Delta-Connected Cascaded H-Bridge Multilevel Converters for Large-Scale Photovoltaic Grid Integration

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Abstract—The cascaded H-bridge (CHB) converter is becoming a promising candidate for use in next generation large-scale photovoltaic (PV) power plants. However, solar power generation in the three converter phases can be significantly unbalanced, especially in a large geographically-dispersed plant. The power imbalance between the three phases defines a limit for the injection of balanced three-phase currents to the grid. This paper quantifies the performance of, and experimentally confirms, the recently proposed delta-connected CHB converter for PV applications as an alternative configuration for large-scale PV power plants. The required voltage and current overrating for the converter is analytically developed and compared against the star-connected counterpart. It is shown that the delta-connected CHB converter extends the balancing capabilities of the star-connected CHB and can accommodate most imbalance cases with relatively small overrating. Experimental results from a laboratory prototype are provided to validate the operation of the delta-connected CHB converter under various power imbalance cases.

Index Terms—ac-dc power converters, cascaded H-bridge converter, multilevel converter, photovoltaics.

I. INTRODUCTION

The cascaded H-Bridge (CHB) converter is considered one of the most suitable configurations to be used in next-generation large-scale photovoltaic (PV) power plants, attracting significant research interest both from the technical and financial perspective [1]–[22]. With multilevel waveform synthesis, the switching frequency at the device level can be greatly reduced while the converter still achieves excellent harmonic performance [23]. Multiple H-bridges cascaded in series also enable the converter to be directly connected to medium-voltage (MV) grids without the presence of a bulky and lossy line-frequency transformer. In addition, each H-bridge also operates at low voltage, which effectively reduces PV module mismatch loss [14], [15].

In applications where the CHB converter has achieved commercial success, such as Variable Speed Drives (VSDs) and Static Synchronous Compensators (STATCOMs) [24]–[28], the active or reactive power processed by all of the
PV recently proposed delta-connected CHB converter for large-scale PV applications (Section II), its control implementation (Section III) and the analytical derivation of its power balancing capabilities also in comparison with the star-connected topology (Section IV). Detailed experimental results under various power imbalance cases are presented in Section V to demonstrate and verify the delta-CHB converter and its power balancing capabilities.

II. DELTA-CONNECTED CHB CONVERTER FOR PV APPLICATIONS

Fig. 1 illustrates the layout of a three-phase, \((2N + 1)\)-level, delta-connected CHB converter for large-scale PV plants. As with a star-connected converter [14]–[18], each phase consists of \(N\) bridges, each of which is fed by multiple PV strings via independent dc-dc converters. Galvanic isolation can be provided in the dc-dc conversion stage (high-frequency transformers are typically preferred) to isolate PV modules from the grid, because most commercial PV modules are designed to bear less than 1000 V between the active part of the module and the grounded frame [29], although general consensus on the optimal topology does not exist. Under balanced PV generation, the delta connection requires a greater number of bridges cascaded in series than the star connection, to reach the line-to-line grid voltage, thus inevitably increasing the size of the converter.

During balanced operation, the power generation level of each of the three phases is equal to the other two. The three-phase line currents delivered to the grid (\(I_{ga}, I_{gb}, I_{gc}\) in Fig. 2) are balanced with a unity power factor; so are the three-phase phase-leg currents (\(I_{gb}, I_{cb}, I_{ca}\)). The converter is modulated to generate voltage vectors \(V_{ab}, V_{bc}, V_{ca}\), which are also symmetrical.

However, when power generation levels of the three phases become unequal, the three-phase line currents are no longer balanced. To overcome this issue, a zero-sequence current can be used to re-balance the line currents. Fig. 2b shows the phasor diagram for unbalanced power generation. The injected zero-sequence current vector \(I^0\) contributes to the power transfer among the three phases. For the case illustrated in Fig. 2b, \(I^0\) helps transfer the excessive power in phase \(ab\) to phases \(bc\) and \(ca\). Since the zero-sequence current only flows within the delta, the three-phase line currents are still balanced. Therefore, viewed from the grid side, the converter produces three-phase balanced line currents, just like the case of equal power generation.

