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1 Assessing seabird bycatch in gillnet fisheries using electronic monitoring

2
3 Gildas Glemarec, Lotte Kindt-Larsen, Louise Scherffenberg Lundgaard, Finn Larsen
4

5 Abstract

6 The unintentional capture (bycatch) of seabirds in gillnet fisheries kills hundreds of thousands of
7 individuals annually and is thought to threaten the conservation of entire populations. However,
8 data from commercial fisheries is often lacking to confirm these suspicions. In Denmark, sparse or
9 incomplete catch data from small-scale gillnetters prevent managers from gaining a comprehensive
10 overview of the importance of seabird bycatch in coastal waters. In this study, electronic monitoring
11 (EM) with video is used to identify and quantify seabird bycatch in a Danish coastal gillnet fishery.
12 Three gillnetters were monitored over a period of 9 years, resulting in 2118 fishing trips and 10,964
13 hauls; 700 birds from six families were identified. Three species composed $\geq 90\%$ of the incidental
14 captures, the common eider (*Somateria mollissima*), the great cormorant (*Phalacrocorax carbo*) and
15 the common guillemot (*Uria aalge*), respectively qualifying regionally as endangered, least
16 concerned and near threatened. There was a clear species-specific spatial and seasonal variability in
17 bycatch per unit effort (BPUE) estimates, highlighting areas of high risk of seabird bycatch.
18 Approximately 40% of all bycatch events were observed in 0.2% of the hauls, suggesting that the full
19 fishing activity should be analysed to obtain accurate seabird bycatch estimates.
20

21 **Keywords:** Electronic monitoring, Seabirds, Bycatch, Gillnets, Fisheries interaction
22

23 **Running head:** Electronic monitoring of seabird bycatch
24

25 1. Introduction

26 Unintentional captures in fishing gears (or bycatch) are a major cause of mortality for air-breathing
27 marine animals like seabirds, sea turtles, or cetaceans (Tasker et al., 2000; Lewison et al., 2014;
28 Northridge et al., 2017). In particular, entanglement in gillnets is responsible for the drowning of
29 hundreds of thousands of seabirds each year (Žydelis et al., 2013), and has been identified as a major
30 threat for some vulnerable populations (Žydelis et al., 2009; Croxall et al., 2012; Dias et al., 2019). In
31 the European Union, despite the commitments of the Member States to protect and conserve
32 avifauna (EU, 2009), and although a strong legislative body is in place to guarantee no or minimal
33 bycatch of sensitive species (through the Common Fisheries Policy and the Marine Strategy
34 Framework Directive notably), seabird bycatch remains an unresolved problem. In 2012, the
35 European Commission established an “Action Plan for reducing incidental catches of seabirds in
36 fishing gears” (EC, 2012), calling upon Member States to estimate the impact of their national
37 fisheries on seabirds, and to come up with effective methods to reduce or suppress incidental
38 catches. However, in most European countries, bycatch data collection relies upon non-dedicated
39 programmes conducted under the Data Collection Framework (DCF). Only few dedicated bycatch
40 sampling programmes exist, usually limited in time and space (ICES, 2018), with the noteworthy
41 exception of the long-term protected species bycatch monitoring programme (PSBMP) in the United
42 Kingdom.

43 Gillnets, a common type of fishing gear consisting of vertical walls of nettings invisible to fish, are
44 considered the most deadly gear for seabirds (Dias et al., 2019). Bycatch of seabirds in gillnet

45 fisheries alone is estimated to kill ca. 400,000 birds globally each year, with at least 76,000 in the
46 Baltic Sea (Žydelis et al., 2013). Detailed registrations of incidental catches over extended periods are
47 crucial to understand what influences seabird bycatch in time and space, and ultimately how to
48 remedy it (Northridge et al., 2017). Accordingly, recording bycatch of protected species is now a
49 requirement for all EU fisheries (EC, 2016). Yet, reliable data is frequently limited for small-scale and
50 artisanal fisheries (Pott and Wiedenfeld, 2017; ICES, 2018). Worldwide, long-term data series on
51 bycatch remain the exception, and in most regions incidental catches of birds are only sporadically
52 monitored, e.g. through independent on-board observer programmes (Le Bot et al., 2018).

53 Gillnet fishing fleets often consist of numerous small-scale vessels. In high-waged countries with like
54 Denmark, a regular on-board observer monitoring scheme can rapidly become prohibitively
55 expensive (Kindt-Larsen et al., 2011). Danish commercial gillnetters are mostly vessels below 15 m in
56 length, and the national on-board observer programme supervised by the National Institute of
57 Aquatic Resources (DTU Aqua) covers only about 0.1% of the whole fleet (Anonymous 2019). In
58 these conditions, catches of seabirds, rare by nature, are likely to remain undetected. In Denmark,
59 bird bycatches must be reported in fishing logbooks (EC, 2016). However, in small-scale fisheries
60 where no constraining enforcement or verification protocol is in place, self-reported bycatch raises
61 concerns of reliability (Mangi et al., 2015). Indirect observations, e.g. carcass collections and
62 interviews with fishers, can complete the overall picture locally, but also commonly lead to
63 underreporting (see e.g. Bellebaum et al., 2013). Therefore, the characteristics and the magnitude of
64 seabird bycatch in the Danish gillnet fishery are essentially unknown.

65 Deploying electronic monitoring (EM) systems on fishing vessels offers an alternative to on-board
66 observers, while reducing overall costs (Mangi et al., 2015; Plet-Hansen et al., 2019). EM systems
67 consist of a set of closed-circuit television (CCTV) cameras, gear and position sensors (GPS), and a
68 dedicated computer permanently installed on-board a fishing vessel. The fishing activity is recorded
69 and stored, either locally on a hard drive, or on a dedicated storage server. These data are then
70 readily accessible for researchers to analyse the characteristics of the fishing activity, including
71 distribution of the fishing effort and catch composition. DTU Aqua first started using EM systems in
72 2008 on commercial trawlers, seiners and gillnetters around Denmark, originally as a means to
73 evaluate discards in these fisheries (Dalskov and Kindt-Larsen, 2009). Rapidly, EM became a tool to
74 assess the effects of the implementation of the European catch quota management system (Kindt-
75 Larsen et al., 2011; 2012a; Plet-Hansen et al., 2019), and later still, to study incidental catches of
76 marine mammals in the Danish gillnet fisheries (Kindt-Larsen et al., 2012b; 2016). Unlike on-board
77 observers, EM systems are able to follow a fishing vessel all-year long and can potentially record
78 every catch provided that no technical failure occurs and that the system is not tampered with.
79 Using EM, discreet and rare fishing events, such as seabird bycatch, can thus be registered and
80 accounted for.

