required for semiconductor switches


\textsuperscript{240} CIGRE Brochure, Technical Requirements and specifications of state-of-the-art HVDC switching equipment, 2017.

\textsuperscript{241} Ibid.
The disadvantages of power electronic HVDC circuit breakers are as follows: 242

• High on-state losses
• Sensitivity of semiconductor devices
• Minimal overcurrent and overvoltage capacity
• No galvanic isolation (without additional equipment)
• Cooling requirements
• Expensive

The hybrid DC circuit breaker is a combination of mechanical and power electronic switches. Hybrid DC circuit breaker has superior steady state and dynamic performance than power electronic DC circuit breaker. The advantages of hybrid HVDC circuit breakers are as follows: 243

• Low conduction losses
• Can withstand very high currents in closed position
• Very low leakage current and can withstand high-voltage in open position

The disadvantages of hybrid HVDC circuit breakers are as follows: 244

• Slower operation than power electronic circuit breaker
• Mechanical wear and maintenance required because of moving mechanical parts

11.2.2 Technical feasibilities

N/A

11.2.3 Stages of Development

Future

Although manufacturers like ABB and Siemens have developed and tested DC circuit breakers for HVDC applications, however there has not been any practical implementation of these technologies. 245, 246

243. Ibid.
244. Ibid.
11.2.4 Cost and Lifetime

- **Capex:** N/A
  
  Since there is no practical implementation till date, it is hard to estimate/assume cost of DC breakers, but it can be expected to be in the range of tens of million euros.

- **Opex:** N/A

- **lifetime:** N/A

11.3 Fault Current Limiter

11.3.1 Description

Fault current limiters (FCL) as name suggests, are devices used to limit the fault current to acceptable levels. These devices are generally applied in AC systems, but some concepts can also be used for DC systems. For AC systems, there are two general types of FCLs- Resistance based or Reactance based.

The reactance based concept cannot directly be used in DC systems while resistance based concept is similar for DC and AC systems. Generally, non-linear properties are desired for FCLs, in order to have more impact on fault-operation as compared to normal operation. However, linear components can also be used for limiting the fault current.

Different types of FCL are as follows:

- Inductors
- Polymeric Positive Temperature Coefficient Resistor-based FCL
- Liquid Metal FCL
- Superconductive FCL

11.3.2 Technical feasibilities

- 10 MVA Key Parameters
  - Line Voltage : 11kV, 50Hz, 3-ph
  - Nominal load current (power through) : 525 A rms (10MVA)
  - Prospective fault current : 5.34kA rms, 13.6kA peak
  - Limited fault current 2.22kA rms, 9.13kA peak

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248. Ibid.
249. Ibid.
– Fault current reduction (clipping) : 58% of steady state rms (33% of first peak)
– Tested fault withstand duration : 3 seconds
– Recovery from fault to normal load : Instantaneous (less than 1msec)
– CB reclosing : Fully tested w/ 500 msec dead zone between faults
– Voltage drop during normal operation : 0.8-2%
– Power frequency voltage withstand : 28kV
– Lightning impulse withstand : 75kV

11.3.3 Stages of Development
Mature

11.3.4 Cost and Lifetime

• Capex: N/A
• Opex: N/A
• lifetime: N/A
12 Auxiliary Equipment

12.1 Tapping equipment

12.1.1 Description

Tapping converter is connected to a point to point connection somewhere along the line or cable and used as ‘tap’ to supply a small load that is typically an auxiliary equipment required for operation of the system. It has much lower power rating compared to the main power rating of the HVDC scheme which it is connected to.\textsuperscript{251}

12.1.2 Technical feasibilities

N/A

12.1.3 Stages of Development

Distant future

12.1.4 Cost and Lifetime

- Capex: N/A
- Opex: N/A
- lifetime: N/A

12.2 Supervisory, control and data acquisition (SCADA)

12.2.1 Description

A vital element of the wind farm is the SCADA system. This system acts as a ‘nerve centre’ for the project by connecting the individual turbines, the substation and meteorological stations to a central computer for monitoring and control. The SCADA computer communicates with the turbines via optical fibre based communications network. It allows the operator to supervise the behaviour of all the wind turbines and also the wind farm as a whole. It also records energy output, availability and error signals, which can help in planning, maintenance, warranty calculations etc.\textsuperscript{252} SCADA also allows to operate the wind farm in different operational modes based on network requirements such as frequency control, voltage control, power curtailment, reactive power support etc.


