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State-of-the-art and engineering practices

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A critical review of clarifier modelling: State-of-the-art and engineering practices

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Abstract

This outline paper aims to provide a critical review of secondary settling tank (SST) modelling approaches used in current wastewater engineering and develop tools not yet applied in practice. We address the development of different tier models and experimental techniques in the field with a particular emphasis on works published since the reference work by Ekama *et al.* (1997). We give insight into the current engineering practice, identify how recent developments can be transferred to engineering practice and pinpoint limitations and potential pathways for further development of models and measurement techniques. As a follow-up to the present work, we believe there is a need for the development of a protocol for systematic clarifier modelling depending on the modelling objective and in line with good modelling practice.

Keywords

Clarifier model; Computational fluid dynamic modelling; one-dimensional modelling; zero-dimensional modelling; process modelling; sedimentation tank; simulators; parameter variability.

INTRODUCTION

Promoting *good modelling practice* in wastewater engineering is paramount, thereby guiding engineers using models, and providing appropriate sets of *a priori* assumptions in model selection, model setup, calibration/validation, result interpretation and documentation. For this purpose, an IWA Scientific Technical Report has been elaborated by the IWA GMP Task Group (Rieger *et al.*, 2012). However, its main focus is on the activated sludge portion of the plant and only a rather small section is dedicated to secondary settling tank (SST) models, limited to typically used engineering practices. IWA's Activated sludge model family (ASM1/2/2d/3), has undergone significant development (Henze *et al.*, 2000), and effectively found its way to practice in the past

decades. Despite the progress made in the field of SST modelling since the publications by Krebs (1995) and the IWA Scientific and Technical Report (Ekama *et al.*, 1997), it seems that many of these scientific findings have not entered into current engineering practice. Part of the reason for this shortcoming, the authors believe, is that an ASM-like, consensus-based set of SST models is still missing. Another reason might be the lack of internationally accepted SST modelling guidelines, i.e. procedures to suggest SST models for specific tasks, which are as simple as possible, but fulfil the needs and list the data required to feed and calibrate/validate the models. Compiling such guidelines requires insights both from practice and academia and consensus building. This paper is intended to serve as a basis for the development of an SST modelling guideline according to current knowledge and practice.

The outline paper is organised as follows: first, the available model portfolio is briefly introduced; next, engineering practice is reviewed, highlighting shortcomings; finally, scientific knowledge gaps are identified. Conclusions are drawn and potential future developments listed. The outline paper is meant to provide a position statement, serving as a starting point to develop a systematic guideline for use of clarifier models depending on the objectives.

MODEL PORTFOLIO

Depending on the objectives, a continuum of options in SST model complexity is available (Table 1). SST models can characterize performance, given specification of the characteristics of the feed sludge (e.g., hindered settling velocity). These characteristics, however, show high variability in WWTPs, and are not predicted by any available models used in practice!

Zero-dimensional (0-D) models. Simple 0-D model representations are practically ideal splitters of flow and solids, and are the simplest models around only having one parameter, the fraction of solids recirculated into the activated sludge reactors. Additionally, 0-D models can also be used with limitations imposed by state-point analysis on the solids transport (Daigger and Roper, 1985; Lynggaard-Jensen *et al.*, 2009). In these models, effluent solids or removal efficiency can be either a direct model input or a function of the flow rate through the SST.

One-dimensional (1-D) models. For design and operation, flux-based one-dimensional (1-D) clarifier models can be used. These models describe the hydrodynamic behaviour in 1 dimension and its interaction with the flocs that are settling. These are important elements to estimate the clarification and thickening behaviour as well as solids inventory of clarifiers in plant-wide process predictions. First- and second-order 1-D models are available. The 10-layer (first-order) model proposed by Takács *et al.* (1991) and the more recent suggested models (e.g., Plósz *et al.*, 2007, De Clercq *et al.*, 2008), based on 1-D advection-dispersion partial differential equation (PDEs) are examples. One important difference between first- and second-order models is the way discretisation (layer number) is approached, and thus the way dispersion is approximated. In WWTP simulators, 1-D SST model implementations additionally require numerical integration methods – an area investigated, most notably, by Jeppsson and Diehl (1996) and Bürger *et al.* (2011).

Two- or three-dimensional (2-D/3-D) models. At the highest tier we find the 2-3D models which have been developed in Computational Fluid Dynamics (CFD). 2-D and 3-D models predict tank hydrodynamics, internal processes and internal configurations, allowing visualization of the internal conditions in the clarifier, like position of the sludge blanket and flow pattern (examples of 2-D and

3-D outputs presented in Fig. 2). Typically, multidimensional CFD models are based on the following principles: (1) continuity of conservation of fluid volume; (2) conservation of momentum; (3) conservation of mass of solids, including the modeling of the settling behavior of the particles; and (4) turbulence modeling equations. Additionally, some models, e.g., De Clercq (2003), Griborio (2004), McCorquodale *et al.* (2005), Weiss *et al.* (2007) have incorporated the rheology of the activated sludge, and some models, e.g., Parker *et al.* (2008), have attempted to simulate and quantify the flocculation-deflocculation processes in SSTs.

ENGINEERING PRACTICE INCLUDING MODEL SHORTCOMINGS

SST models

SST models can be used at various levels of wastewater engineering, comprising design, construction, operation, control and diagnosis/trouble-shooting (Table 2). One of the principal constraints for the general use of the more sophisticated SST models is that sludge characteristics are determined largely by the characteristics of the upstream activated sludge system. Since sludge characteristics significantly determine SST performance, and it is not possible to clearly characterize or predict these characteristics, the utility of sophisticated SST models thus is somewhat compromised relative to routine practice.

