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Optimal Design of DC Fast-Charging Stations for EVs in Low Voltage Grids

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Abstract— DC Fast Charging Station (DCFCS) is essential for widespread use of Electric Vehicle (EVs). It can recharge EVs in direct current in a short period of time. In recent years, the increasing penetration of EVs and their charging systems are going through a series of changes. This paper addresses the design of a new DCFCS for EVs coupled with a local Battery Energy Storage (BES). DCFCS is equipped with a bidirectional AC/DC converter for feeding power back to the grid, two lithium batteries and a DC/DC converter. This paper proposes an optimal size of the BES to reduce the negative impacts on the power grid through the application of electrical storage systems within the DC fast charging stations. The proposed solution decreases the charging time and the impact on the low voltage (LV) grid significantly. The charger can be used as a multifunctional grid-utility such as congestion management and load levelling. Finally, an optimal design of the DCFSC has been done to evaluate the feasibility and the operability of the system in different EVs load conditions.

Keywords— DC fast charging station, battery energy storage, electric vehicle.

I. INTRODUCTION

European cities are increasing driving restrictions on gasoline vehicles and replacing them with electric vehicles (EVs) as a responsible alternative to reduce the CO2 emissions. Many factors are contributing to the spread of electric transportation, and the sector is starting to benefit from incentives given by individual governments and European Commission [1]. Considering the growing number of EVs, it seems necessary to establish a smart DC fast charging infrastructure to provide their required energy demand in a short period of time. The EN/IEC 61851 and automotive engineers in U.S. SAE J1772 have proposed their standards on the charging modes for EVs and the maximum current delivered in DC [2]. According to the international standards, there are different charging modes classified as mode 1, 2, 3 and 4 for the EV conductive charging system. IEC 61851 applies to on-board and off-board equipment for charging electric vehicles and providing electrical power for any additional services on the vehicle if required when connected to the electrical grid. One method for EV charging is to connect the AC supply network to an on-board charger, the power delivered is between 7 kW and 43 kW [3]. The charging rate requires about 2-3 hours to store the energy needed to cover 150km. Another method to recharge EVs is to use an off-board charger for delivering direct current to recharging in a short period of time. In addition the charging facilities operating at high power levels. Currently, the delivered power in DC is between 50 kW and 120 kW for public charging stations with a charging rate about 45 min and 30 min to store energy for 150km of driving. The fast charging station has met implementation difficulties in the major European cities, because its progress poses demanding requirements in terms of EV battery and charging rate restrictions. In addition, there are many issues related to the impact of the DC fast charging on the distribution network in the low voltage (LV), such as control the congestion during the peak hours and the high losses among the feeders [4]. The widespread use of EVs and especially the installations of the fast charger requires investigating on the distribution grid impact. So far, many studies have been done about the EVs and their grid impact.

To address this issue, research is moving in various directions, for example in some papers, a coordinated charging system is proposed to minimize the power losses and maximize the main grid load force for an optimal charging profile for EVs and plug-in hybrid electric vehicles (PHEVs) [5]. To mitigate the congestion form EVs, other studies have proposed dynamic price for the uses to keep the reliability of the electrical grid [6]. N.G. Paterakis has developed a detailed energy management system structured for unpredictable load such as EVs and PHEVs. He has determined the optimal day-ahead appliance scheduling of a smart-load based hourly pricing and peak power limiting based on a demand response strategies [7]. Other authors have focused their studies on the impact of the charging stations based on simulation models. The models determine the spatial distribution of different charging stations to evaluate the potential for load shifting EVs demand [8]. Although the DC fast charging station has a deep impact on the grid and at the moment few researcher are working to determine the fast charging stations’ demand.

It is very important to design an appropriate fast charging station for EVs, which is able to meet the expected demand. Designing an appropriate charging station in LV grid requires not only meeting the charging demand at any time of the day, but also minimizing the station operation costs [9]. Especially, in LV grid where the operators are focused to minimized the losses and to reduce the size of the electrical lines and avoid the network congestion. The load curve profile of the DC fast-charging station can increases significantly the peak load demand as well as high connection fees to grid operators in order to offset the cost of larger transformers and electrical equipment.