\textsuperscript{252} European Wind Energy Association et al., *Wind energy—the facts: a guide to the technology, economics and future of wind power* (Routledge, 2012).
12.2.2 Technical feasibilities
Compliance with IEC 61400-25 standard for wind turbines

12.2.3 Stages of Development
Mature

12.2.4 Cost and Lifetime
• Capex: N/A
• Opex: N/A
• lifetime: N/A
13 Summary

The main components needed for the development of an offshore grid are available today. The main uncertainty, in terms of components, is the availability, cost and technical maturity of the DC breakers, which are needed in the case of a meshed grid design. However, there are ways around it, mainly by using a modular grid design, where each sub-grid is below the N-1 single outage contingency limit in the different synchronous areas. Nevertheless, at this point it is rather safe to assume that full scale DC breakers will be tested and operated by a time horizon of 2030.

- Table 3 summarizes the stages of development for all the technologies.
- Table 4 summarizes the costs and lifetime for all the technologies.

Table 3: Stages of development for different components

<table>
<thead>
<tr>
<th>Components</th>
<th>Mature</th>
<th>Young</th>
<th>Future</th>
<th>Distant-Future</th>
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<td>VSC converters</td>
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<td>DRU converters</td>
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<td>SCADA</td>
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Table 4: Costs and lifetime for different components

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<th>OPEX</th>
<th>Lifetime</th>
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<td>XLPE-HVAC Cables</td>
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<td>7.3-8.1 k€/km</td>
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<td>N/A</td>
</tr>
<tr>
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<td>1470-1625 k€/km</td>
<td>2.9-3.2 k€/km</td>
<td>&gt;40 yrs</td>
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<td>MI-HVDC Cables</td>
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<td>N/A</td>
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<td>SFF-HVDC Cables</td>
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<td>LCC converters</td>
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<td>40 yrs</td>
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<tr>
<td>VSC converters</td>
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<td>DRU converters</td>
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Appendices

A HVDC Converter Station Configuration

There are three basic configurations of VSC based HVDC Converter Station in a HVDC grid.

• Asymmetrical monopole configuration:

![Figure 11: Asymmetrical monopolar configuration](image)

This configuration as shown in Figure 11 has only one high voltage conductor (overhead line or cable) and one grounded neutral conductor. The neutral conductor acting as metallic return, although is fully rated for the load current but only lightly insulated which makes it cheaper and more reliable. A major disadvantage of this converter is that if any of the major component of the converter is lost, either due to a fault or during maintenance, complete disruption of power transfer through this converter is needed.

• Symmetrical monopole configuration

![Figure 12: Symmetrical monopolar configuration](image)

Figure 12 shows the configuration of a symmetrical monopole. As opposing to the asymmetrical monopole, the AC connection is made to the midpoint of the VSC converter. This type of configuration requires two fully rated high-voltage conductors. Two DC terminals are connected to the positive and negative pole of the converters operating at equal and opposite DC voltage. A major disadvantage of this configuration is that if any of the major component of the configuration is lost, either due to a fault or during maintenance, complete disruption of power transfer through this converter is needed. Symmetrical monopoles have been widely used configuration.257

- Bipolar configuration

![Bipolar configuration](image)

Figure 13: Bipolar configuration258

Figure 13 shows schematic diagram of bipolar configuration. In this configuration, two asymmetrical monopoles are connected through ground connected poles which can be connected using a neutral conductor. The advantage of this configuration is that in case of loss of any major element of the configuration, only 50% of the transmission capacity is lost.259

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