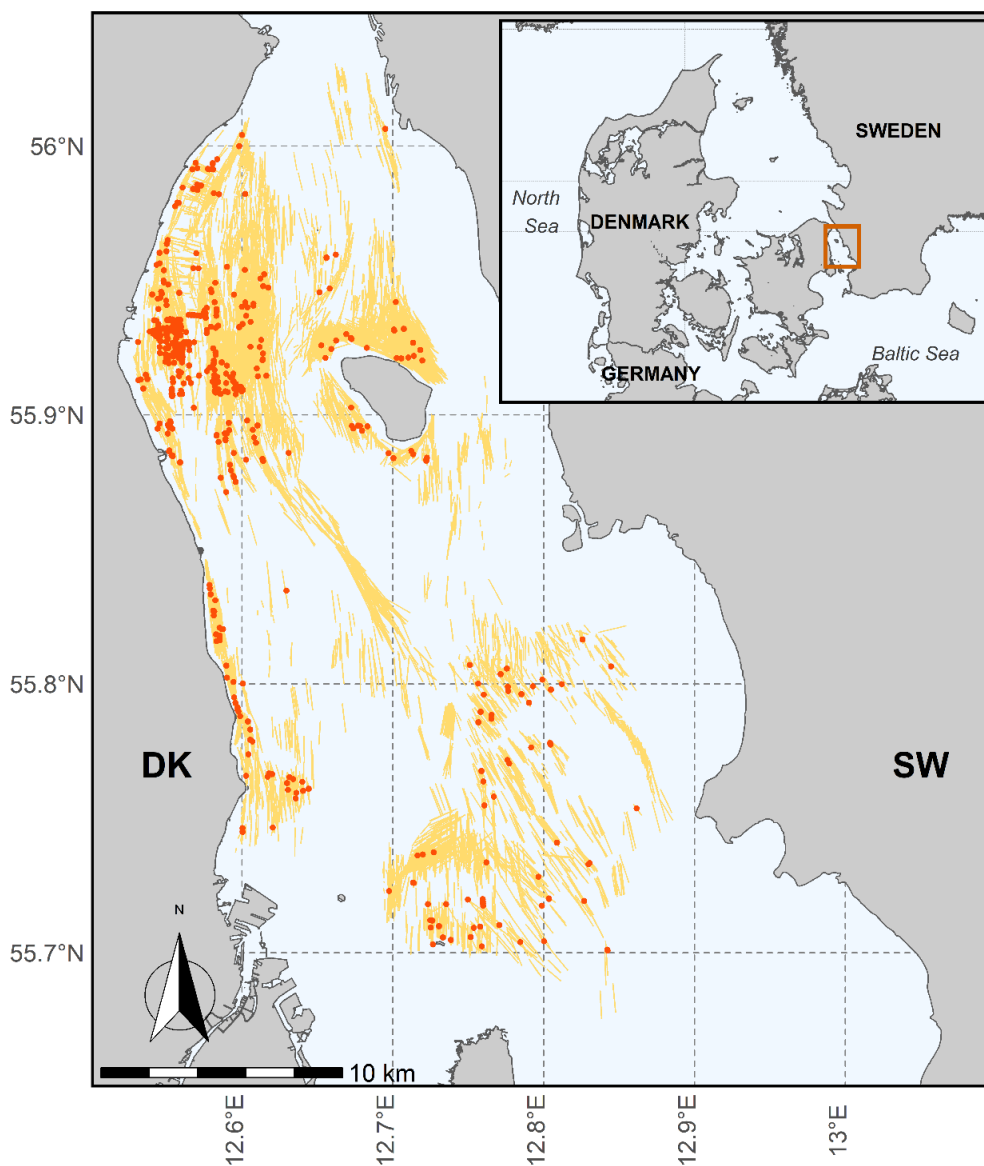
81 In the present study, three commercial gillnet vessels operating on the East coast of Denmark were
82 equipped with an electronic monitoring system with CCTV. We recorded the entire fishing activity,
83 including the bycatch of seabirds. Using data spanning from 2010 to 2018, we examined the fine-
84 scale spatio-temporal variations of the fishing activity, and we estimated the variations of seabird
85 bycatch rates in the study area. Based on these observations, we discuss the ability of EM
86 technologies with CCTV to provide precise information on incidental catches of seabirds in a small-
87 scale gillnet fishery. Such data are valuable both in a fisheries management and in a conservation
88 context, as this issue is often largely ignored in small-scale fisheries. Specifically, we show that EM
89 technologies with CCTV can be used to record incidental catches of seabirds accurately in a
90 commercial gillnet fishery. Then, we describe the seasonal variations of bycatch rates per species in
91 the study area. Finally, we identify the benefits and weaknesses of using EM for collecting seabird
92 bycatch data.

93

94 2. Material and methods

95 2.1. Study area and sampled fishing vessels

96 The data collection was conducted using EM systems on-board three anonymised Danish
97 commercial gillnetters. The periods during which EM was active differed between vessels: vessel 1
98 was sampled from May 2010 to June 2016, vessel 2 from March 2016 to December 2018, and
99 vessel 3 from May 2010 to April 2014 and from March 2016 to December 2018. The vessels operated
100 in the Sound (Figure 1), an important fishing ground for small-scale gillnetters below 15 m, situated
101 on the Eastern coast of Denmark. Skippers went out for daily coastal trips of a few hours, targeting
102 mostly cod (*Gadus morhua*) and European plaice (*Pleuronectes platessa*) year long, with seasonal
103 shift to lumpsucker (*Cyclopterus lumpus*) between end of January and end of April. Other valuable
104 species included Atlantic salmon (*Salmo salar*), turbot (*Scophthalmus maximus*) and Atlantic
105 mackerel (*Scomber scombrus*).



106
107 **Figure 1: Study area, positions of the hauls (in yellow), and positions of seabird bycatch events (in orange) observed on**
108 **three gillnetters using electronic monitoring for the period 2010-2018.**

109

110 The sampled vessels' overall length varied between 9.63 m and 11.05 m, for a gross tonnage (GT) of
111 5.8 GT to 10.7 GT and an engine power of 74 kW to 107 kW. For these small-scale gillnetters, the
112 duration of a fishing trip never exceeded 9 h. All three vessels used traditional monofilament
113 bottom-set gillnets – or rarely trammel nets – with mesh sizes between 120 mm to 250 mm. Vessels
114 typically set 5 net fleets per fishing trip (median: 5, mean: 5.2, sd: 1.9), with a net length spanning
115 between 200 m and 5500 m (median: 731 m, mean: 790 m, sd: 324 m). Most fishing trips consisted
116 of hauling the net fleets set the previous day, but the soak time could be considerably longer when
117 the target species was lumpsucker (median soak time: 13.8 h, mean: 40.8 h, sd: 43.7 h). Fishing
118 depth varied considerably between vessels and within vessels along the year. Vessel 1 generally set
119 net fleets in deeper waters (median: 15.0 m, mean: 16.9 m, sd: 10.3 m), than the two others
120 (respectively, median: 7 m and 14 m, mean: 8.0 m and 13.0 m, sd: 3.4 m and 3.8 m). On occasions,
121 other gears (e.g. pots, fyke nets) were used and the corresponding trips were excluded. One vessel
122 was one-man crewed (vessel 2), while the two others were operating with either one or two
123 crewmembers on deck.

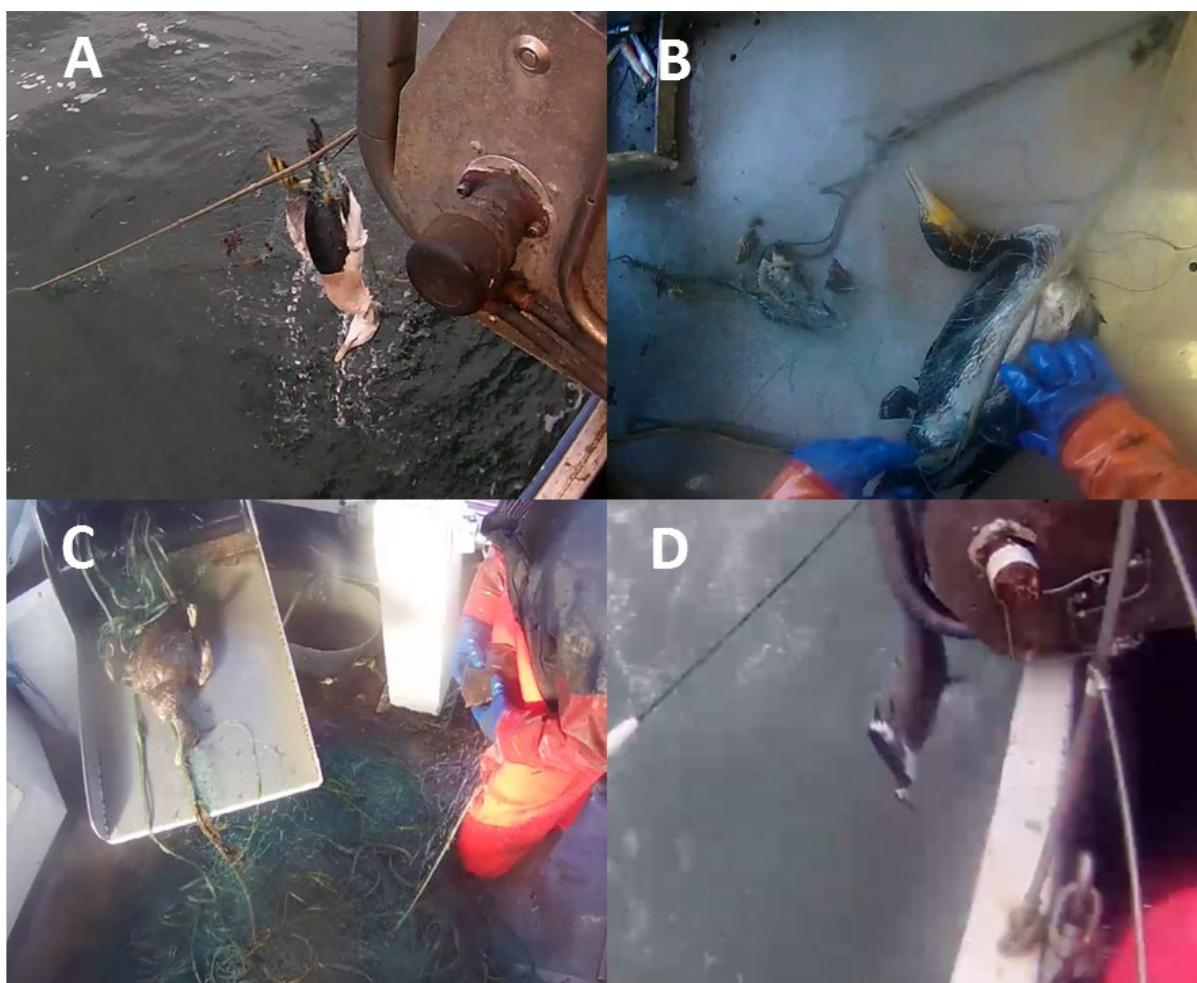
124 2.2. EM systems

125 Two different EM systems were used to monitor the fishing activity. Originally, two vessels were
126 equipped with EM Observe, a solution developed by Archipelago Marine Research Ltd, Canada
127 (<http://www.archipelago.ca>). Later, these systems were replaced with Black Box Video, developed
128 by Anchorlab, Denmark (<http://www.anchorlab.dk/>). The third vessel was also equipped with this
129 system. Both hardware solutions worked on the same general principle: a control box installed in the
130 wheelhouse, associated with 2 to 4 waterproof rugged closed-circuit television (CCTV) cameras
131 recording the activity on deck from different angles, and linked to a position sensor (GPS receiver). A
132 monitor plugged onto the control box allowed checking the camera recordings and the system
133 status. The videos were stored on-board on high-capacity hard drives. For the EM Observe system,
134 once the storage capacity was below 25%, a DTU Aqua staff manually replaced the hard drive with a
135 new one in the control box. The full hard drives were retrieved or sent by mail to DTU Aqua. For the
136 Black Box Video system, data were uploaded to a dedicated server automatically every time the
137 vessel was in an area covered with Wi-Fi or GSM/3G/4G mobile network (e.g. the harbour).