The power generation ratios (\(\lambda_{ab}, \lambda_{bc}, \lambda_{ca}\)) are defined to reflect the actual power generation levels in the three phases [16]:

\[
\lambda_i = \frac{P_i}{P_{\text{nom}}^3}, \quad i \in \{ab, bc, ca\},
\]

where \(P_{\text{nom}}\) denotes the three-phase nominal power.

Assuming a delta connections, the three-phase grid voltages (line-to-line) can be defined as:

\[
v_{gab} = \sqrt{2}V_g \cos (\omega t + \pi/6),
\]

\[
v_{gbc} = \sqrt{2}V_g \cos (\omega t - \pi/2),
\]

\[
v_{gca} = \sqrt{2}V_g \cos (\omega t + 5 \pi/6),
\]
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When the power generation becomes unbalanced, the active power imbalance becomes severe, the amplitude of the zero-sequence voltage becomes larger. The converter creates six sectors in the phasor diagram. These sectors are defined in Table I and illustrated in Fig. 2b, which also shows an imbalance case with the zero-sequence vector in Sector I.

The phasor diagram is divided into six sectors according to the relationship between the three-phase power generation ratios, as in Fig. 2b and Table I.

For the star connection, the resultant converter output voltage of each phase consists of i) the grid voltage, ii) the inductor voltage, and iii) the zero-sequence voltage. When the inter-phase power imbalance becomes severe, the amplitude of the zero-sequence voltage becomes larger. The converter may reach saturation and grid currents would then become unbalanced and distorted. Therefore, voltage overrating is required by connecting more H-bridges in series to increase the available dc voltage.

However, the scenario in the delta connection is different. The phase-leg current consists of a positive-sequence current required by connecting more H-bridges in series to increase the inter-phase power imbalance becomes severe, the amplitude of the zero-sequence voltage becomes larger. The converter may reach saturation and grid currents would then become unbalanced and distorted. Therefore, voltage overrating is required by connecting more H-bridges in series to increase the available dc voltage.

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TABLE I

<table>
<thead>
<tr>
<th>Power Generation Ratios</th>
<th>Sector</th>
</tr>
</thead>
<tbody>
<tr>
<td>( \lambda_{bc} &lt; \lambda_{ca} &lt; \lambda_{ab} )</td>
<td>(I)</td>
</tr>
<tr>
<td>( \lambda_{bc} &lt; \lambda_{ab} &lt; \lambda_{ca} )</td>
<td>(II)</td>
</tr>
<tr>
<td>( \lambda_{ab} &lt; \lambda_{bc} &lt; \lambda_{ca} )</td>
<td>(III)</td>
</tr>
<tr>
<td>( \lambda_{ab} &lt; \lambda_{ca} &lt; \lambda_{bc} )</td>
<td>(IV)</td>
</tr>
<tr>
<td>( \lambda_{ca} &lt; \lambda_{ab} &lt; \lambda_{bc} )</td>
<td>(V)</td>
</tr>
<tr>
<td>( \lambda_{ca} &lt; \lambda_{bc} &lt; \lambda_{ab} )</td>
<td>(VI)</td>
</tr>
</tbody>
</table>

By simultaneously solving (5), the zero-sequence current required to balance the phase-leg power levels can be calculated as:

\[
I^0 = \frac{\sqrt{2}\Delta P_{nom}}{9V_g},
\]

\[
\begin{align*}
\theta_\Delta &= \begin{cases}
\pi/6 + \sin^{-1} \left( \frac{\sqrt{6}(\lambda_{ca} - \lambda_{bc})}{2\Gamma_\Delta} \right) & \text{Sectors (I), (VI)} \\
5\pi/6 + \sin^{-1} \left( \frac{\sqrt{6}(\lambda_{bc} - \lambda_{ab})}{2\Gamma_\Delta} \right) & \text{Sectors (II), (III)} \\
3\pi/2 + \sin^{-1} \left( \frac{\sqrt{6}(\lambda_{ab} - \lambda_{ca})}{2\Gamma_\Delta} \right) & \text{Sectors (IV), (V)}
\end{cases}
\end{align*}
\]

where \( \Gamma_\Delta = \sqrt{(\lambda_{ab} - \lambda_{bc})^2 + (\lambda_{bc} - \lambda_{ca})^2 + (\lambda_{ca} - \lambda_{ab})^2} \).