0-D models. In current engineering practice, simple point-settlers, ideal-settler-with-volume and variations thereof are widely used. These models only model the separation of particles but not the settling behaviour. Therefore, some 0-D models are used with limitations imposed by state-point analysis on the solids transport. In a number of modelling projects the use of simple point or ideal clarifier models (phase separators) will be sufficient. In these models effluent solids or removal efficiency is a direct model input.

1-D models. Current WWTP models often combine ASM models (Henze *et al.*, 2000) with 1-D tools. Layered flux models (1-D) are usually required only under dynamic conditions, to model settling and to better represent effluent and underflow concentration changes and sludge mass shifts when these are relevant to model the behaviour of the plant. However, effluent suspended solids predictions from 1-D models should not be taken for granted as these models were not designed for this purpose. The most well-known and used is the 10-layer model by Takács *et al.* (1991). The more recently developed second-order 1-D models are not yet available for engineering use in commercial WWTP simulators. An advantage of the latter models is that they allow a more effective calibration using measured settling parameters, as compared to first-order models.

2-D/3-D models. CFD is traditionally used for designing and optimising new and existing secondary clarifiers (e.g., placing baffles in underperforming clarifiers), and to detect the causes of malfunction of these process separation units. CFD models can incorporate hydrodynamics, flocculation, turbulence, sludge rheology, settling characteristics and temperature effects. These tools describe systems in more than one dimension, and are based on higher dimensional PDEs that are numerically solved. The use of 2-D and 3-D CFD clarifier models still requires long computational times and high computational capacity. CFD is used for clarifier construction, optimisation and trouble shooting exercises in engineering practice. Also 2-D and 3-D models have been linked with whole plant simulators for the dynamic simulation of wet weather events and wet

weather strategies (GriBORIO *et al.*, 2010). One area that can potentially stimulate CFD use in wastewater engineering is in improving simpler clarifier models – in terms of model structure and calibration – used in WWTP simulations (De Clercq, 2003).

Data availability in typical projects

Unfortunately, in most scientific and engineering projects, even the well-described protocols (e.g., batch settling tests) are not standard applied. Usually sludge settleability is characterized in terms of sludge volume index (SVI) – which gives very limited information on sludge settleability (e.g., Dick & Vesilind, 1969). SVI data then is converted with empirical equations to the V_0 and n parameters in the flux zone settling velocity equation $V_S = V_0 \exp(-nX_t)$ (Ekama *et al.*, 1997). In that way, at least, the steady state 1-D flux theory or dynamic 1-D layered models can be used. With regard to typical (mostly non-academic) projects, the calibration of 1-D models almost always rely on settling velocity parameters inferred using some form of SVI-based correlation equation. This is a major reason why 0-D models are still used in most applications.

SCIENTIFIC KNOWLEDGE GAPS

For greater application of 1-D and CFD models to SSTs, it is important to further develop and implement models that describe the clarification, settling and compression behaviour of the sludge across the *entire concentration range with measurable parameters* than to develop further advances in the mathematics of these models. It is in the specification of sludge settling characteristics that even the multi-D CFD modelling of SSTs is the most deficient of and lags far behind the mathematical developments for solving the complex CFD equations. Currently no widely accepted and easy to implement methods are available for measuring sludge settling behaviour outside the zone settling range. Therefore, it has been accepted (cautiously) in CFD modelling of SSTs to date that the zone settling behaviour equation (Eq. 1) modified to include f_{ns} and the r_p exponential term for dilute concentrations, applies to the full range of concentrations found in SSTs. Most CFD models for SSTs use Eq. 2 at this current stage of development. The r_p value has a direct effect on $X_{TSS,eff}$ and because it cannot be measured directly on the activated sludge, it is actually a model calibration parameter using measured $X_{TSS,eff}$ in SST performance tests. However, this includes the effect of the internal features of the SST that are not completely covered by the CFD-model, and, therefore, r_p cannot actually be considered a sludge characteristic as it compensates for model deficiencies. It thus applies only to the specific SST simulated.

Measurement techniques and data availability

In general, the level of mathematics of settling tank models in one, two or even three dimensions has gone far beyond the level of measurement quality with which these models are fed. This means that the lack of experimental methods (e.g. data to calibrate settling velocity functions including hindered and compression settling) and high-resolution data (e.g. concentration profile) is what is most limiting the use of advanced settling models. Even CFD model implementations include empirical equations, describing the sludge clarification, thickening and compaction behaviour. Besides the additional data requirements, the development of specific and easy-to-use experimental setups is needed to properly test these model advancements. Currently, no practical methods are available for measuring sludge settling behaviour outside the zone settling range (Ekama and Marais, 2004). Still, recent studies have proposed relatively complex methods to measure the concentration and pressure profiles during batch settling (De Clercq *et al.*, 2005), providing the required information to model the zone and compression settling behaviour. In the foreseeable

future, however, models will continue to rely on empirical functions for the assessment of the hindered settling velocity and the excess pore pressure. Such innovative techniques, nevertheless, need to be further explored in how they can address some of the issues with regard to shortage of data. Communicating the current lack of data and measurement techniques to the research community thus is a crucial step.

CONCLUSIONS AND OUTLOOK

To close the gap between research and practice and outline the potential directions for development, this critical review gives an overview on published clarifier models, current engineering practice and on typical demands on clarifier models. We draw the conclusions that all tiers of SST models can significantly benefit from increasing data availability and improved measurement techniques to make them more accurate.

This deserves attention in future and will likely be the key to improved understanding, further improved SST models and their use in engineering practice. Innovative techniques thus need to be further explored at an academic level in how they can address some of the issues with regard to the shortage of data.

Communicating these perspectives to the research community is a crucial first step forward. In the future, a protocol is needed on the choice of an appropriate SST model for the purpose and accompanying requirement for data collection and calibration/validation.

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