138 On each vessel, one camera was oriented to observe the net breaking the water surface during the
139 hauling phase, while another camera was placed above the sorting table to monitor catch
140 composition and discard. On one vessel, two additional cameras were installed to record the activity
141 on the deck (Figure 2). All cameras were fixed on existing structures whenever possible, but
142 sometimes the addition of a mounting rack was required to obtain the desired field of view.

143 The quality of the digital recordings varied considerably between the two EM systems (Table 1). In
144 particular, because it was necessary to replace the full hard drives manually on EM Observe, the
145 number of frames per second (fps) and the resolution of the picture were reduced in order to extend
146 the recording time. Conversely, Black Box Video was transmitting data directly over the air, so
147 internal storage capacity was not an issue, and picture quality was thus increased to the maximum.
148 In these conditions, Black Box Video was generally much better at picking up small details in the
149 picture than EM Observe was.

150



151

152 **Figure 2: Examples of bird bycatch in Black Box Analyzer [A: common eider (*Somateria mollissima*) adult male; B: great**
 153 **cormorant (*Phalacrocorax carbo*) immature; C: common eider adult female], and in EMI Observe [D: common guillemot**
 154 **(*Uria aalge*)].**

155 **Table 1: Comparison between the electronic monitoring systems**

	EM Observe		Black Box Video		
Company	Archipelago Marine Research Ltd		Anchor Lab		
Vessel	vessel 1	vessel 3	vessel 1	vessel 2	vessel 3
Monitoring period	May 2010 to November 2013	March 2011 to April 2014	December 2013 to September 2016	March 2016 to December 2018	March 2016 to December 2018
Temporal resolution	1 GPS position recorded every 10 seconds		1 GPS position recorded every 10 seconds		
Lenses	2.6 to 8 mm	2.6 to 8 mm	2.6 to 8 mm	2.6 to 8 mm	2.6 to 8 mm
Frames per second (overview)	2 fps	2 fps	5 fps	5 fps	5 fps
Frames per second (haul & catch)	6 to 9 fps	6 to 9 fps	5 fps	5 fps	5 fps
Camera resolution	640 x 480	640 x 480	1280 x 800 to 1360 x 768	1360 x 768	1360 x 768
Dedicated software for data analysis	EM Interpret (Europe release, Version 11.3.11189)		Black Box Analyzer (Version 4.0.3.0)		

156 2.3.Video analysis: identifying fishing activity and bycatch events

157 Analyses of the temporal and spatial characteristics of the fishing trips were done using an electronic
158 monitoring analyser software (EM analyser). Each EM system came with its own dedicated EM
159 analyser (Table 1). Simply put, the recordings made on-board the fishing vessels were stored in a
160 database that associated time, GPS positions and videos. For the end-user, EM analysers presented
161 one or several fishing trips at a time for each vessel, displaying alongside a map with the GPS trace, a
162 timeline indicating the instantaneous vessel speed, and the video recordings from the different
163 cameras.

164 Analysing video monitoring data is without doubt tedious, and auditing the fishing activity as a full-
165 time job was considered likely to end up lowering the overall quality of the data. Therefore, for this
166 task, students were hired on 12 h per week contracts, and taught how to identify the fishing activity
167 and detect seabird bycatch events. Four weeks of initial training with an experienced auditor were
168 necessary before a new recruit could work independently. In addition, a random 10% check was put
169 into place to verify the quality of the analysed data. In case important differences were found, a
170 senior staff would watch the corresponding footages with the auditor to understand where the
171 errors originated and what to do to remedy them.

172 Relevant information was inserted manually as notes in the EM analyser software, and consisted of
173 supplementary rows added to the database. These notes included temporal (date and time), spatial
174 (longitude, latitude) and categorical data, and were used to identify the start and end positions of
175 the sets (i.e. the deployment of the net) and of the hauls (i.e. the retrieval of the net), as well as the
176 occurrence of seabird bycatch. The fishing activity (i.e. steaming, hauling or setting nets) was
177 generally detectable using only the speed, position and course of the vessel. Conversely, detecting
178 seabird bycatch events required watching the videos of each individual haul at no more than 3 to 5
179 times the normal speed, depending on the quality of the recordings. The resulting database was
180 extracted as a spreadsheet for later use in a statistical software.

181 Some important parameters were not directly available from the EM analyser, e.g. fishing depth and
182 distance to shore. A GIS software was used to obtain these variables respectively by overlaying the
183 vessels' GPS trace with a high-definition bathymetric map provided by DTU Aqua and using an ad-
184 hoc "distance to feature" function.

185 2.4.Video analysis: bird identification

186 Each bycatch was identified at the lowest possible level using all characteristic features visible on the
187 videos, i.e. general shape and size, colour(s) of the plumage, beak and feet shape and colour, or any
188 other distinctive clue. When possible, sex and other information related to age (e.g. adult, juvenile,
189 first or second winter, breeding or non-breeding, eclipse plumage for male ducks, etc...) were also
190 recorded. EM analyser software provided the possibility to play the recorded footage frame by
191 frame, zoom onto distinctive anatomical features of the animals (plumage, beak, feet...), use
192 different camera angles and replay the sequences as many times as necessary. Being able to review
193 the key characteristics guaranteed that each individual was identified with the highest degree of
194 certainty (Figure 2). Nevertheless, ambient luminosity, weather, cleanliness of the camera lenses or
195 sun glares could strongly affect the overall readability of the picture and thus the identification
196 process. Likewise, fishers would sometimes block the view of the camera, e.g. when disentangling a
197 bird with their back turned toward the lens. In most cases, at least a few frames were exploitable to
198 identify an animal, but at times, very bad video quality made the identification impossible. Such
199 birds were marked as not identified.

200 2.5. Fishing effort and seabird bycatch rate estimates

201 Fishing effort was calculated at a fine scale (in kilometer.hour) as the product of total net fleet
202 length and soak time (i.e. the duration of submersion of gillnet fleets). First, the net fleet length was
203 measured as the distance in a straight line between the positions of the start and of the end of a
204 haul; these were defined as the moments (year, month, day, hour, minute, second) where the
205 beginning of the first panel and the end of last panel of the fleet, respectively, broke the water
206 surface. Next, each set and each haul was assigned a unique time value corresponding to the
207 difference between their respective start and end times. Finally, soak time was approximated as the
208 duration between the averaged time of a set and the averaged time of the matching haul.

209 Mean yearly bycatch rate estimates and associated confidence intervals were obtained using
210 100,000 bootstrap iterations. Seabird bycatch per unit effort (BPUE) was calculated using two
211 alternative metrics: number of birds captured per fishing trip (*bpt*) and number of birds captured per
212 kilometer.hour (*bkh*). The former metric is a widely used estimate, useful for comparing BPUE across
213 regions; the latter gave access to a measure of bycatch rates at haul level, using the product of
214 length and soak time of the submerged net fleets.

215 2.6. Fishing logbooks

216 To verify the completeness of the EM data, official logbooks were collected from the three sampled
217 vessels for the period 2010-2018. Danish fishers are legally bound to fill in these logbooks, which
218 must include information for each individual trip: departure/arrival date and time, type of fishing
219 gear and mesh size, as well as total catch in weight by species by ICES (International Council for the
220 Exploration of the Sea) rectangle. Danish logbooks make no mention of fishing effort in terms of
221 number of nets, soak time or net length. The fishing trips recorded in the EM database were
222 matched to the ones in the logbooks to verify how many trips that actually occurred were missed,
223 i.e. not recorded with the EM systems.