Some recent studies have focused on using battery energy storage as a buffer between the grid and the charging stations in
order to reduce their peak consumption [10], but more work is required on the optimal size of BES in the station. In this paper, the authors attempt to determine the optimal design of the DC fast charging station to reduce their grids impact. In particular, we propose a new design of a stationary battery energy system that physically decouples a DC fast charging from an LV distribution.

The rest of the manuscript is organized as follows. In Section II conductive charging modes and in the Section III charging station design and demand modelling. Section IV the description of the optimal design of the BES is given in Section IV and V, respectively with the simulation results. Finally, in Section VI the conclusions with the optimal size of the BES within the DC fast-charging stations and its practical implementation in LV grids.

II. CONDUCTIVE CHARGING MODES IEC61851

According to IEC 61851 there are four charging modes classified as mode 1, 2, 3 and 4 [3] for EV conductive charging. IEC 61851 applies to on-board and off-board equipment for charging electric vehicles and providing electrical power for any additional services on the vehicle if required when connected to the electrical grid. One method for charging EVs is to connect the AC supply network to an on-board charger. An alternative method is to use an off-board charger for delivering direct current, for charging in a short period of time. Special charging spots are operating at high power levels by using medium voltage (MV). The EV charging modes are the following: Charging Mode 1: homes and offices, Charging Mode 2: private facilities. Charging Mode 3: public charging stations. Charging Mode 4: public charging stations. The mode 4 has been implemented for the AC/DC charging by the use of off-board chargers. Typical at the moment the charging time of the mode 4 is from 50 to 30 minutes to reach 80% of battery SoC with a power between 50 and 120kW. Figure 1 summarizes the main characteristics of the charging modes with their respective powers according to IEC 61851 and IEC 62196 [2]-[3]. The IEC 62196 applies to plugs, socket-outlets, and connectors which use conductive charging.

![Figure 1. DC - Fast charging station in mode 1, 2, 3 and 4](image)

In the European cities, the charging systems most used at the moment are mode 2 and mode 3, for the following reasons: low infrastructure costs, electrical grid and international standards availability. The AC charging architecture is robust, but it has power limitations of 43kW. Furthermore, recharging in AC entails high conversion losses on the EV side. The efficiency of an on-board converter is around 85% and this represents an increasing energy demand from the EV in order to reach 80% of SoC. In mode 3 the charging rate to reach 80% of the EV battery with 22kW takes approximately 1 hour with a vehicle of 20kWh. To solve the problem of the low range, the major car manufacturers are increasing the battery pack of the new models form 20/25kWh to 40/60kWh such as Tesla model 3 and eGolf. Therefore charging in AC will represent an issue for the long charging time and in particular space congestion of the public parking. Recently, some company are starting to develop new fast charging systems in DC because the standard allows charging with 400A and maximum power of 240kW in Chademo and Combined Charging System (Combo). The state of art at the moment is the following: 120kW by Tesla connected in MV (outside the cities), 50kW by ABB with combo in LV (inside the cities), 62.5kW by Chademo system in LV (inside the cities), 150kW ABB with combo in MV (outside the cities). Mode 4 significantly reduces the charging time and the conversion losses on the EV side.

III. CHARGING STATION DESIGN AND DEMAND MODELLING IN LV GEIDS

Two DC charging stations of 240kW might require the connection in MV with a high investment costs Figure 2. The new dedicated line and the transformer have high economic costs and space restrictions, especially if the installation takes place in the cities [9].

![Figure 2. New connection in MV for DC-fast charging stations](image)
The DCFCS in combination with the BES can represent a reliable solution to avoid the connection in MV especially within residential areas. The annual cost reduction of BEVs has been estimated around 8% [11]-[12]. This represents a chance to evaluate possible scenarios of the DCFCS in order to develop a smart charging station and control methods for these flexible loads [13].

In addition, DCFCS with the BESs gives the opportunity to the users to recharge the EVs up to 80% of their SOC with charging rate of 9-10 minutes. The new design of the charging stations is based on the installation of two identical battery energy system (BES1 and BES2) that physically decouples a DC fast charging station (DCFCS) from an LV distribution grid, as shown in Figure 4.

The operation of such a system is based on successive switches of the BES connections that allow one of the batteries (BES2) to be charged from the grid while the other (BES1) is charging an EV, as shown in Figure 5.

