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Outdoor luminescence imaging strategies for drone-based PV array inspection

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Regular fault detection for effective maintenance is highly important to ensure expected return on investment (ROI) of small and large-scale photovoltaic (PV) installations. Present day PV panels are designed to operate for 25-30 years, however field experience shows that after 11-12 years of operation, 2% or more of all PV panels fail [1].

In practice, the frequency and inspection detail level is often limited by manpower and cost. Presently, drone-based infrared (IR) thermography inspection of solar plants is a reality [2], [3]. The accuracy of thermographic fault detection though, presents limitations – primarily related to deconvoluting the failure signature into failure type and severity, which can be overcome when performed in combination to electro-(EL) or photo-(PL) luminescence imaging of the panels. The combination of defect detection techniques has been already tested in laboratory [1], [4], although many limitations still need to be addressed in order to obtain image acquisition outdoors and integrate, automate and optimize the imaging system in a drone. The concept of PL/EL in a drone is illustrated in Fig. 1.

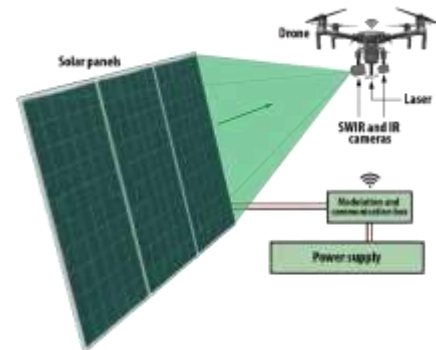


Fig. 1. Concept of automated drone inspection.

In this work, we present the results corresponding to the development of two luminescence-imaging strategies for PV modules defect detection in outdoor conditions, with the aim of choosing the most suitable method for implementation on a drone-based PV plant inspection system.

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