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# Fundamental Limits in Bayesian Thermometry and Attainability via Adaptive Strategies

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We investigate the limits of thermometry using quantum probes at thermal equilibrium within the Bayesian approach. We consider the possibility of engineering interactions between the probes in order to enhance their sensitivity, as well as feedback during the measurement process, i.e., adaptive protocols. On the one hand, we obtain an ultimate bound on thermometry precision in the Bayesian setting, valid for arbitrary interactions and measurement schemes, which lower bounds the error with a quadratic (Heisenberg-like) scaling with the number of probes. We develop a simple adaptive strategy that can saturate this limit. On the other hand, we derive a no-go theorem for nonadaptive protocols that does not allow for better than linear (shot-noise-like) scaling even if one has unlimited control over the probes, namely, access to arbitrary many-body interactions.

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**Introduction.**—Preparing quantum systems at low temperatures is an essential task for development of quantum technologies [1–3]. Measuring temperature precisely is necessary to validate cooling and ensure the performance of quantum protocols, and has been demonstrated in cutting-edge experiments [4–12]; it is however challenging. Due to the scarcity of thermal fluctuations at such low temperatures, the relative error on thermometry can be enormous. Moreover, the fragility of quantum systems requires additional forward planning to minimise disturbance while maximising the information obtained. The theory of quantum thermometry is built to address these pivotal challenges [13,14].

Quantum thermometry finds fundamental limits on precision [15–18] and designs protocols to achieve them in different platforms [19–22], and improve them thanks to quantum correlations [23,24], coherence [25,26], many-body interactions and criticality [27–32] or other resources [33,34]. To date, such enhancements have been developed in the context of local thermometry, aiming at designing a thermometer that detects the smallest temperature variations around a known temperature [13,14]. In many practical situations, however, one might not know the temperature accurately beforehand. Rather, one has limited prior knowledge about the temperature of the sample. Under such circumstances, Bayesian estimation is a more suitable approach, and has been the subject of a few recent studies [35,36].

The goal of this Letter is to set the ultimate bounds of Bayesian equilibrium thermometry, and to develop adaptive strategies to saturate them. It is insightful to first recall analogous results in the local approach to equilibrium

thermometry [13,14]. Within such a framework—contrary to dynamical approaches where the probe evolves according to some predefined model parametrized by the temperature [37,38], e.g., a superconducting qubit in radiometry [39]—the probe always thermalizes to the temperature of the sample whose value is known *a priori*. In that case, for any unbiased estimator  $\tilde{\theta}$  of the temperature  $\theta_0$ , the mean square error is inversely proportional to the heat capacity of the probe:  $\Delta\tilde{\theta} \propto 1/C$  [15,16,29,40]. For  $n$ -body probes,  $C$  can scale superextensively with  $n$  in the vicinity of a critical point, with the ultimate bound  $C \approx n^2/4$  [15,41]—a quadratic scaling with the number of resources reminiscent of the Heisenberg scaling in quantum metrology [42]. Here, we show that similar bounds hold in the Bayesian approach, but adaptive strategies are needed to saturate them, contrary to the local case. In fact, we prove that any nonadaptive strategy necessarily leads to  $\Delta\tilde{\theta} \propto 1/n$  for sufficiently large  $n$ —i.e., a shot-noise-like scaling [42]—a no-go result that holds even when arbitrary control over the  $n$ -body probe Hamiltonian is allowed. Thus, adaptive measurement strategies are a crucial ingredient for optimal thermometry whenever the temperature value is *a priori* not perfectly known.

**Preliminaries and setup.**—We consider estimation of the temperature  $\theta_0$  of a (possibly macroscopic) sample given some prior distribution  $p(\theta)$  reflecting our initial knowledge on  $\theta_0$ . We assume we have at our disposal  $N$  copies of a  $d$ -dimensional system that we use as probes, which are much smaller than the sample. When put in contact with the sample, we assume that the probes eventually reach thermal equilibrium at temperature  $\theta_0$ . By measuring them we infer

$\theta_0$ . This corresponds to the framework of equilibrium thermometry, which is by nature robust [13,14]. In order to establish fundamental bounds, we assume full control on the Hamiltonian of the probes, and in particular the ability to make them interact. Therefore, alternatively one can think of a  $d^N$ -dimensional probe, which constitutes our resource.