IV. OPTIMAL DESIGN OF BESs IN FUNCTION OF CHARGING DEMAND

The charging station will have one or more charging slots, and each of them can be connected in the LV grid with a minimum power of 100kW required form the grid in AC. Every EV has a nominal capacity given by the manufacturers that represents an amount of kilometres that the car can reach with specific driving conditions. According to the tests performed in the EV laboratory, only 90% of the nominal capacity is used as work capacity. To make the EV demand study more realistic, the following steps are made: SoC of the EV battery is fixed at 25% SoC (worst case). The EVs load demand capacity is between: 7.2 kWh and 36kW, Table 1:

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Mitsubishi i-MiEV</td>
<td>100</td>
<td>16</td>
<td>14.4</td>
<td>3.6</td>
<td>10.8</td>
<td>7.2</td>
</tr>
<tr>
<td>Smart Electric</td>
<td>110</td>
<td>17</td>
<td>15.3</td>
<td>3.8</td>
<td>11.5</td>
<td>7.7</td>
</tr>
<tr>
<td>Chevy Spark EV</td>
<td>130</td>
<td>20</td>
<td>18</td>
<td>4.5</td>
<td>13.5</td>
<td>9</td>
</tr>
<tr>
<td>BMW i3</td>
<td>130</td>
<td>22</td>
<td>19.8</td>
<td>4.95</td>
<td>14.9</td>
<td>10</td>
</tr>
<tr>
<td>Ford Focus EV</td>
<td>130</td>
<td>23</td>
<td>20.7</td>
<td>5.17</td>
<td>15.5</td>
<td>10.33</td>
</tr>
<tr>
<td>Fiat 500e</td>
<td>140</td>
<td>24</td>
<td>21.6</td>
<td>5.4</td>
<td>16.2</td>
<td>10.8</td>
</tr>
<tr>
<td>Leaf 24kWh</td>
<td>130</td>
<td>24</td>
<td>21.6</td>
<td>5.4</td>
<td>16.2</td>
<td>10.8</td>
</tr>
<tr>
<td>Leaf 30kWh</td>
<td>165</td>
<td>30</td>
<td>27</td>
<td>6.75</td>
<td>20.3</td>
<td>13.55</td>
</tr>
<tr>
<td>Kia Soul EV</td>
<td>150</td>
<td>30</td>
<td>27</td>
<td>6.75</td>
<td>20.3</td>
<td>13.55</td>
</tr>
<tr>
<td>Mercedes BClassEV</td>
<td>170</td>
<td>36</td>
<td>32.4</td>
<td>8.1</td>
<td>24.3</td>
<td>16.2</td>
</tr>
<tr>
<td>VW eGolf</td>
<td>300</td>
<td>37</td>
<td>33.3</td>
<td>8.3</td>
<td>25</td>
<td>16.7</td>
</tr>
<tr>
<td>Tesla S 60</td>
<td>340</td>
<td>60</td>
<td>54</td>
<td>13.5</td>
<td>40.5</td>
<td>27</td>
</tr>
<tr>
<td>Tesla model 3</td>
<td>350</td>
<td>60</td>
<td>54</td>
<td>13.5</td>
<td>40.5</td>
<td>27</td>
</tr>
<tr>
<td>Tesla model S80</td>
<td>450</td>
<td>80</td>
<td>72</td>
<td>18</td>
<td>54</td>
<td>36</td>
</tr>
</tbody>
</table>

The following statistical calculations are carried out to evaluate EVs load demand in different confidence intervals (2):

Sample mean: $\overline{X}_{n} = \frac{1}{n} \sum_{i=1}^{n} X_i = 15.42 \text{kWh}$, with $n=14$

Sample variance: $s_{n}^2 = \frac{1}{n-1} \sum_{i=1}^{n} (X_i - \overline{X}_{n})^2$ (1)
\[ s^2 = \frac{1}{n-1} \sum_{i=1}^{n} (X_i - \overline{X}_n)^2 = \frac{1}{14-1} \sum_{i=1}^{14} (X_i - \overline{X}_{14})^2 = 107.65 \]

and

\[ s = \sqrt{107.75} = 10.375 \]