224

225 3. Results

226 3.1. Details of the observed seabird bycatch

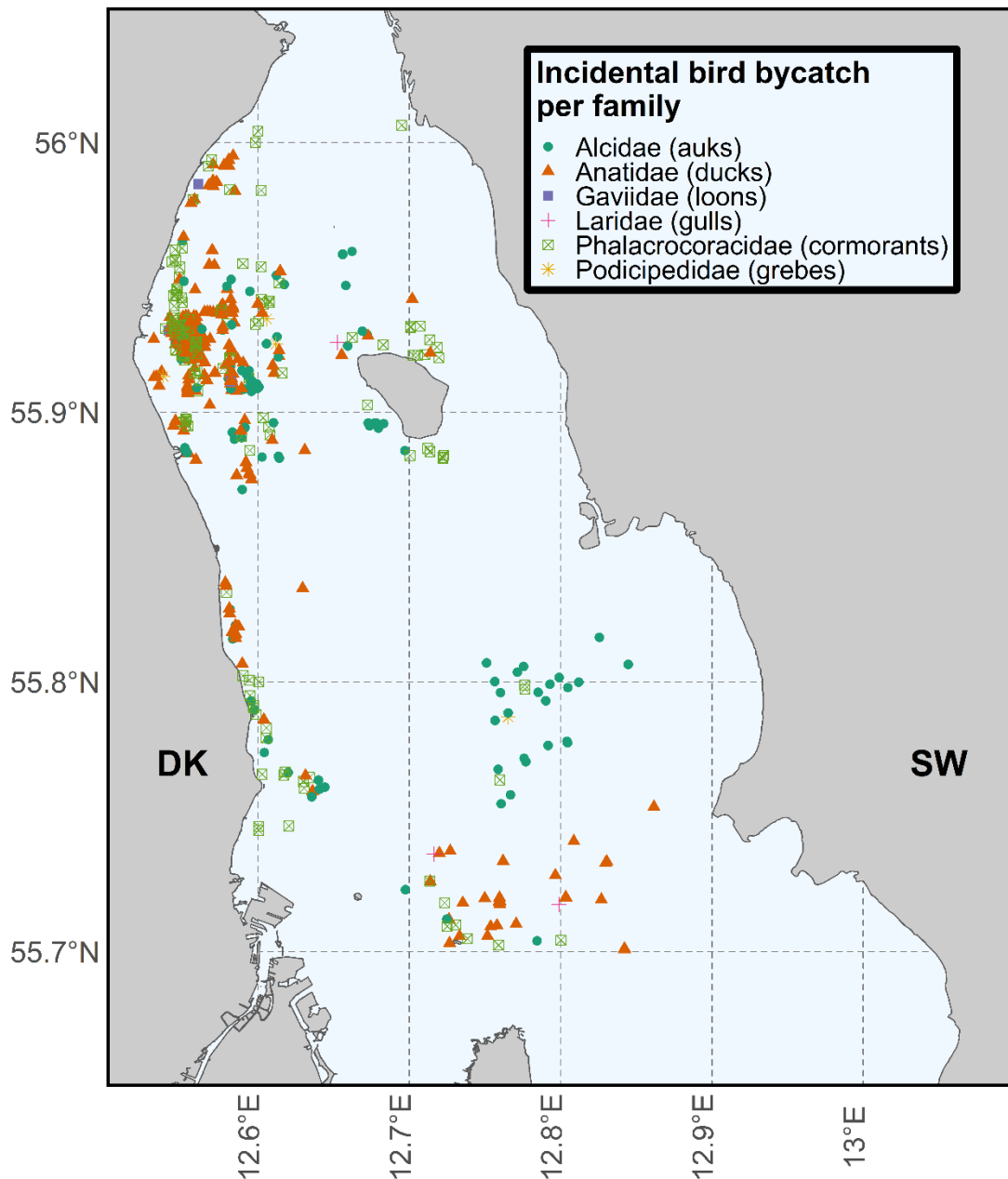
227 Although a European requirement (EC, 2016), official fishing logbooks did not mention seabird
228 bycatch for any of the sampled gillnetters throughout the time of the study. Instead, the video
229 analysis of the EM data allowed the detection of 700 birds from six different families, most of them
230 identifiable at species level (Table 2 and Figure 3). Only eight animals (1.1%) could not be identified;
231 yet, although the species could not be determined, the crew's behaviour clearly indicated that these
232 were indeed birds. A fisher disentangling a bird exhibits a different behaviour than if the catch is a
233 fish. That is, the handling of a dead bird usually takes more time than that of a fish, and bird bycatch
234 are normally stored apart from the boxes containing fish, if not directly discarded overboard. The
235 yearlong sampling scheme gave an insight into the species-specific seasonal variations in bird
236 bycatch in the commercial gillnet fishery taking place in the Sound. Table 2 presents the bycatch
237 records per season and the associated bycatch per unit effort (BPUE) estimates. Anecdotally, a
238 dozen seagulls and great cormorants (*Phalacrocorax carbo*) were entangled while trying to predate
239 on discards; all the affected animals were swiftly freed and released alive by the fishers and did not
240 seem to suffer any injuries. These events were not recorded as bycatch.

241

242 **Table 2: Seasonal variations of the number of birds taken as bycatch in gillnets, grouped by family and species; the**
 243 **corresponding bycatch per unit effort (expressed as the number of birds per kilometer.hour) is indicated in the**
 244 **parentheses. The identification is given at the lowest possible level (species, genus, family). Data were recorded on**
 245 **three electronically monitored Danish commercial gillnetters in the Sound for the period 2010-2018 (spring = March-**
 246 **May; summer = June-August; fall = September-November; winter = December-February).**

Family	Species	% total bycatch	Spring	Summer	Fall	Winter	YEAR
Anatidae	Common eider <i>Somateria mollissima</i>	58.4	n = 106 (0.000606)	n = 14 (0.000289)	n = 236 (0.054200)	n = 53 (0.007150)	n = 409 (0.001758)
	Scoter <i>Melanitta spp.</i>	3.1	n = 2 (0.000007)	-	n = 18 (0.000383)	n = 2 (0.000006)	n = 22 (0.000099)
	Not identified	0.4	n = 2 (0.000008)	-	n = 1 (0.000026)	-	n = 3 (0.000009)
Phalacrocoracidae	Great cormorant <i>Phalacrocorax carbo</i>	19.6	n = 2 (0.000008)	n = 15 (0.000417)	n = 84 (0.002272)	n = 36 (0.009180)	n = 137 (0.009040)
Alcidae	Common guillemot <i>Uria aalge</i>	12.4	n = 1 (0.000003)	-	n = 39 (0.001335)	n = 47 (0.001954)	n = 87 (0.000823)
	Razorbill <i>Alca torda</i>	2.3	-	n = 1 (0.000024)	n = 8 (0.000136)	n = 7 (0.000096)	n = 16 (0.000064)
	Not identified	1.0	n = 4 (0.000013)	-	n = 3 (0.000077)	-	n = 7 (0.000023)
Laridae	Gull <i>Larus spp.</i>	0.4	n = 1 (0.000002)	n = 1 (0.000014)	n = 1 (0.000011)	-	n = 3 (0.000007)
Gavidae	Loon <i>Gavia spp.</i>	0.6	n = 1 (0.000005)	-	n = 3 (0.000073)	-	n = 4 (0.000019)
Podicipedidae	Great crested grebe <i>Podiceps cristatus</i>	0.4	-	-	-	n = 3 (0.000047)	n = 3 (0.000012)
	Red-necked grebe <i>Podiceps grisegena</i>	0.1	-	n = 1 (0.000031)	-	-	n = 1 (0.000008)
Unidentified bird		1.1	n = 1 (0.000002)	n = 1 (0.000007)	n = 2 (0.000033)	n = 4 (0.000093)	n = 8 (0.000034)
All birds		100%	n = 120 (0.000653)	n = 33 (0.000782)	n = 395 (0.009430)	n = 152 (0.003142)	n = 700 (0.003300)

247
 248 Generally, bird bycatch, when reported (e.g. using official logbooks), is not associated to a specific
 249 position, but is instead mentioned as number of birds per fishing trip per statistical area (e.g. ICES
 250 statistical rectangle level). Therefore, having access to the exact coordinates of every incidental
 251 catch was a major benefit of using electronic monitoring (Figure 3).



252

253 **Figure 3: Positions of the incidental catch of seabirds in gillnet recorded using EM and grouped by families.**

254

255 Moreover, electronic monitoring provided information on the structure of the populations of
 256 seabirds captured in gillnets. Some groups of seabirds, e.g. ducks (Anatidae), display characteristic
 257 dimorphism between sexes, or between juveniles, immatures and adults. In particular, it was
 258 possible to identify the sex and maturity (adult or juvenile) of the common eiders (*Somateria*
 259 *mollissima*) taken as bycatch, and to distinguish juvenile (or immature) great cormorants from
 260 breeding and non-breeding adults (Table 3). Male common eiders represented 69.7% of the catches
 261 and females 23.0%, the rest being juveniles (3.4%) and unidentifiable individuals (3.9%). Bycatch of
 262 great cormorant was dominated by juvenile and immature birds (56.2%), while adult birds made up
 263 less than a third of the yearly average bycatch. However, due to a system failure, 21 individuals (i.e.
 264 about 15%) could not be classified. The reason for this is that some of the oldest video data, where
 265 these bycatches were recorded, were lost; species identification had been done prior to the data
 266 loss, but not the aging of the birds.