The location of the zero-sequence vector depends on the relation between the three-phase power generation ratios which creates six sectors in the phasor diagram. These sectors are defined in Table I and illustrated in Fig. 2b, which also shows an imbalance case with the zero-sequence vector in Sector I.

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However, the scenario in the delta connection is different. The phase-leg current consists of a positive-sequence current required by connecting more H-bridges in series to increase the inter-phase power imbalance becomes severe, the amplitude of the zero-sequence current is expected to increase. However, the positive-sequence current decreases during this condition, owing to the drop in overall power. The necessary semiconductor overrating to tolerate all possible power imbalance cases is, therefore, reduced [22]. In addition, a temporary over-current (< 5 s), during severe imbalance, can usually be tolerated in industrial converters, whereas any over-voltage is likely to destroy the semiconductors immediately.

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Fig. 3. Controller implementation, (a) Inter-bridge power balance loop with fundamental frequency components and, (b) inter-bridge power balance loop with power flow direction detection.

III. CONTROL IMPLEMENTATION

The operation of CHB converters in PV applications require controllers in order to address both the inter-bridge and the inter-phase imbalance. The controller implementation used in the rest of the paper is described in this section.

A. Inter-bridge power balance loop

The inter-bridge power balance loop (phase \( ab \)) is shown in Fig. 3 [12]–[16], [18]. The loop is formed based on the assumption that power always flows from the converter to the grid (defined as positive power flow). Therefore, the bridge with its dc-side capacitor voltage higher than the average synthesizes a larger share (> 1/N) of the phase output voltage to increase the output power, and vice versa [12]–[18], [28].

Furthermore, when the phase-leg current is low, the inter-bridge power balance loop has poor dynamic performance, because the amount of power exchange is limited by the current magnitude. Therefore, an additional third harmonic zero-sequence current \( i^0 (3\omega) \) is injected to increase the current magnitude. The control method used to inject the third harmonic current is described in the next section.

B. Inter-phase power balance loop

An inter-phase power balance loop generates a fundamental frequency zero-sequence current, which helps maintain three-phase balanced line currents, even with unbalanced three-phase power generation [14]–[18]. The fundamental frequency zero-sequence current reference \( i^0 (\omega) \) (Fig. 4a) is calculated according to power generation levels in the three phases as in (6). A proportional resonant (PR) controller with the resonant gain tuned at \( \omega \) generates a zero-sequence voltage \( v^0 \) to track the reference \( i^0, (\omega) \). The zero-sequence voltage \( v^0 \) is then added to the positive-sequence component \( v^p_{ab}, v^p_{bc}, v^p_{ca} \) to obtain the final converter output voltage references. Please note the zero-sequence voltage in the delta connection is much smaller than that in the star connection [14], [15] because in the delta connection the zero-sequence voltage is only responsible for creating zero-sequence current, rather than driving the inter-phase power exchange.

An additional third harmonic current reference \( i^0 (3\omega) \) is added to the fundamental frequency zero-sequence current reference in Fig. 4a. It does not affect the inter-phase power balance loop, but improves the dynamic performance of inter-bridge power balance loops as mentioned in the previous subsection. An additional resonant gain tuned at \( 3\omega \) is required to track \( i^0 (3\omega) \).

Finally, the decoupled \( dq \) control regulates the positive-sequence component of the phase-leg currents, assuming equal amounts of power are generated by the three phases. The active power reference (Fig. 4b) of each bridge is calculated by comparing the measured dc-side capacitor voltage \( v_{dc(ij)} \) \( i \in \{ ab, bc, ca \}; j \in \{ 1, 2, ..., N \} \) to its command \( v^*_{dc} \). The phase power reference can then be obtained by adding the bridge power references in the phase leg, and the overall power reference by adding the three phase power references.