The confidence interval is 0.95 of \( BES \in X \), with \( n=14 \), the confidence interval is:

\[ BES \subset \left\{ \overline{X}_{14} - \frac{s}{\sqrt{n}} (1 - \frac{a}{2}) (n-1), \overline{X}_{14} + \frac{s}{\sqrt{n}} (1 - \frac{a}{2}) (n-1) \right\} \quad (2) \]

The estimation of the BES size is calculated with this expression and student's \( t \) distribution (3):

\[ F(t) = \int_{-\infty}^{t} \frac{\Gamma((n+1)/2)}{\Gamma(n/2)\sqrt{n\pi(1 + \frac{x^2}{n})^{(n+1)/2}}} \, dx = (t(0.975))^{13} = 2.16 \]

\[ \alpha = 0.05, \, t \rightarrow t(1 - \frac{a}{2}) = t(0.975) = 2.16 \]

\[ BES \subset \left\{ \overline{X}_{14} - \frac{s}{\sqrt{n}} (1 - \frac{a}{2}) (n-1), \overline{X}_{14} + \frac{s}{\sqrt{n}} (1 - \frac{a}{2}) (n-1) \right\} \]

\[ BES \subset \left\{ 15.42 - \frac{10.375}{\sqrt{15}} 2.16, 15.42 + \frac{10.375}{\sqrt{15}} 2.16 \right\} \]

\[ \{9.634, 21.2\} \text{ kWh} \]

If the confidence interval is 0.99 of \( BES \in X \) with \( n=14 \), the confidence interval is (4):

\[ BES \subset \left\{ 15.42 - \frac{10.375}{\sqrt{15}} 3.012, 15.42 + \frac{10.375}{\sqrt{15}} 3.012 \right\} \quad (4) \]

\[ \{7.35, 23.5\} \text{ kWh} \]

To satisfy the energy demand from EVs, the optimal BES for an DCFCS is 16kWh because it meets the highest level of SoCs satisfaction. In addition, according to Danish National Transport Survey, the average Danish driving distance is around 29.48km per day, therefore 205 km are sufficient for driving in the city and outside. Each BES has been oversized of 19.2 kWh (Figure 6) because it cannot exceeding 20% SoC for two reasons: overheating issues and faster degradation of the battery.

Table 2 shows the results of different BES and the energy in terms of kilometers provided by the BES. The driving efficiency of the new EVs model between 2020 and 2025 will be around 0.1kWh/km.

<table>
<thead>
<tr>
<th>BES [kWh]</th>
<th>[%] of EVs charged up to 80%</th>
<th>[%] of EVs charged up to 70%</th>
<th>Average [km] with 0.1 kWh/km</th>
<th>Average [km] of EVs with SoC 25%</th>
<th>Total [km]</th>
</tr>
</thead>
<tbody>
<tr>
<td>23.5</td>
<td>78%</td>
<td>93%</td>
<td>235 [kWh]</td>
<td>45 [km]</td>
<td>280</td>
</tr>
<tr>
<td>21.5</td>
<td>78%</td>
<td>93%</td>
<td>215 [kWh]</td>
<td>45 [km]</td>
<td>260</td>
</tr>
<tr>
<td>19.5</td>
<td>78%</td>
<td>78%</td>
<td>195 [kWh]</td>
<td>45 [km]</td>
<td>240</td>
</tr>
<tr>
<td>17.5</td>
<td>78%</td>
<td>78%</td>
<td>175 [kWh]</td>
<td>45 [km]</td>
<td>220</td>
</tr>
<tr>
<td>16</td>
<td>78%</td>
<td>78%</td>
<td>160 [kWh]</td>
<td>45 [km]</td>
<td>205</td>
</tr>
<tr>
<td>15.5</td>
<td>75%</td>
<td>78%</td>
<td>155 [kWh]</td>
<td>45 [km]</td>
<td>200</td>
</tr>
<tr>
<td>15</td>
<td>65%</td>
<td>78%</td>
<td>150 [kWh]</td>
<td>45 [km]</td>
<td>195</td>
</tr>
<tr>
<td>13.5</td>
<td>50%</td>
<td>78%</td>
<td>135 [kWh]</td>
<td>45 [km]</td>
<td>180</td>
</tr>
<tr>
<td>11.5</td>
<td>50%</td>
<td>64%</td>
<td>115 [kWh]</td>
<td>45 [km]</td>
<td>160</td>
</tr>
<tr>
<td>9.5</td>
<td>22%</td>
<td>50%</td>
<td>95 [kWh]</td>
<td>45 [km]</td>
<td>140</td>
</tr>
</tbody>
</table>