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Table 3: Bycatch composition for the two bird species the most frequently captured in gillnets in the Sound, the common eider and the great cormorant, per season (spring = March-May; summer = June-August; fall = September-November; winter = December-February) for the period 2010-2018. The number of observations per group is indicated in the parentheses.

Species	Status	Spring	Summer	Fall	Winter	Yearly average
Common eider	Female	16.0% (n=17)	28.6% (n=4)	25.0% (n=59)	26.4% (n=14)	23.0%
	Male	75.5% (n=80)	42.9% (n=6)	69.5% (n=164)	66.0% (n=35)	69.7%
	Juvenile (undetermined sex)	4.7% (n=5)	0.0% (n=0)	2.5% (n=6)	5.7% (n=3)	3.4%
	Unidentified	3.8% (n=4)	28.6% (n=4)	3.0% (n=7)	1.9% (n=1)	3.9%
Great cormorant	Adult (breeding and non-breeding)	50.0% (n=1)	6.7% (n=1)	33.3% (n=28)	25.0% (n=9)	28.5%
	Juvenile and immature	0.0% (n=0)	66.7% (n=10)	50.0% (n=42)	69.4% (n=25)	56.2%
	Unidentified	50.0% (n=1)	26.7% (n=4)	16.7% (n=14)	5.6% (n=2)	15.3%

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3.2. Fishing effort

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Through the study periods, official logbooks recorded 2748 fishing trips in total, while sensor data from EM systems recorded 2118 trips, consisting of 10964 hauls (Table 4). Fishing trips registered in official logbooks and recorded using electronic monitoring could in general be linked together, although some gaps were found (Table 4 and Table 5). Unrecorded trips in the EM system resulted from occasional technical issues, e.g. GPS sensor defects or power failure in the wheelhouse. These failures often required to send a technician on-board the fishing vessel to fix the problem, and could sometimes last for extended periods (e.g. vessel 2). A number of trips (78) that were recorded with electronic monitoring were not mentioned in the official logbooks. On one vessel, a closer look at the logbook data showed that, sometimes, the skipper aggregated two consecutive trips into one or that some fishing trips were simply not registered at all. Therefore, and although the logbooks are normally assumed to provide an exact measure of the fishing effort, a small uncertainty exists concerning the real number of fishing trips per vessel over the whole study period. Furthermore, the mean monthly fishing effort varied considerably along the year between and within vessels (Table 5). For example, in case of adverse weather conditions or strong currents that could damage their nets, skippers normally choose to stay in harbour.

288 **Table 4: Comparison between the numbers of trips registered in logbooks and recorded with the EM systems. The years**
 289 **indicate the periods where electronic monitoring was active for each vessel. The total number of hauls recorded and**
 290 **analysed using electronic monitoring are indicated per vessel, as well as the corresponding number of hauls per trip (± 1**
 291 **standard deviation).**

VESSEL	Total number of fishing trips (from logbooks)	Number of fishing trips recorded with EM (% covered)	Number of hauls recorded with EM (mean number of hauls per trip \pm sd)
Vessel 1 (2010-2016)	1344	1197 (89%)	6798 (3.70 \pm 2.17)
Vessel 2 (2016-2018)	436	196 (45%)	532 (2.10 \pm 1.14)
Vessel 3 (2010-2014 and 2016-2018)	968	725 (75%)	3635 (3.16 \pm 1.66)
TOTAL	2748	2118 (77%)	10965 (3.44 \pm 2.02)

292

293 **Table 5: Comparison of the mean number of fishing trips per month per vessel recorded using EM (in bold) and**
 294 **registered in logbooks (in italics in parentheses). The years indicate the periods where electronic monitoring was active**
 295 **for each vessel.**

Vessel	Jan	Feb	Mar	Apr	May	June	July	Aug	Sep	Oct	Nov	Dec
Vessel 1 (2010-2016)	22.3 <i>(23.2)</i>	15.5 <i>(16.2)</i>	21.5 <i>(21.2)</i>	9.0 <i>(7.8)</i>	17.0 <i>(21.0)</i>	20.5 <i>(20.0)</i>	14.6 <i>(15.7)</i>	13.3 <i>(18.0)</i>	15.0 <i>(20.2)</i>	19.8 <i>(23.5)</i>	23.0 <i>(23.5)</i>	19.7 <i>(18.7)</i>
Vessel 2 (2016-2018)	5.0 <i>(10.0)</i>	8.0 <i>(9.5)</i>	7.3 <i>(14.0)</i>	5.3 <i>(14.0)</i>	3.5 <i>(13.7)</i>	7.5 <i>(11.0)</i>	6.0 <i>(11.0)</i>	4.0 <i>(16.3)</i>	10.3 <i>(14.3)</i>	7.3 <i>(10.7)</i>	10.0 <i>(18.0)</i>	5.0 <i>(9.3)</i>
Vessel 3 (2010-2014; 2016-2018)	6.0 <i>(7.8)</i>	14.3 <i>(13.2)</i>	17.8 <i>(19.8)</i>	7.8 <i>(10.3)</i>	20.2 <i>(23.2)</i>	19.2 <i>(23.3)</i>	20.8 <i>(23.0)</i>	19.2 <i>(19.2)</i>	10 <i>(12.7)</i>	0 <i>(4.0)</i>	4.0 <i>(19.8)</i>	9.7 <i>(16.3)</i>

296

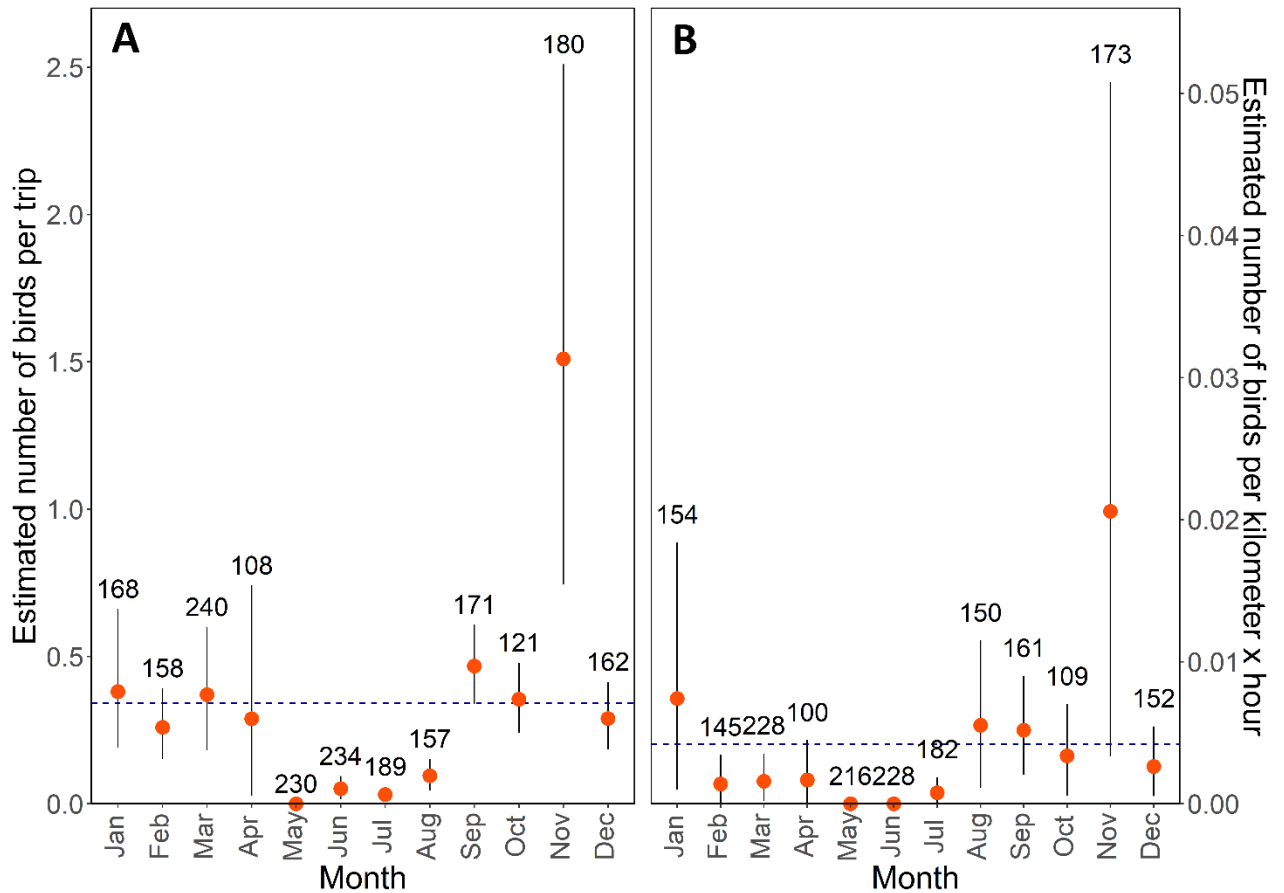
297 3.3. Bycatch rate estimates

298 Bycatch of birds occurred in 13.3% of the fishing trips recorded with EM and in 3.5% of the hauls. A
 299 few mass bycatch events may have had an overly strong influence on the mean bycatch rate
 300 estimates (Table 2). Especially, estimated bycatch per unit effort (BPUE) rates observed in November
 301 were higher than for any other months, notably because of several extreme bycatch events recorded
 302 in 2014. In fact, in 95% of the trips where bycatch was observed, no more than six birds per trip were
 303 captured, while in the remaining 5%, up to 57 birds per trip were taken as bycatch. These 5%

304 represented only 14 out of 2118 fishing trips, but accounted for 40% of the total incidental catch of
 305 seabirds observed during the study.