The thermometry process is divided into  $m$  rounds, each involving  $n = N/m$  probes. Every round consists of (I) preparation of the  $n$ -body probe, (II) interaction with the sample and thermalization, (III) measurement or data acquisition, and (IV) data analysis (see Fig. 1). In the first round, we start by engineering the Hamiltonian  $H_n^{(1)}$  of the  $n$ -body probe into any desired configuration based on the prior distribution  $p(\theta)$ . That is, we arrange the energy distribution of the  $n$ -body probe to become most sensitive to the relevant temperature range. Next, in step (II), this  $n$ -body system is put in contact with the sample, and reaches thermal equilibrium with it. Therefore, it can be described by the Gibbs state  $\omega_{\theta_0}(H_n^{(1)}) := \exp[-H_n^{(1)}/\theta_0]/Z$ , with  $Z = \text{Tr}(\exp[-H_n^{(1)}/\theta_0])$  the partition function. Then, in step III, a measurement is performed that yields an outcome  $x_1$ . We focus on energy measurements since they are optimal as the Gibbs state is diagonal in the energy basis. In the data analysis (step IV), the posterior distribution is obtained through Bayes' rule:

$$p(\theta|x_1) = \frac{p(x_1|\theta)p(\theta)}{p(x_1)}, \quad (1)$$

where  $p(x|\theta)$  is the likelihood function (which depends on the temperature *and* the Hamiltonian),  $p(\theta)$  is the prior distribution on  $\theta$ , and  $p(x) = \int d\theta p(\theta)p(x|\theta)$  is the outcome probability. The next round proceeds in an analogous way, but replacing the prior  $p(\theta)$  by  $p(\theta|x_1)$  and  $H_n^{(1)}$  by  $H_n^{(2)}$ . Likewise, in round  $k > 1$ ,  $p(\theta)$  is replaced by  $p(\theta|\mathbf{x}_{k-1})$  with  $\mathbf{x}_{k-1} \equiv \{x_{k-1}, \dots, x_2, x_1\}$  and  $H_n^{(1)}$  is replaced by  $H_n^{(k)}$ . Such a strategy is adaptive since  $H_n^{(k)}$  depends on  $\mathbf{x}_{k-1}$ . In contrast, a nonadaptive strategy satisfies  $H_n^{(k)} = H_n \forall k$ , where  $H_n$  is chosen according to the initial prior  $p(\theta)$  only. At the end of the thermometry process (round  $m$ ), the final estimate  $\tilde{\theta}(\mathbf{x}_m)$  of  $\theta_0$  is computed.

In order to gauge the quality of the estimator, we need to introduce an error quantifier that describes how far  $\tilde{\theta}$  is from  $\theta_0$ , on average. A natural measure which is suitable for equilibrium probes is the expected mean square logarithmic error (EMSLE) (see Ref. [35] for justification and the accompanying paper [43] for a deeper analysis and generalization)

$$\text{EMSLE} := \int d\theta p(\theta) \int d\mathbf{x}_m p(\mathbf{x}_m|\theta) \ln^2 \left[ \frac{\tilde{\theta}(\mathbf{x}_m)}{\theta} \right], \quad (2)$$

with  $d\mathbf{x}_m := dx_m \dots dx_1$ . Moreover,

$$\tilde{\theta}(\mathbf{x}_m) = \exp \left[ \int d\theta \frac{p(\theta)p(\mathbf{x}_m|\theta)}{p(\mathbf{x}_m)} \ln \theta \right], \quad (3)$$

is the optimal temperature estimator, i.e., it minimizes EMSLE [35].

We wish to find lower bounds for EMSLE, as well as optimal strategies to saturate them, for both adaptive and nonadaptive measurements. More precisely, our aim is to minimize EMSLE as a function of the number  $N$  of probes, with  $N = mn$ . We will pay particular attention to the relevant case where  $m \gg 1$  is large (asymptotic regime) but  $n$  is limited due to, e.g., experimental limitations on the amount of probes that can be collectively processed. In this case, we will focus on the scaling of EMSLE with  $n$  for a fixed but large  $m$ .

**Main results.**—Our main results are (i) an ultimate precision limit for Bayesian thermometry that holds for both adaptive and nonadaptive strategies, which in principle allows for a quadratic (Heisenberg-like) scaling with  $n$ , (ii) a no-go theorem that forbids superextensive scaling in any nonadaptive scenario, and (iii) an adaptive strategy that reaches the ultimate limit. These results are derived in what follows (technical details are given in the Supplemental Material [44]).

