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ENHANCED FUNCTIONALITY OF CANTILEVER BASED MASS SENSORS USING HIGHER MODES AND FUNCTIONALIZED PARTICLES

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ABSTRACT
By positioning a single gold-particle at different locations along the length axis on a cantilever based mass sensor, we have investigated the effect of mass position on the mass responsivity and compared the results to simulations. A significant improvement in quality factor and responsivity was achieved by operating the cantilever in the 4th bending mode thereby increasing the intrinsic sensitivity. It is shown that the use of higher bending modes grants a spatial resolution and thereby enhances the functionality of the cantilever based mass sensor.

Keywords: Cantilever, Sensor, Sensitivity, Modes

INTRODUCTION
The demand for sensors with high sensitivity, improved functionality and reduced analyte usage as well as the demand for portable devices is driving the development of sensors from the micro- to the nano-regime. Cantilever based sensors have been a part of this development since the method was proposed by Chen et. al [1] in 1995. Today cantilevers are used widely in sensor applications in the static mode where a reaction on the surface creates surface stress which in turn causes a bending of the cantilever [2-3]. Also, the use of vibrating cantilevers shows great promises for sensor applications and recently systems capable of detecting masses in the 10^-10 g range have been reported [4-5]. Here we report on the investigation of cantilever sensitivity using a movable point-mass, and experimental results are compared with simulations.

The resonant frequencies for a cantilever are given by

\[ f_n = \frac{\omega_n}{2\pi} = \left( \frac{2\pi}{\omega_n} \right)^2 \sqrt{\frac{1}{m_n^*}} \]  

(1)

where \( m_n^* \) is the effective mass of the \( n \)th mode of vibration. The higher the mode of vibration the smaller the effective mass due to the increasing number of nodal points. Schematics of the first four bending modes are shown in fig. 1. It is seen that certain regions of the cantilever do not take part in the vibration and the positions of these are changing with the mode of vibration. The resonant frequency change caused by added mass therefore depends on the mass position.

This has previously been investigated theoretically on the macroscopic scale [6-8]. The sensitivity of cantilever based mass sensors has been investigated by several groups [9-10] and the terminology used here is adopted from the work of Ekinci et al. [10]. The mass responsivity is \( R \approx 2\pi m^*/2m \), and the intrinsic sensitivity is \( \delta m_c \approx R^{-1} \sqrt{1/\omega Q} \) (assuming the energy in the cantilever is constant).

As an alternative to use the entire cantilever surface for molecular adsorption we propose to use only certain areas of the cantilever and positioning these for optimum sensitivity. We investigate the concept by adding a point-mass to a micro cantilever. By moving this point-mass in small steps along the length direction of the cantilever, and simultaneously determining the resonant frequency for several bending modes, we can locate the positions yielding high mass responsivity. The experimental data is compared to simulations performed using finite element software.

EXPERIMENT

The experimental setup (fig. 2) consists of a HeNe laser, which is focused on a micrometer sized cantilever. The cantilever-chip is clamped on top of a piezo actuator which is driven by a HP4194A gain/phase analyzer and placed in a custom built vacuum chamber capable of maintaining a vacuum of 0.5 mbar at which all experiments are performed. The position of the reflected beam is registered by a photo-
the SOz cantilevers.

The cantilever used in the experiment is fabricated in SiO2 and subsequently coated on the topside with 10 nm Ti and 100nm Au (the fabrication process is described in [11]). The cantilever dimensions are measured in a SEM yielding a length, width and thickness of approximately 153 µm, 11 µm and 1.05 µm respectively. A rather large cantilever with a large surface area was chosen because it facilitates easy manipulation of particles on the cantilever surface and it gives high resolution in the length direction. The metal coating was used to improve the reflectivity of the SiO2 cantilevers.

The cantilever structure on which simulations are performed using the finite element software, CoventorWare, is shown in fig. 3b. The simulated cantilever has the same dimensions as the cantilever used in the experiment and is also metal coated. The density (ρ) and Young’s (E) modulus for the simulated materials are ρ=2150 kg/m³ and E=70 GPa (SiO2), ρ=4500 kg/m³ and E=110 GPa (Ti) and ρ=19300 kg/m³ and E=57 GPa (Au). The mesh generated for the calculations consists of bricks which are 1 µm in the length direction of the cantilever.

The resonant frequency (f_w) of the first four bending modes of the micro-cantilever is measured before the gold-bead is positioned on the cantilever. The results are shown in Table I together with the simulated peaks are shown for clarity.

A single gold-bead with a radius of 0.9 µm, corresponding to a mass of approximately 60 pg, is positioned on the cantilever (fig. 3a) using a manipulation setup based on a high resolution optical Navitar microscope: A Newport XYZ stage is used for cantilever positioning, while an etched tungsten tip with a tip diameter of roughly 1 µm mounted on a Burleigh PCS-5400 piezo-micromanipulator is used for manipulating the gold-bead. The position of the gold bead is determined from optical images with an estimated accuracy of ±1 µm. After positioning of the gold-bead the resonant frequency of the cantilever is measured, and the bead is pushed with the tungsten tip to a new location where the resonant frequency is measured again.