306 In order to visualise the influence of rare mass bycatch events on mean bycatch rate estimates,
 307 BPUE was calculated both with the full dataset (Figure 4), and after having excluded the 14 fishing
 308 trips where more than six birds had been captured (Figure 5).

309



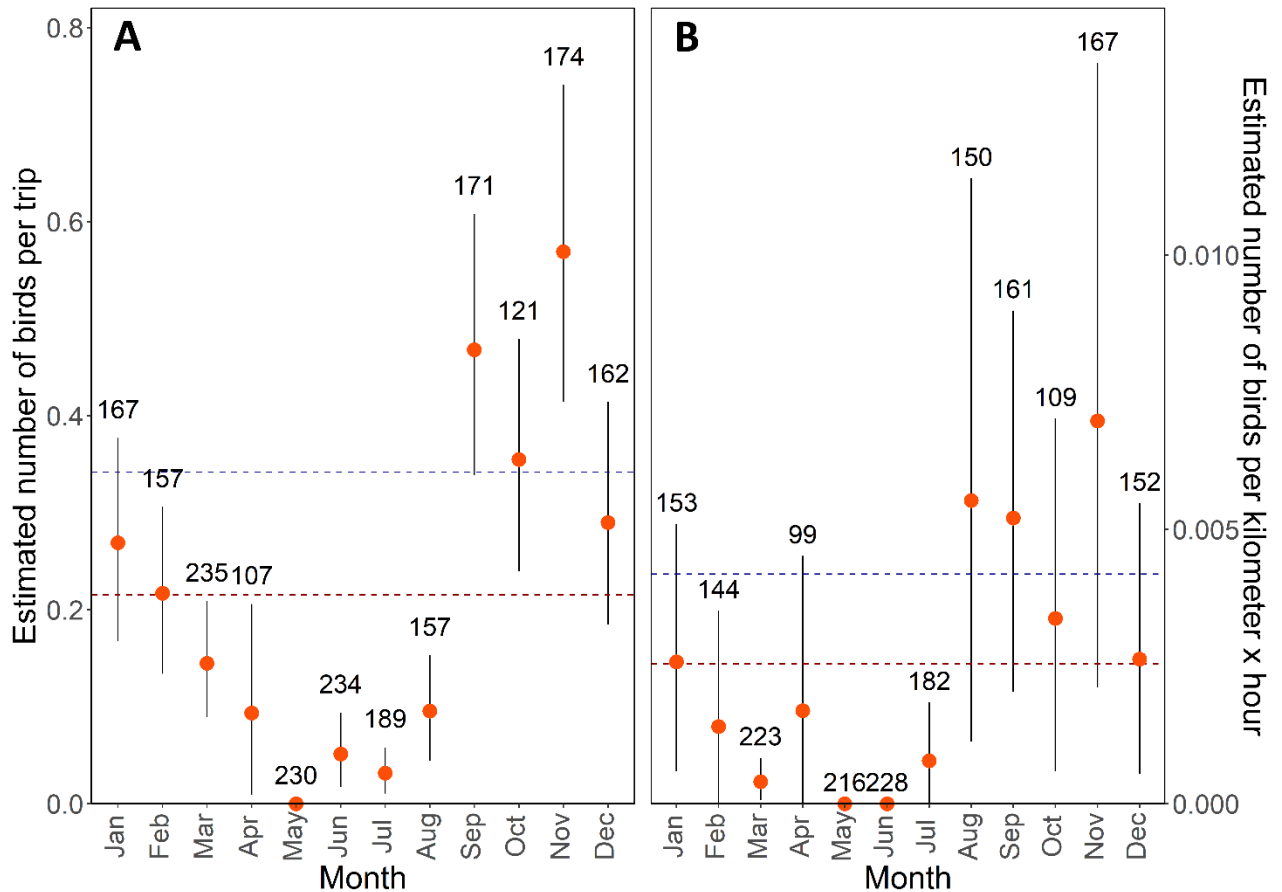
310

311 **Figure 4: Monthly estimated bycatch per unit effort (BPUE). A. Total number of incidental bird bycatch per fishing trip; B.**
 312 **Total number of incidental bird bycatch per kilometer.hour. Orange dot: mean BPUE estimates; plain black bars: 95%**
 313 **confidence intervals; dashed blue bar: average yearly bycatch rate. The total number of fishing trips for each month is**
 314 **indicated on top of the CI bars. The estimates are based on 100,000 bootstrap repetitions.**

315

316 Using the full dataset, mean BPUE was estimated at 0.00418 bird per kilometer.hour (95%
 317 confidence interval: 0.00075 to 0.00966; 100 000 bootstraps), or 0.34 bird per trip (95% confidence
 318 interval: 0.18 to 0.56; 100 000 bootstraps), with important variation between months (Figure 4). The
 319 reduced dataset containing only the fishing trips where no more than 6 birds had been captured led
 320 to an estimated yearly average of 0.0026 bird per kilometer.hour (95% confidence interval: 0.0006
 321 to 0.0052; 100 000 bootstraps), and 0.21 bird per trip (95% confidence interval: 0.14 to 0.30; 100
 322 000 bootstraps) (Figure 5).