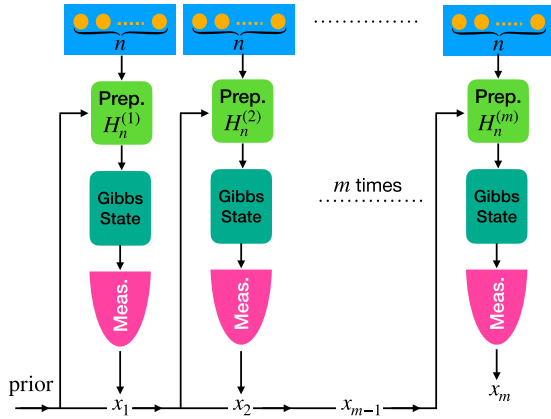


FIG. 1. Schematic representation of the adaptive scenario. A total of  $N$  probes are used in groups of  $n$  to estimate the temperature of the sample,  $\theta_0$ . Initially, our prior temperature distribution is given by  $p(\theta)$ , according to which we choose the Hamiltonian of the first  $n$  probes to be  $H_n^{(1)}$  that minimizes the expected mean square logarithmic error. The probes interact and thermalize with the sample followed by an energy measurement, yielding an outcome, say  $x_1$ . Our knowledge about the temperature will be reflected in the posterior distribution  $p(\theta|x_1)$ . This will be used as the prior for the second round—in order to find the optimal Hamiltonian  $H_n^{(2)}$ . This process is repeated  $m = N/n$  times. In contrast, in the nonadaptive scenario the Hamiltonian is fixed  $H_n^{(k)} = H_n \forall k$ .

Given the prior  $p(\theta)$ , and by utilizing the Van Trees inequality [46,47] we construct a lower bound on the estimation error after  $m$  rounds

$$\text{EMSLE}^{-1} \leq Q[p(\theta)] + \sum_{k=1}^m \int d\mathbf{x}_{k-1} p(\mathbf{x}_{k-1}) \times \int d\theta p(\theta|\mathbf{x}_{k-1}) C(\theta; H_n^{(k)}), \quad (4)$$

where  $p(\theta|\mathbf{x}_0) = p(\theta)$ ,  $p(\mathbf{x}_0) = p(\mathbf{x}_0|\theta) = 1$ , and  $\int d\mathbf{x}_0 = 1$  are introduced to compress our notation. Here,  $Q[p(\theta)]$  quantifies the prior information and reads

$$Q[p(\theta)] := \int d\theta p(\theta) [1 + \theta \partial_\theta \log p(\theta)]^2. \quad (5)$$

The second term quantifies the information acquired through all measurements. It also establishes a connection to the quantum Fisher information through its proportionality to the heat capacity [15]. The heat capacity of the probe at round  $k$  of the measurement is denoted  $C(\theta; H_n^{(k)})$ , with the Hamiltonian  $H_n^{(k)}$  designed according to the prior and the information acquired so far. Recall that, by definition,  $C(\theta; H_n) := \partial_\theta E(\theta; H_n)$ , where  $E(\theta; H) = \text{Tr}[H\omega_\theta(H)]$  is the energy of the probe at thermal equilibrium. To bound Eq. (4), we first define the maximum of the integrand over  $\{H_n^{(k)}\}_{k=1}^m$  for a specific trajectory  $\mathbf{x}_m$ :

$$\Gamma(\mathbf{x}_m) := \max_{\{H_n^{(k)}\}_k} \sum_{k=1}^m \int d\theta p(\theta|\mathbf{x}_{k-1}) C(\theta; H_n^{(k)}) \leq \sum_{k=1}^m \int d\theta p(\theta|\mathbf{x}_{k-1}) C_D = mC_D, \quad (6)$$

where  $C_D := \max_{H_n} C(\theta; H_n)$ , i.e., the maximum heat capacity of an  $n$ -body probe. In the last line we used that  $C_D$  is independent of  $\theta$  (see Refs. [15] or [44] for the explicit expression of  $C_D$ ). Furthermore, we have  $C_D \approx \frac{n^2}{4} \log^2 d$ , for large enough  $n$ . Putting everything together, we obtain from Eq. (4)

$$\text{EMSLE}^{-1} \leq Q[p(\theta)] + mC_D \stackrel{n \gg 1}{\approx} Q[p(\theta)] + m \frac{n^2}{4} \log^2 d. \quad (7)$$

This gives an ultimate bound on Bayesian thermometry [result (i)], which both adaptive and nonadaptive strategies should respect. This bound implies that any Bayesian thermometry protocol is ultimately limited by a quadratic Heisenberg-like scaling.