IV. COMPARISON BETWEEN STAR AND DELTA CONNECTIONS

To deal with inter-phase power imbalance, additional zero-sequence voltage (Y) or current (Δ) must be injected, both of which are expected to increase as the inter-phase power imbalance becomes more severe. As a result, the converter needs to be overrated in terms of voltage or current. This section analytically derives both the required voltage and current...
overrating for the star and delta connections, considering a generalized unbalanced case with non-zero connection inductance. Although the extreme power imbalance associated with worst scenarios in terms of voltage or current overrating may rarely happen in practice, this section calculates the converter rating required to tolerate all possible power imbalance cases.

A. Voltage Overrating (Δ)

The required voltage overrating can be calculated by developing an analytical function of the overrating as a function of the power imbalance and identifying the worst case power imbalance. The per-unit value of the filtering inductor \( L_f \) in the delta connection is defined as:

\[
L_f(p.u.), \Delta = \frac{\omega L_f P_{\text{nom}}}{3V_g^2}.
\]

The required voltage rating during balanced operation (Fig. 2b):

\[
V_{\text{nom}}^\Delta = \sqrt{\sqrt{V_g^2 + V_L^2}},
\]

where \( V_L, \Delta = L_f(p.u.), \Delta V_g \).

Again, the case when the zero-sequence current vector \( I^0 \) is located in Sector I (\( \lambda_{ab} \geq \lambda_{ca} \geq \lambda_{bc} \)) (Fig. 2b) is analyzed. The required voltage rating with the injected zero-sequence current can be derived as:

\[
V_{\text{nom}}^\Delta = \sqrt{\sqrt{V_g^2 + V_L^2}} \left( \frac{\lambda_a + \lambda_b + \lambda_c}{3} V_L, \Delta - \omega L_f I^0 \cos \left( \theta_{\Delta} + \frac{\pi}{6} \right) \right)^{1/2},
\]

with \( I^0 \) and \( \theta_{\Delta} \) of (6).

The required voltage overrating is a function of the power generation ratios

\[
V^\Delta = \sqrt{2} \sqrt{G(\lambda_{ab}, \lambda_{bc}, \lambda_{ca})},
\]

where

\[
G = \left( V_g + \frac{3L_f(p.u.), \Delta V_g^2 I^0 \sin \left( \theta_{\Delta} + \frac{\pi}{6} \right)}{P_{\text{nom}}} \right)^2 + \left( \frac{3L_f(p.u.), \Delta V_g^2}{P_{\text{nom}}} \left( \frac{I_g}{\sqrt{3}} - I^0 \cos \left( \theta_{\Delta} + \frac{\pi}{6} \right) \right) \right)^2.
\]

The partial derivatives of \( G \) with respect to \( \lambda_{ab}, \lambda_{bc} \) and \( \lambda_{ca} \) are then:

\[
\frac{\partial G}{\partial \lambda_{ab}} = \frac{2V_g^2 L_f(p.u.), \Delta}{3} \left( \sqrt{3} + L_f(p.u.), \Delta \left( \lambda_{ab} - \lambda_{bc} \right) \right) > 0,
\]

\[
\frac{\partial G}{\partial \lambda_{bc}} = -\frac{2V_g^2 L_f(p.u.), \Delta}{3} \left( \sqrt{3} + L_f(p.u.), \Delta \left( \lambda_{ab} - \lambda_{bc} \right) \right) < 0,
\]

\[
\frac{\partial G}{\partial \lambda_{ca}} = 2V_g^2 L_f(p.u.), \Delta \lambda_{ca} \geq 0.
\]

Therefore, \( G(\lambda_{ab}, \lambda_{bc}, \lambda_{ca}) \) reaches the maximum value at \( \lambda_{ab} = 1, \lambda_{bc} = 0, \lambda_{ca} = 1 \). The maximum required device voltage rating

\[
\frac{V_{\text{nom}}^\Delta}{V_g} = \sqrt{\frac{3 + 2 \sqrt{3} L_f(p.u.), \Delta + 4 L^2_f(p.u.), \Delta}{3 \left( 1 + L^2_f(p.u.), \Delta \right)}}.
\]

The worst cases are \( (\lambda_{ab}, \lambda_{bc}, \lambda_{ca}) = (1, 1, 0), (1, 0, 1) \) and \( (0, 1, 1) \), which again correspond to two phases generating full power while the third phase produces zero power.