323



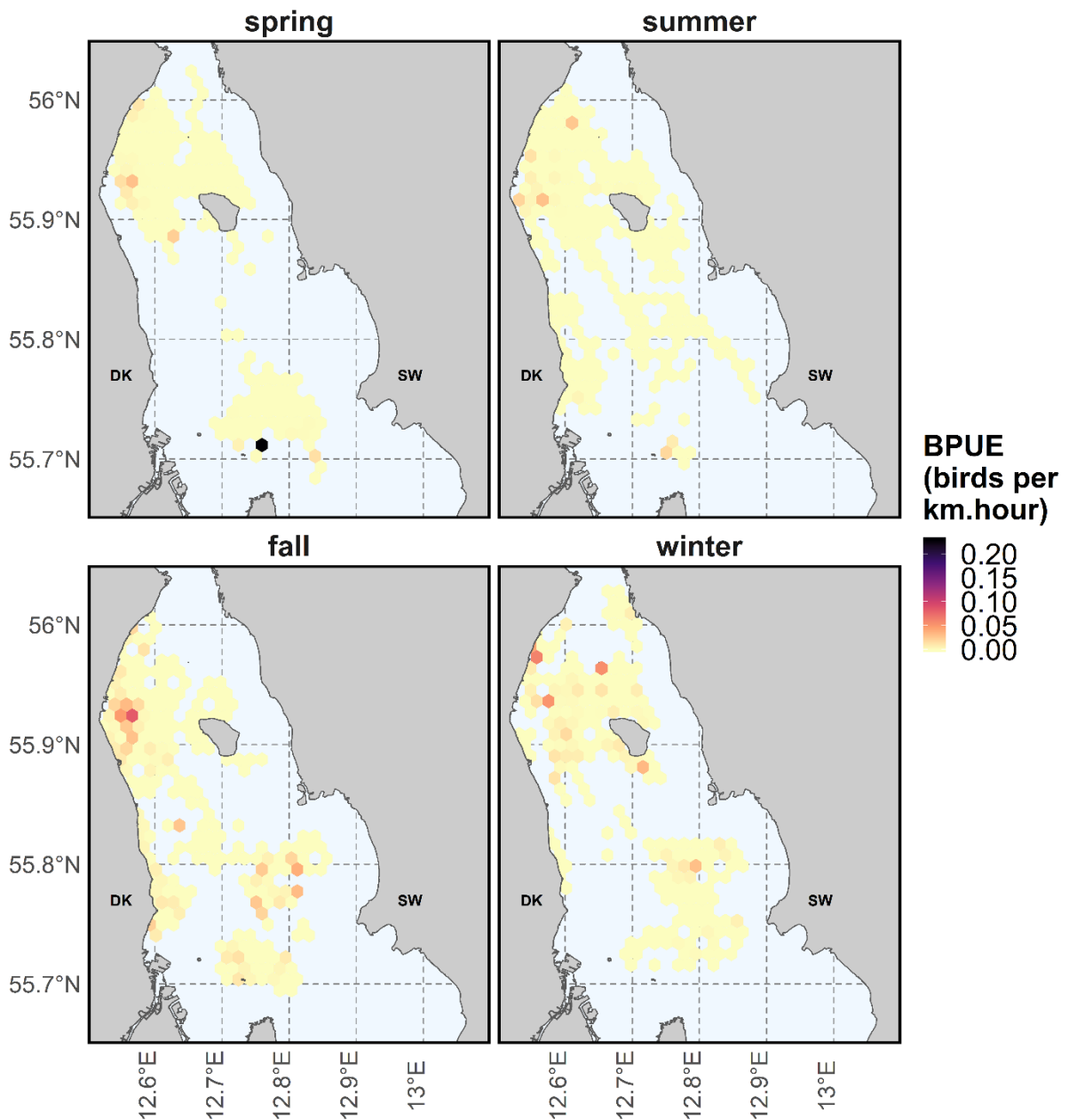
324

325 **Figure 5: Monthly estimated bycatch per unit effort (BPUE), after excluding the 14 most extreme bycatch events,**
 326 **corresponding to the 5% upper quantile: A. Total number of incidental bird bycatch per fishing trip; B. Total number of**
 327 **incidental bird bycatch per kilometer.hour. Orange dot: mean BPUE estimates; plain black bars: 95% confidence**
 328 **intervals; dashed red bar: average yearly bycatch rate excluding the 14 fishing trips where more than six birds were**
 329 **captured (i.e. 95% of the trips with bycatch); dashed blue bar: average yearly bycatch rate including the whole dataset.**
 330 **The total number of fishing trips for each month is indicated on top of the CI bars. The estimates are based on 100,000**
 331 **bootstrap repetitions.**

332

333 In the full dataset, the influence of mass bycatch events on BPUE estimates was clear. November in
 334 particular stood out as the month where birds were the most at risk of drowning in fishing nets.
 335 Overall, fall and winter were the seasons for which the rate of incidental catch was the highest,
 336 when many seabirds use the Sound as a feeding and resting ground. The period between the end of
 337 spring and summer showed in comparison very few occurrences of bycatch. Seasonal variations of

338 BPUE also revealed a spatial component (Figure 6), with important local differences in mean bycatch
 339 rates between seasons, indicating potential seasonal bycatch hotspots.



340
 341 **Figure 6: Seasonal variations in mean estimated bycatch per unit effort (in number of bird per kilometer.hour) in the**
 342 **Sound for the period 2010-2018 (spring = March-May; summer = June-August; fall = September-November; winter =**
 343 **December-February).**

344

345 4. Discussion

346 There is a relative lack of knowledge on the overall impact of fishing on seabird populations in
 347 Europe (EC, 2012). In this context, the present paper demonstrates the feasibility of using electronic
 348 monitoring (EM) systems to collect long fine-scale time-series of incidental catch of seabirds in
 349 commercial fisheries. In this study, whereas no bycatch was reported in official logbooks, EM
 350 systems were able to detect incidental catches of seabirds. Bycatch could be identified at species
 351 level, with only 1.1% of the 700 specimen remaining unidentified (Table 2). Combined with the exact

352 position of the fishing gears and the precise duration of soak time, EM allowed measuring fishing
353 effort at high-resolution (spatial and temporal). The systems offered the possibility to calculate
354 estimates of bird bycatch per unit effort (BPUE) at haul level (Figure 4), thus uncovering potential
355 areas of high risk of bycatch (Figure 6). In addition, for some bird species with plumage dissimilarities
356 between sex (e.g. common eider), or between juveniles and adults (e.g. great cormorant), it was
357 possible to establish ratios revealing differences in bycatch risks between groups of individuals of the
358 same species (Table 3).

359 The quality of bycatch data collected using CCTV monitoring is highly dependent on the quality of
360 the videos on the one hand, and on the other hand, on the ability of the video analysts to detect
361 bycatch. The EM systems, in particular the cameras, were upgraded in 2014. At first, the main
362 motivation for this change was to provide a more convenient workflow for the analysts, and to
363 reduce the risk of data loss by going from manual data acquisition (postal delivery of the hard drives)
364 to automatized over-the-air data acquisition. In the first part of the study, to reduce the number of
365 postal shipments to a minimum, the Archipelago EM Observe systems were set up to maximize the
366 recording time by limiting the video quality in terms of fps and resolution. After the change to the
367 Black Box Video system, internal storage capacity was not an issue anymore, so the video quality
368 was increased accordingly: higher resolution, higher number of frames per seconds, better contrasts
369 (Table 1). Nevertheless, even with the best cameras installed on-board, the readability of the
370 recorded footage still degrades quickly if the lenses are covered with smudge, water droplets or salt
371 crusts. It was therefore essential to contact skippers regularly to re-address the importance of
372 frequently wiping clean the cameras and to use simple prevention measures such as applying rain
373 repellent on the lenses.

374 Another recurring concern is to maintain the capacity of the human analysts to correctly and
375 consistently identify the fishing activity (anchor sets, retrieving of the nets, bycatch). Sometimes,
376 unanticipated events may occur, and a critical eye is necessary to understand and judge the situation
377 correctly. This is particularly true for gillnet fisheries when estimating soak time from EM recordings.
378 For instance, after a storm, a net fleet might have been broken apart and scattered. Associating the
379 correct set, and thus the correct soak duration, to each net fragment requires high focus. Generally,
380 hours on end of video analysing leads to mental fatigue for the analysts. Therefore, video auditors
381 were asked to work no more than 6 h daily with a pause every 2 h in order to maintain the required
382 level of concentration. Another incentive to keep standards high is to operate random quality checks
383 on already audited data. Moreover, feedback from the EM analysts is essential. Regular meetings
384 with the whole team to discuss possible methodological improvement, data flaws and to plan future
385 work clearly improved the quality of the bycatch data collection over time.

386 Besides human operators, computer-assisted image recognition, artificial intelligence and deep-
387 learning algorithms were initially considered to facilitate and speed up the analysing process. These
388 fields of research are progressing rapidly (e.g. Chen et al., 2014; Niemi and Tanttu, 2018; Hong et al.,
389 2019). Still, at the time the study started, no algorithm could perform better than a trained human
390 being does, at least not with data from small-scale vessels. Standardising video footage might help
391 accelerate the development of efficient image-recognition software. However, EM systems are
392 always customised configurations, which are adapted to specific vessel's characteristics, e.g. in terms
393 of camera placement, arrangement of deck and fishing procedures. Obtaining standardised images
394 for all small-scale vessels is therefore unrealistic. Nonetheless, there is no doubt that in a near
395 future, these technologies will be mature enough to be implemented in operational electronic
396 monitoring systems.

397 Even if the analysts assess the videos from the fishing vessels with the greatest care, there is always
398 a risk of missing an inconspicuous bird. Ideally, vessels participating in such a study should at least
399 register the number of bycatch per fishing trip – and if possible the species – as is already a

400 requirement in the European Union (EC, 2016). Nevertheless, the accuracy of fisher-reported data is
401 questionable (Mangi et al., 2015). Skippers may make mistakes filling in logbooks (Kindt-Larsen et al.,
402 2011). Regarding bycatch of protected species, some authors report a systematic lack of congruence
403 between EM data (and/or on-board observers data) and logbook data (Macbeth et al., 2018; Emery
404 et al., 2019). Fishers may also sometimes simply miss a bycatch, e.g. if a bird falls from the net
405 before being hauled up on board. Therefore, EM analysts should treat logbook data with a grain of
406 salt, and they should not only audit the days where fishers registered bycatch.

407 Bearing in mind that the quality of the data collected with EM was not always optimal and that some
408 fishing trips were not recorded in the first place (Table 4), the bird bycatch per unit effort (BPUE)
409 estimations presented in this study should be considered as conservative. Yet, the overall temporal
410 trend was clear. Estimated BPUE was one order of magnitude higher in fall and winter than in spring
411 and summer (Table 2), leading to more bird casualties in this period (547 versus 153, respectively).
412 This was expected, as the Sound is a major wintering area for many migratory birds (Skov, 2011). In
413 terms of proportion, three species made up to more than 90% of the total observed bycatch: the
414 common eider *S. mollissima* (58.4%), the great cormorant *P. carbo* (19.6%) and the common
415 guillemot *Uria aalge* (12.4%). Except for seagulls (0.4%), all the birds found drowned in gillnets were
416 diving species. These findings confirm that diving seabirds are generally more vulnerable to bycatch
417 in gillnets than are surface feeding seabirds (Żydelski et al., 2009; 2013). This contrasts with a recent
418 study from Norway, which found that the largest proportion of bird bycatch in the Norwegian
419 Reference Fleet coastal gillnet fishery was a surface-feeding seabird, the Northern fulmar *Fulmarus*
420 *glacialis* (Bærum et al., 2019). Moreover, the distribution of bycatch in the Sound showed important
421 disparities between species and a possible clustering for some (Figure 3). Common eider bycatch
422 was registered mostly in shallow waters, whereas pursuit divers such as common guillemots were
423 typically observed farther offshore. This is in line with what is known of the feeding strategies of
424 those species. Common eiders feed principally on molluscs and forage on the seabed. In the Sound,
425 their favourite prey item, the blue mussel *Mytilus edulis*, is abundant and grows in large
426 aggregations (*aka* mussel banks). Problematically for these birds, fishers tend to set their nets in and
427 around mussel banks where they expect to find the largest cods. On the contrary, common
428 guillemots can dive farther down to catch the fish they feed on, and they were accordingly often
429 captured in nets set in deeper waters. Conversely, incidental catch of great cormorants, also a
430 pursuit diver, did not seem to be associated with depth or distance to shore. Individuals taken as
431 bycatch may have been specialised in foraging in nets, which would put them at higher risks of
432 entanglement (Bregnballe and Frederiksen, 2006). Furthermore, a differential risk of drowning was
433 observed within two species: the common eider and the great cormorant (Table 3). Common eider
434 vulnerability to bycatch was clearly sex-biased. Males represented almost 70% of the total catch, but
435 this proportion reflects the male bias in the Baltic population (Ramula et al., 2018). Great cormorant
436 bycatch appeared age-biased (56% juveniles and immature birds). Bregnballe and Frederiksen (2006)
437 hypothesised that young and less experienced individuals are more at risk of interacting with soaked
438 fishing gears and drown.