The ultimate bound (7) becomes tight and can be saturated by adaptive strategies in the regime  $m \gg 1$  (see results below). However, nonadaptive strategies fail

to saturate it, and in fact  $\text{EMSLE}^{-1}$  can increase at most linearly with  $n$  [result (ii)]

$$\text{EMSLE}^{-1} \stackrel{\text{nonadaptive}}{\leq} Q[p(\theta)] + f[p(\theta)] mn \log d, \quad (8)$$

where  $f[p(\theta)] = \int_{\mathcal{R}} d\theta [-\partial_\theta p(\theta)] \theta$  is a functional of only the prior distribution, and  $\mathcal{R}$  is the temperature domain where  $\partial_\theta p(\theta) \leq 0$ . This result is rigorously proven in the Supplemental Material [44], but let us provide some intuition. It is already noted in the literature that engineered probes for thermometry show enhanced sensitivity only in a small temperature range  $\Delta$  [13,15,48–50]. Finite-size scaling theory hints that if  $C \propto n^{1+\alpha}$ , then  $\Delta \propto n^{-\gamma}$  with  $\gamma \geq \alpha$  in order to ensure that the energy density of an equilibrium state remains finite [51]. This implies that, for any  $p(\theta)$  with a finite width (independent of  $n$ ), the term  $\int d\theta p(\theta) C(\theta)$  in Eq. (4) grows at most linearly with  $n$  for sufficiently large  $n$ . In other words, optimal  $n$ -body probes require priors with a width smaller than  $\mathcal{O}(1/n)$  to obtain superlinear scaling, and conversely a finite width in  $p(\theta)$  will eventually kill any superlinear scaling. The no-go result (8) makes this intuition rigorous.

The above reasoning also explains why adaptive protocols can potentially saturate (7). By updating the prior  $p(\theta)$  to the posterior  $p(\theta|\mathbf{x}_{k-1})$  in each step of the process ( $k = 1, \dots, m$ ), it can stay inside the optimal region for sufficiently large  $m$ , thus enabling superlinear precision. This also suggests using optimal probes for local thermometry as an *ansatz* for the Bayesian thermometry with adaptive strategies. The optimal thermometer in the local scenario is an effective two-level system with  $d^n - 1$ -fold degeneracy in the excited state [15]. Although this Hamiltonian is useful to obtain fundamental bounds [15] it involves  $n$ -body interactions and is hence highly complex for  $n \gg 1$ . Nonetheless, it can be well approximated through two-body interactions by the method developed in Ref. [52] and, furthermore, it can be effectively realized with a few-fermionic mixture confined in a one-dimensional harmonic trap [41]. Motivated by this progress, at the  $k$ th round we restrict to the class of Hamiltonians  $H_n^{(k)}$  with the aforementioned two-level structure, and tune the energy gap to minimize the EMSLE (2). As we show in the example below, we can achieve a quadratic scaling with  $n$  and saturate (7) using this strategy [result (iii)].

*Case study.*—The results presented here are valid for a broad class of priors, but in what follows we stick to a specific choice in order to illustrate their usage. In any relevant application of thermometry, the temperature is known *a priori* to lie within a certain range, i.e.,  $\theta_{\min} \leq \theta \leq \theta_{\max}$ . We use a family of probability distributions that are suitable in this case and were proposed in Ref. [53]:

$$p(\theta) = \frac{1}{k_\alpha(\theta_{\max} - \theta_{\min})} [e^{\alpha \sin^2(\pi \frac{\theta - \theta_{\min}}{\theta_{\max} - \theta_{\min}})} - 1] \quad (9)$$

with

$$k_\alpha := e^{\alpha/2} I_0(\alpha/2) - 1, \quad (10)$$

where  $I_0$  is the modified Bessel function of the first kind. In the limit  $\alpha \rightarrow -\infty$  the above prior becomes a constant, while in the limit  $\alpha \rightarrow 0$  we have  $p(\theta) \propto \sin^2(2\theta)$ .