B. Current Overrating (Δ)

Similarly to the previous calculation, the worst case imbalance for the current overrating can be calculated. The required current rating during balanced operation is:

\[
I_{\text{nom}}^\Delta = \sqrt{2} \sqrt{H(\lambda_{ab}, \lambda_{bc}, \lambda_{ca})},
\]

where

\[
H = \left( \frac{I_g}{\sqrt{3}} + I^0 \cos \left( \theta_{\Delta} - \frac{\pi}{6} \right) \right)^2 + \left( I^0 \sin \left( \theta_{\Delta} - \frac{\pi}{6} \right) \right)^2.
\]

The partial derivatives of \( H \) with respect to \( \lambda_{ab}, \lambda_{bc} \) and \( \lambda_{ca} \) are:

\[
\frac{\partial H}{\partial \lambda_{ab}} = \frac{2P_{\text{nom}}^2}{9V_g^2} \lambda_{ab} \geq 0,
\]

\[
\frac{\partial H}{\partial \lambda_{bc}} = \frac{2P_{\text{nom}}^2}{27V_g^2} \left( \lambda_{bc} - \lambda_{ca} \right) \leq 0,
\]

\[
\frac{\partial H}{\partial \lambda_{ca}} = \frac{2P_{\text{nom}}^2}{27V_g^2} \left( \lambda_{ca} - \lambda_{bc} \right) \geq 0.
\]

Therefore, \( H(\lambda_{ab}, \lambda_{bc}, \lambda_{ca}) \) reaches the maximum value at \( \lambda_{ab} = 1, \lambda_{bc} = 0, \lambda_{ca} = 1 \). The maximum required device current rating

\[
\frac{I_{\text{nom}}^\Delta}{V_g} = \frac{2 \sqrt{3} P_{\text{nom}}}{3V_g} = \frac{2 \sqrt{3}}{3} \approx 1.155.
\]

The worst cases are \( (\lambda_{ab}, \lambda_{bc}, \lambda_{ca}) = (1, 1, 0), (1, 0, 1) \) and \( (0, 1, 1) \), which again correspond to two phases generating full power while the third phase produces zero power.
C. Voltage overrating (Y)

A similar analysis can be developed for the star-connected CHB converter, assuming operation in Sector I. The per-unit value of the filtering inductor \( L_f \) is:

\[
L_f(p.u., Y) = \frac{\omega L_f P_{nom}}{V_g^2},
\]

(26)

and the required voltage rating per-phase during balanced operation:

\[
V_y^{Y_{nom}} = \sqrt{\frac{2}{3}} \left[ \left( \frac{V_g}{\sqrt{3}} \right)^2 + V_{L,Y}^2 \right],
\]

(27)

where \( V_{L,Y} = L_f(p.u., Y) V_g/\sqrt{3} \).

The required voltage rating per phase with the injected zero-sequence voltage is given by:

\[
V_y = \sqrt{2} \left( \frac{V_g}{\sqrt{3}} + V^0 \cos \theta_Y \right)^2 + \left( V^0 \sin \theta_Y + \frac{\lambda_a + \lambda_b + \lambda_c}{3} V_{L,Y} \right)^2 \right]^{1/2},
\]

(28)

The required voltage overrating is a function of the power generation ratios:

\[
V_y = \sqrt{2} \sqrt{F(\lambda_a, \lambda_b, \lambda_c)},
\]

(30)

In practical application, the per-unit inductance value should be quite small (0 < \( L_f(p.u., Y) \) ≤ 0.1) and it can be shown that \( F(\lambda_a, \lambda_b, \lambda_c) \) reaches its maximum value at \( \lambda_a = 1, \lambda_b = 0, \lambda_c = 0 \). The required overrating of the star-connected CHB converter is given by substituting these values into (28):

\[
\frac{V_{Y_{max}}}{V_{Y_{nom}}} = \frac{81 + L_f^2(p.u., Y)}{1 + L_f^2(p.u., Y)}. \]

(31)

Similar analysis can be repeated in the remaining sectors. The worst cases are \( (\lambda_a, \lambda_b, \lambda_c) = (1, 0, 0), (0, 1, 0) \) and \( (0, 0, 1) \), which corresponds to one phase generating full power while the remaining two phases producing zero power.