439 These few examples emphasize that deadly seabird-fishery interactions cannot be summarised as a
440 simple overlap between fishing effort distribution and seabird distribution. Complex and species-
441 specific relationships exist between birds and fisheries, and depend on many factors including
442 behavioural, operational, environmental or meteorological (Torres et al., 2013; Clay et al., 2019). In
443 the Sound, in the absence of detailed maps of the fishing effort and of the seabird distribution, long
444 term EM monitoring of coastal gillnetters provides insightful data, which helps understanding
445 underlying bird-fisheries interactions. This knowledge is essential to improve and advance both the
446 management of coastal fisheries and the conservation of marine avifauna (Northridge et al., 2017;
447 Le Bot et al., 2018). Besides, understanding the possible impact of fisheries bycatch at population
448 levels requires further investigation. Two of the most affected species in this study, the common
449 eider and the common guillemot, regionally qualify as near threatened on the IUCN Red List, while

450 the great cormorant is considered least concerned (IUCN 2019). Moreover, because of the large
451 decline observed since the 1990's, the HELCOM Red List categorises the common eider wintering
452 population as endangered (Kontula and Haldin, 2013). Additionally, fishing effort is not randomly
453 distributed, since skippers normally set their nets in areas where they expect to maximize the catch
454 of their target species. Therefore, bycatch numbers are only relevant in relation to fishing intensity.
455 The literature often reports bycatch rates in gillnet fisheries as the mean number of animals
456 captured per trip, or as the mean number of animals captured per net. Here, EM was utilized to
457 access fine-scale effort data over long periods and to identify fishing grounds and bycatch hotspots
458 precisely. Furthermore, incidental catches are rare events, and authors studying seabird-fisheries
459 interactions often work with datasets containing sporadic bird bycatch. Such data are typically
460 overdispersed (relative to the Poisson assumption), with a high proportion of zeros (i.e. no bycatch
461 in a haul/trip) and localised large counts due to the gregarious behaviour of some species (Sims et
462 al., 2008). As suggested by Bærum et al. (2019), these unpredictable extreme events could
463 considerably bias mean BPUE estimates and lead to exaggeratedly high predictions if used to feed a
464 statistical model. In the present study, 14 fishing trips (corresponding to the 5% upper quantile)
465 captured more than six birds per trip. To visualize the influence of mass bycatch, BPUE estimates
466 were presented with and without these extreme events (Figure 4 and Figure 5). Moreover, BPUE
467 estimates were also reported both as the number of bird captured per fishing trip (*bpt*) – as is the
468 case in numerous publications on seabird bycatch in gillnet fisheries (Le Bot et al., 2018) – and as the
469 number of birds per kilometer.hour (*bkh*). The latter estimates BPUE at haul level by incorporating
470 explanatory operational factors (soak duration and net length). Regardless of the metric, the
471 comparison of Figures 4 and 5 showed that mass bycatch events clearly affect the mean estimator of
472 BPUE: after excluding the 5% upper quantile, mean yearly estimated bycatch rates dropped by
473 almost a third, and months where extreme bycatch had been observed (especially November)
474 appeared much less peculiar. Therefore, it may be necessary to remove these outliers when building
475 a predictive statistical model to allow the model to converge or at least to calculate reliable
476 estimates. However, with 40% of all observed bycatch recorded in mass bycatch events, ignoring
477 these will necessarily result in over-optimistic results.

478 A straightforward solution to overcome the problem of accuracy of bycatch rate estimates is to
479 increase the monitoring effort. However, the cost associated with EM (both implementation and
480 running cost) is often pointed out as a weakness (van Helmond et al., 2019). Consequently, it is
481 tempting to choose to analyse only a randomly selected fraction of the fishing activity.
482 Problematically, bird bycatch events are rare and not randomly distributed. In this study, 40% of the
483 casualties were recorded in less than 0.2% of the hauls. As a result, examining a sample of the
484 complete dataset would likely result in inaccurate estimates. Still, compared to alternatives like
485 human observers, EM is generally less biased (no observer effect) and more cost-effective (Michelin
486 et al., 2018). Additionally, self-reporting of bycatch for the vessels equipped with EM could help
487 reduce the number of hauls to analyse and the cost associated with it, as long as quality control
488 procedures are in place. In turn, a dedicated EM programme should aim at evaluating bycatch rates
489 accurately on few representative vessels instead of spreading the monitoring effort on a large
490 portion of the fleet whose activity will be only partially analysed.

491 Quality EM data requires the full cooperation of the participating fishing vessels. Crewmembers
492 need to comprehend the necessity to keep a clear and unobstructed view for the CCTV cameras, and
493 not withdraw information by switching off the monitoring system. A close collaboration between the
494 fishing industry and scientists, as well as strong incentives (e.g. in the form of additional quotas or
495 days at sea), is necessary to overcome the initial distrust that the fishing community might have
496 toward EM systems (Mangi et al., 2015). Ideally, a monitoring programme should randomly select
497 the fishing vessels to survey. It was not the case here. The sampled vessels were all volunteers, and
498 consequently, they cannot be considered representative of the overall fishing fleet. Besides, regular
499 contacts with the skippers involved in the project may have made them aware of seabird bycatch

500 issues. In turn, they may have avoided areas where they believed the risk of incidental catch was
501 high, thus making the estimated BPUE for the sampled gillnetters lower than for the rest of the fleet.
502 However, on small-scale vessels such as the ones in the Sound, catching many birds increases
503 handling time enormously and reduces profitability. Therefore, fishers tend to minimise unwanted
504 catches, avoiding fishing grounds where the possibility of capturing many seabirds is high, even if
505 this means relocating their nets to areas potentially less attractive in terms of catches of target
506 species (Savina, 2018).

507 In summary, i) bycatch rate estimates were based on a fraction of the total fishing effort of the
508 sampled vessels (Table 4), ii) mass bycatch events were excluded to obtain more reliable mean BPUE
509 estimates (Figure 4 and Figure 5), and iii) participating fishing vessels may have been more attentive
510 to seabird bycatch than average. Consequently, the seabird bycatch rates presented here ought to
511 be considered conservative estimates. Nevertheless, determining such a baseline is essential to
512 unfold the overall impact of gillnets on the seabird populations of the western Baltic Sea.

513 Establishing long-term electronic monitoring programmes in small-scale gillnet fisheries can provide
514 unique information on incidental captures of seabirds and on the factors associated with bycatch,
515 including fishing effort. Collecting such data is essential in fisheries with a suspected bird bycatch
516 problem. For instance, the lump sucker gillnet fisheries in the North Atlantic, characterized by long
517 soak times, extensive net length and the use of large meshes, have been reported to capture large
518 numbers of seabirds (Christensen-Dalsgaard et al., 2019). In these fisheries, EM with CCTV could,
519 together with on-board observers, be the most efficient way to collect seabird bycatch data,
520 essential both for fisheries managers to ensure the sustainability of artisanal coastal fisheries and for
521 conservation scientists to tackle seabird populations decline.

522

523 Conclusions

524 Electronic monitoring with CCTV appears to be a reliable solution for monitoring the bycatch of
525 seabirds in coastal gillnet fisheries, where vessels are usually too small to accommodate an on-board
526 observer. Video monitoring data is accurate enough to identify individuals at species level and for
527 some species to age and sex them. The high precision of the bycatch rates estimates, both spatially
528 and temporally, allows the determination of areas of high risks of bird bycatch, although mean BPUE
529 are arguably underestimated due to the nature of the sampling scheme. More in-depth analysis of
530 the EM data collected for this study will allow determining which operational and non-operational
531 factors influence seabird bycatch in gillnets, which in turn will permit estimating the overall number
532 of bird casualties at fleet level.

533

534 Declaration of competing interest

535 None.

536

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544

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