The adaptive strategy works as follows. We consider as a resource  $N$  qubits, which are divided in  $m$  groups of  $n$  qubits. In each group, the  $n$ -qubit Hamiltonian is engineered to become a two-level system with degeneracy  $(2^n - 1)$  and with a tunable gap  $\epsilon$ . In the first round, we tune the gap to  $\epsilon^{(1)}$  to minimize the single shot EMSLE, that is we set  $m = 1$  in Eq. (2). Then, we measure the energy of the system. Given the outcome  $x_1$  is observed, we update the prior to  $p(\theta) \rightarrow p(\theta|x_1)$ , and implement the same procedure to choose  $\epsilon^{(2)}$  in the second round [i.e., we minimize Eq. (2) replacing  $p(\theta) \rightarrow p(\theta|x_1)$ ]. This process is repeated until all probes are used.

In our simulations, we apply the adaptive process for a given  $\theta_0$  sampled from  $p(\theta)$ , which yields a trajectory as illustrated in the left panel of Fig. 2. We see that the prior peaks around the true temperature as  $k$  increases, and the estimated temperature gets closer to the true temperature, i.e.,  $\tilde{\theta}/\theta_0 \rightarrow 1$ . The average over a large amount of trajectories enables us to compute EMSLE in Eq. (2) with

high accuracy (in the numerical simulations, we consider  $\mathcal{O}(1000/m)$  trajectories, which ensures convergence). In the right panel of Fig. 3 we plot EMSLE in the adaptive scenario for various values of  $n$ , benchmarked against the no-go bound for nonadaptive scenarios—only the shaded area can be accessed by nonadaptive strategies given any  $n \leq N$ . We see that as  $n$  increases the error gets smaller for large enough  $N$ . In particular, there exist some thresholds  $n$  for which one can beat the no-go bound via adaptive strategies. As an example, given  $N = 10^3$  and  $\theta_{\max}/\theta_{\min} = 10$  in Eq. (9) (with  $\alpha = 1$ ), adaptive strategies using  $n \approx 10$  interacting qubits outperform arbitrary nonadaptive strategies.

Next, we ask whether the adaptive strategy can reach the Heisenberg-like scaling,  $\text{EMSLE}^{-1} \propto mn^2$ . To this aim, we study the behavior of the error with the resources  $n$  for a sufficiently large number of repetitions  $m$ . The results are depicted in Fig. 3, where we see Eq. (7) is saturated and therefore the proposed adaptive scheme reaches the ultimate bound on thermometry.

Finally, we note that although the optimal protocol requires a very idealized Hamiltonian for the probe [a  $(2^n - 1)$ -degenerate two-level system], adaptive protocols already become useful for small  $n$ . Namely, for  $n = 1, 2$ , they decrease the error more than 60% and 80%, respectively, compared to the nonadaptive protocols [44]. For larger  $n$ , a realistic method to obtain a scaling of the EMSLE beyond the SNL would be to combine the adaptive method derived here with thermal phase transitions [51].