D. Current overrating (Y)

When the inter-phase power imbalance occurs in the star connection, the current is always less than the nominal, because of the drop in overall power. As a result, current overrating is not necessary in the star-connected CHB.

E. Comparison & Discussion

A comparison between the power balancing capabilities of the two converters can be made based on the overrating considerations and considering that the two designs would share the same i) grid voltage \( V_g \), ii) nominal power rating \( P_{nom} \), iii) dc-side capacitor voltages \( V_{dc} \), iv) semiconductor requirements and v) harmonic performance.

Two metrics that assess the converter power balance capabilities are the Power Balance Space (PBS) and the Power Balance Factor (PBF) [33]. The power generation of each phase fluctuates with changing solar irradiance and/or ambient temperature of the solar panels connected to that phase. Based on the definition of power generation ratios, these can only vary between zero and one for the delta or the star configuration so that 0 ≤ \( \lambda_{ab}, \lambda_{bc}, \lambda_{ca} \) ≤ 1 (Δ) or 0 ≤ \( \lambda_a, \lambda_b, \lambda_c \) ≤ 1 (Y) all possible power imbalance cases fall within a unity cube (1 × 1 × 1).

Each power imbalance case can be represented by a unique operation point \( (\lambda_{ab}', \lambda_{bc}', \lambda_{ca}') \) or \( (\lambda_a', \lambda_b', \lambda_c') \) inside the cube. If the maximum converter output voltage is lower than the total available dc-side voltage of one phase-leg then three-phase balanced grid currents can be generated without saturation, and this operation point can be rebalanced using the given method. PBS is defined as the three-dimensional space that includes all operation points \( (\lambda_a, \lambda_b, \lambda_c) \) (Y) or \( (\lambda_{ab}, \lambda_{bc}, \lambda_{ca}) \) (Δ) that can be tolerated by the converter. PBF, defined as the volume of PBS, indicates the converter power balance capability [14], [15]. A larger PBF indicates more operation points can be rebalanced.

\[
PBF = \int \int \int F(\lambda_a, \lambda_b, \lambda_c) d\lambda_a d\lambda_b d\lambda_c,
\]

(32)

where

\[
F(\lambda_a, \lambda_b, \lambda_c) = \begin{cases} 1, & \text{max} \{v_a, v_b, v_c\} (\lambda_a, \lambda_b, \lambda_c) \leq N_v dc \\ 0, & \text{max} \{v_a, v_b, v_c\} (\lambda_a, \lambda_b, \lambda_c) > N_v dc \end{cases},
\]

(33)

The PBS of two designed star and delta-connected converters of Table II is shown in Fig. 5 with the corresponding PBF. The PBS of the delta-connected converter, based on the assumptions of the comparison (Fig. 5a), features a much larger volume than that of the star-connected counterpart (Fig. 5b),
With three bridges in the phase leg, the converter output voltages feature seven-level waveforms with an equivalent switching frequency of 9 kHz. In practical applications with a higher number of bridges per phase, a lower carrier frequency can be used to achieve similar harmonic performance. A limitation of the experimental implementation is that the converter can only track the MPP under nominal conditions, because $v_{dc}$ is kept constant during the operation and dc-dc converters are not included in the setup. When the irradiance changes, the converter cannot track the MPP of the new condition, because $v_{dc}$ remains constant. However, this does not affect the results and conclusions from the experiment as there still exists an unbalanced power generation between the three phases of the converter i.e., it is only the magnitude of that imbalance which is slightly different.

### A. Balanced operation ($\lambda_{ab} = \lambda_{bc} = \lambda_{ca} = 1$)

Under steady-state and balanced operation, all nine PV simulators are subject to the same nominal conditions of 1000 W/m$^2$ irradiance assuming temperature of 25°C. The three-phase converter output voltages and phase-leg currents are depicted in Fig. 7(a), both of which are balanced and symmetrical, as the power generation levels from the PV side is equal in the three phases. The three-phase line currents are also balanced and symmetrical with an average rms value of 12.4 A. The zero-sequence current to deal with the power imbalance is almost zero (Fig. 7(b)).