In this case study there are two criteria to size the BESs: Fist, considering EVs SoC at 80% and to cover 78% of the EVs demand and the BES should be sized around 23.5kWh. Second, it is important to take into account the number of kilometers needed for driving in the city instead of their SoC at 80%.
The case study uses an AD/DC converter of 100kW and charging rate of 6C (9.7min). The discharging rate through the DC/DC is 9C (6.7min) with a converter of 150kW.

V. SIMULATION RESULTS

The reliability of the system and the performance of the DCFCS are evaluated by a 11-minute simulation in Matlab/Simulink. A boost converter controls the DC/DC converter through the PI controllers. The boost converter helps to keep the voltage limits constant to ensure the stability of the system for each SoC of the EVs.

A. The charging process of the BESs

When the BES2 is charging an EV at 9C, the BES1, if previously discharged, can be recharged through the grid with the AC/DC converter at 100kW and a charging rate of 6C as shown in Figure 5.

B. The charging process of an EV

The graph in Figure 6 shows the charging process of an EV through BES2 and the power absorbed by the electric vehicle. As previously mentioned, the DCFCS has been designed to be used in LV grids, mainly in the cities. It can recharge each vehicle up to 80% of their SoC in a time period of between 6 minutes and 7 minutes, depending on the SoC of each EV. The functionality of the charging system has been evaluated on a large scale by comparing different commercial EVs with different batteries. The case studies take into account several models from 2015 to 2017 with battery pack between 16 kWh and 80 kWh. As shown in table 1 below. All the EVs could be charged by the DCFCS with 150 kW through the BESs. The results associated with the capability of the DCFCS and its limits in order to supply energy to the end users is shown in Figure 5.

C. Capability of the DCFCS

Figure 9 represents the charging limit of the DCFCS and the capability to recharge EVs up to 80% in function of their SoCs and battery packs. The DCFCS can provide to recharge EVs at 80% of SoC with maximum EVs battery pack of 40kWh. For large EVs battery pack such as Tesla models of 60/80kWh, EV-Van and EV-suv, the DCFCS can recharger them fast up to 50/60% their SoC with more then 250km of driving. If the users need more driving kilometers or they want to reach 80% of the SoC with 450 - 500km the EVs could be recharge twice with a charging time around 20min.
VI. CONCLUSIONS

This paper introduced an optimal size of the BES within the DC-fast charging stations with the objective of decoupling the LV grid from the peak load demand from EVs.

The research activities have shown that the DCFCS could be decoupled from the LV grid with the goal of minimizing the connection costs of the grid by using the BESs. In addition, the advantage of this charging station is to reduce the charging time and grid impact during the peak demand. Results show the following main conclusions:

1. The grid impact of the DCFCS grows with the EV market penetration and the integration of the BESs will avoid the connection costs in MV especially within residential areas.
2. The load levelling control by the installation of intermediate battery helps to reduce the power from the grid connection at 34%.
3. The DCFCS provides the possibility of more than 200km driving in less than 10 minutes. It means maximize the user satisfaction minimize the costs form the DCFCS-operators for the public parking lots.
4. The optimal size of the BES will depend from: grid constraint, charging time, SoC satisfaction and EV battery packs.
5. This paper did not take into account optimal storage solution in terms of: lifetime, costs and volumes for the DCFCS. A possible solution could be to use the second life batteries for ancillary services such as primary frequency control or voltage support by using the bidirectional AC/DC converter.

To conclude, an optimal control of the DC/DC has to be implemented with a coordinated strategy to estimate periodically the EVs SoC and the load demand. The IEC 61851 and IEC15118 define the general requirements for the control communication between the DC-charger and the EVs, which could provide the charging/discharging process of the BESs. As a future consideration and thanks to a coordinated control strategy of the BESs, we will propose a DC fast-charging station capable of recharging a large number of EVs fast in LV grids by using load demand prediction in function of EVs SoC.

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