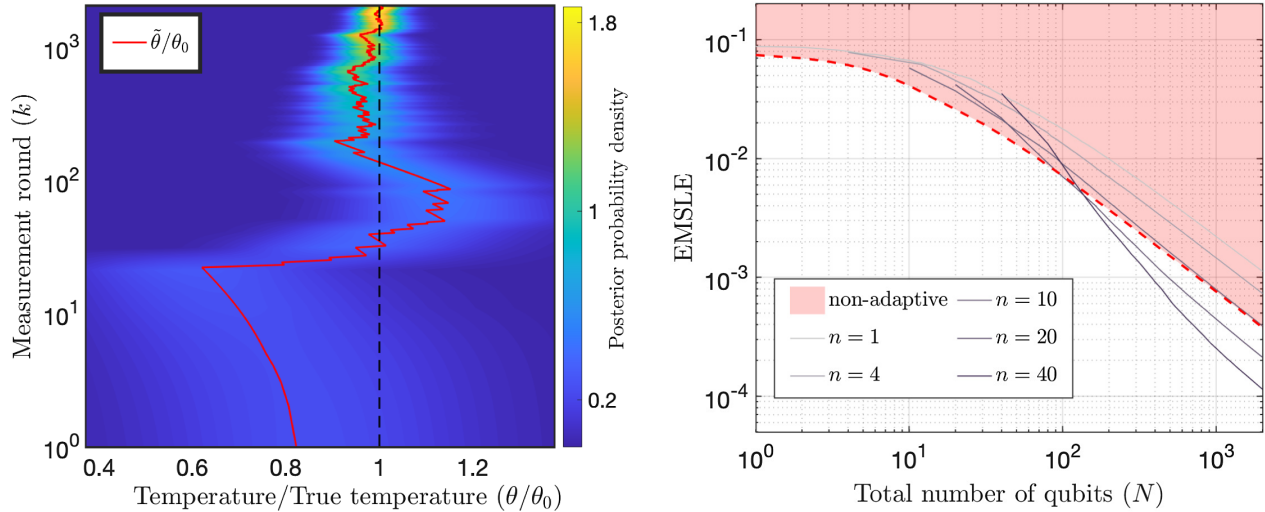


FIG. 2. Left—Contour plot of the prior versus the measurement round  $k \in \{1, \dots, m\}$  (logarithmic scale), and temperature normalized to its true value  $\theta/\theta_0$ . The red trajectory shows the ratio between the estimated temperature and the true temperature  $\tilde{\theta}/\theta_0$ . As  $k$  increases, the prior sharpens around the true temperature, and  $\tilde{\theta}/\theta_0$  approaches one. Here, we have set  $n = 1$ ,  $\alpha = 1$ ,  $\theta_{\min} = 1$ , and  $\theta_{\max} = 10$  in arbitrary units. Right—Loglog plot of the expected mean square logarithmic error attained by the adaptive strategy vs the total number of qubits  $N$ . Dark solid lines represent different values of  $n$ . They show that, for sufficiently large  $N$ , the bigger  $n$  is the smaller the error can get. The red-dashed line is the (not necessarily tight) bound on nonadaptive strategies: only the shaded area can be achieved using nonadaptive protocols. One can cross the border with adaptive strategies for  $n > 10$ .

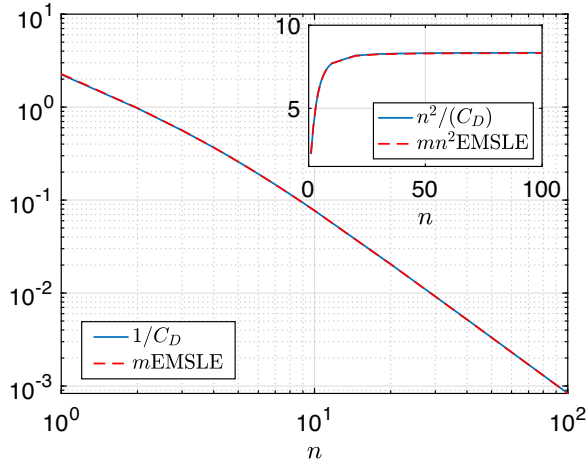


FIG. 3. (Dashed red) Log-log plot of the normalized expected mean square logarithmic error after  $m$  rounds of the adaptive scheme—for sufficiently large  $m$ , here  $m = 2 \times 10^3$ —vs  $n$ . This shows that for large enough  $n$  the error vanishes quadratically with  $n$ , which can be better seen from the inset. (Blue) The minimum achievable EMSLE given by the right-hand side of Eq. (7). The perfect agreement shows the efficiency of the proposed adaptive protocol.

*Conclusions and future directions.*—We derived fundamental limitations of the Bayesian approach to equilibrium thermometry, which shows a Heisenberg-like quadratic scaling with the number of probes. We showed nonadaptive strategies cannot saturate this bound and are limited to shot-noise-like scaling whenever the initial prior is not sharp. We also constructed an adaptive protocol that saturates the ultimate bound, thus highlighting the crucial role of adaptivity in quantum thermometry. This is importantly different to Bayesian phase-estimation protocols [54], where the Heisenberg limit that applies to most general adaptive protocols [55] can be attained by resorting only to measurements being adaptively varied in between the phase-encoding channel uses [56]. In contrast, in equilibrium thermometry the form of probe states (Gibbs) and measurement (energy-basis) is fixed, and it is the probe Hamiltonian that must be adaptively adjusted for the quadratic scaling to become reachable.

While here we considered the total number of probes  $N$  as our resource, future works could include time as an extra resource. This naturally leads to non-equilibrium thermometry, where the probe is measured before reaching thermalization. While considerable progress in this framework has been obtained within the frequentist approach [13,25,37,38,57,58], adaptive protocols could be developed following the Bayesian approach pursued here. Lastly, exploiting adaptive schemes for other metrological tasks involving criticality and quantum phase transitions [59], or restrictions such as limited measurement resolution [17,18,60], can be a subject of future work.

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