### B. Mild inter-phase power imbalance ($\lambda_{ab} \approx 0.5, \lambda_{bc} = \lambda_{ca} = 1$)

The solar irradiance of the three PV simulators in phase $ab$ is decreased from 1000 W/m$^2$ to 500 W/m$^2$ to emulate a mild case of power imbalance between the power generation of the three-phases. Due to the lack of dc-dc conversion stages, the actual power generation level is approximately 50% of its nominal value. Fig. 8(a) shows the three-phase converter output voltages and phase-leg currents under mild inter-phase power imbalance. The phase-leg currents are no longer symmetrical since phase $ab$ generates less power than the other two phases. However, the three-phase line currents injected to the grid (Fig. 8(b)) still feature symmetrical and balanced sinusoidal waveforms with an average rms value of 10.3 A, demonstrating the balancing capabilities and high harmonic performance of the delta-connected CHB converter. The zero-sequence current, which only flows within the delta

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**Table II: Experimental Prototype Parameters**

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Values</th>
</tr>
</thead>
<tbody>
<tr>
<td>Grid Voltage, $V_g$</td>
<td>430 V</td>
</tr>
<tr>
<td>Three-phase Nominal Power, $P_{nom}$</td>
<td>10 kW</td>
</tr>
<tr>
<td>Filtering Inductance per phase, $L_f$</td>
<td>10 mH (0.06 p.u.)</td>
</tr>
<tr>
<td>MPP of PV Simulators</td>
<td>239.4 V, 4.645 A</td>
</tr>
<tr>
<td>dc-side Capacitor Voltage, $v_{dc}$</td>
<td>239.4 V</td>
</tr>
<tr>
<td>Carrier Frequency, $f_s$</td>
<td>1500 Hz</td>
</tr>
</tbody>
</table>

---

**Fig. 6.** Experimental setup: (a) schematic diagram and (b) hardware.
C. Worst-case inter-phase power imbalance

\( \lambda_{ab} = 0, \lambda_{bc} = \lambda_{ca} = 1 \)

The solar irradiance of the three PV simulators in phase \( ab \) is further decreased to 0, which means a small amount of active power needs to be delivered into phase \( ab \) to maintain the capacitor voltage levels, because of the losses. This is the worst inter-phase power imbalance cases derived in Section IV. As illustrated in Fig. 9(a), under this extreme power imbalance case, the three-phase line currents still exhibit symmetrical waveforms with an average \( rms \) value of 8.2 A. The injected zero-sequence current, including both the fundamental and third harmonic components, is also demonstrated in Fig. 9(b). It would not be possible for the star connection to deal with this extreme case without significantly overrating the converter (Section IV and [16]). The superior power balance capability of the presented delta connection is thus confirmed.

Furthermore, in the star connection, the converter output voltage of the phase with low power generation is expected to exhibit lower number of voltage levels, which adversely affects the harmonic performance [16]. However, this issue does not appear in the delta-connected CHB converter. As illustrated in Fig. 9(a), the converter output voltage of the phase with zero power generation still features a seven-level waveform, because with the delta connection, a zero-sequence current \( i_0 \) is injected to ensure the power balance between the three phases instead of a zero-sequence voltage.

VI. Conclusion

The delta-connected CHB converter provides an alternative configuration for large-scale PV applications. A major difference between the two configurations is that the delta-connected topology offers superior power balancing capabilities in order to address unbalanced power generation amongst the three phases without requiring significant voltage or current over-rating. In this paper, the capability has been demonstrated both analytically in terms of worst-case power imbalances and practically by comparing the Power Balance Space of the two configurations. Experimental results demonstrate both the operation of the delta-connected cascaded H-bridge converter in PV applications and its power balancing capabilities.
Fig. 9. Worst-case inter-phase power imbalance: (a) three-phase converter output voltages and phase-leg currents. CH1: voltage of phase \( a \), CH2: current of phase \( ab \), CH3: voltage of phase \( bc \), CH4: current of phase \( bc \), CH5: voltage of phase \( ca \), CH6: current of phase \( ca \), M1: line current of phase \( a \), M2: line current of phase \( b \), M3: line current of phase \( c \), M4: zero-sequence current \( i_0 \). Timescale: 5 ms/div.

REFERENCES


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