The resonant frequency (f_w) of the first four bending modes of the micro-cantilever is measured before the gold-bead is positioned on the cantilever. The results are shown in Table I together with the simulated

RESULTS AND DISCUSSION

The resonant frequency (f_w) of the first four bending modes of the micro-cantilever is measured before the gold-bead is positioned on the cantilever. The results are shown in Table I together with the simulated
Table 1 The resonant frequency measured and simulated for the first four bending modes of the cantilever together with the experimentally observed maximum change in frequency and relative sensitivity for the specific mode.

<table>
<thead>
<tr>
<th>Mode</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>4</th>
</tr>
</thead>
<tbody>
<tr>
<td>$f_{exp}$(Hz)</td>
<td>30712</td>
<td>192493</td>
<td>539060</td>
<td>1056640</td>
</tr>
<tr>
<td>$f_{sim}$(Hz)</td>
<td>31734</td>
<td>198815</td>
<td>556486</td>
<td>1089920</td>
</tr>
<tr>
<td>$\Delta f_{max}$(Hz)</td>
<td>480</td>
<td>2541</td>
<td>6059</td>
<td>9864</td>
</tr>
<tr>
<td>$\delta m / \delta m_0$</td>
<td>1</td>
<td>23</td>
<td>102</td>
<td>276</td>
</tr>
</tbody>
</table>

The resonant frequencies ($f_{sim}$). The simulated resonant frequencies are within 3.5% of the experimental values for all the measured bending modes.

When adding the single gold-bead to the tip of the cantilever the resonant frequency of all four modes decrease as expected from equation 1. Typical examples of the recorded amplitude resonance peaks are depicted in fig. 4. These particular resonant peaks are taken from the 2<sup>nd</sup> bending mode, and the numbering of the peaks refers to the position of the gold-bead on the cantilever (fig. 1). The fitted peaks of the first four bending modes all have an average standard deviation of less than 0.01%, and the standard deviation of successive experiments with no movement of the bead is within this limit. From measurements at all positions an average Q-factor was calculated for each mode (fig. 4). The Q-factor increases almost a factor of 3 going from the first to the second bending mode and the 4<sup>th</sup> mode has a Q-factor that is more than 5 times larger than the 1<sup>st</sup> mode. There is no significant difference between the Q-factor of the loaded and unloaded cantilever.

The change in resonance frequency for the first four bending modes of the cantilever as a function of particle position along the length axis has been recorded. The experimentally observed relative change in resonance is compared to the values obtained by simulations and excellent agreement is obtained for all bending modes (fig. 5). For all modes the highest change in frequency ($\Delta f_{max}$) is obtained when the gold-bead is positioned at the tip of the cantilever (experimental values listed in Table 1). The absolute change in frequency and thereby the responsibility increases with the mode number giving a mass responsivity of ~5 fg/Hz in the 4<sup>th</sup> mode for the added mass of 60 pg. The relative sensitivities $\delta m / \delta m_0$ have been calculated (Table 1), and the sensitivity is seen to increase by a factor of ~300 using the 4<sup>th</sup> mode.

The highest measured resonance mode results in the best mass responsibility of the cantilever and corresponds to our theoretical predictions. The large increase in sensitivity with increasing bending modes is mainly owed to a decrease in the effective mass (eq. 1), but also to the increase in Q-factor. The rather low Q-factor observed for the cantilevers are due to the metal coating [12], and similar uncoated cantilevers have Q-factors that are 10 times higher. The increasing Q-factor has previously been observed [13-14] and is likely due to the smaller centre of mass movement and smaller radiation at the support for increasing bending modes [15].

**CONCLUSION**

In conclusion, a mass responsivity of approximately 5 fg/Hz has been observed for a micrometer sized cantilever when operating the cantilever in the 4<sup>th</sup> mode. The increase in Q-factor and resonant frequency as well as the decrease in effective mass makes the intrinsic sensitivity of the cantilever significantly better for increasing mode numbers (~300 for the 4<sup>th</sup> mode). This implies that a 300 times smaller mass can be detected in the 4<sup>th</sup> mode compared to the 1<sup>st</sup>, assuming the cantilever is the dominant source of noise. To fully utilize the capabilities of a cantilever based mass sensor it is therefore important to operate it at higher modes.

The experimentally observed changes in resonant frequency when adding a point mass show excellent agreement with the simulations for the first four bending modes. From the measurements it follows that a single cantilever operated in the 4<sup>th</sup> mode has four positions for high sensitivity mass sensing. The number

**Fig. 5 Measured shift in resonance as a function of position compared to the simulated values shown for the first four bending modes of vibration.**
of sensitive positions can be further increased by operating at even higher modes.

The method presented can be used for enhancing the performance compared to conventional cantilever based mass sensors since the Q-factor degrading gold coating of the entire cantilever can be avoided. Using higher bending modes for detection it is possible to achieve a significant increase in the intrinsic sensitivity compared to the fundamental bending mode and moreover the method in principle grants a spatial resolution to the cantilever based mass sensor. By measuring different modes of vibration it should be possible to locate the position of the added mass on the cantilever. One possible application could be to detect more than one specific molecule using a single cantilever, by position several particles or coated areas functionalyzed for recognition of different molecules individually on the cantilever.

References